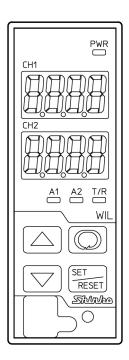
Plug-in Type Digital Indicating DO Meter WIL-102-DO

Instruction Manual





Preface

Thank you for purchasing our WIL-102-DO, Plug-in Type Digital Indicating DO (Dissolved Oxygen) Meter. This manual contains instructions for the mounting, functions, operations and notes when operating the WIL-102-DO. To ensure safe and correct use, thoroughly read and understand this manual before using this instrument.

To prevent accidents arising from the misuse of this instrument, please ensure the operator receives this manual.

Abbreviations used in this manual

Name	Term
DO	Dissolved Oxygen
DO Display	DO Concentration Display
Display Mode	DO Concentration / Temperature Display Mode
	DO % Saturation / Temperature Display Mode
	Oxygen Partial Pressure / Temperature Display Mode

Characters Used in This Manual

					_,					<u> </u>		_	_
Indication	7		i	7	m	4	'n	5	i	8	9	1	Ļ
Number, °C/°F	-1	0	1	2	3	4	5	6	7	8	9	ပ္	°F
Indication	R	5	_	ದ	Ε	F	- C	H	;	<i></i> !	E	L	ij
Alphabet	Α	В	С	D	Е	F	G	Н	I	J	K	L	М
Indication	n	o o	P	7	_	' -,	1	Ш	Ħ	Ü	j	H)] (
Alphabet	Ν	0	Р	Q	R	S	Т	U	V	W	Х	Υ	Ζ



Caution

- This instrument should be used in accordance with the specifications described in the manual. If it is not used according to the specifications, it may malfunction or cause a fire.
- Be sure to follow all of the warnings, cautions and notices. If they are not observed, serious injury or malfunction may occur.
- The contents of this instruction manual are subject to change without notice.
- Care has been taken to ensure that the contents of this instruction manual are correct, but if there are any doubts, mistakes or questions, please inform our sales department.
- This instrument is designed to be installed on a DIN rail within a control panel. If it is not, measures must be taken to ensure that the operator cannot touch power terminals or other high voltage sections.
- Any unauthorized transfer or copying of this document, in part or in whole, is prohibited.
- Shinko Technos Co., Ltd. is not liable for any damage or secondary damage(s) incurred as a result of using this product, including any indirect damage.

Safety Precautions (Be sure to read these precautions before using our products.)

The safety precautions are classified into 2 categories: "Warning" and "Caution".

Depending on the circumstances, procedures indicated by \triangle Caution may result in serious consequences, so be sure to follow the directions for usage.



Procedures which may lead to dangerous conditions and cause death or serious injury, if not carried out properly.



Procedures which may lead to dangerous conditions and cause superficial to medium injury or physical damage or may degrade or damage the product, if not carried out properly.



Warning

- To prevent an electrical shock or fire, only Shinko or other qualified service personnel may handle the inner assembly.
- To prevent an electrical shock, fire or damage to the instrument, parts replacement may only be undertaken by Shinko or other qualified service personnel.



SAFETY PRECAUTIONS

- To ensure safe and correct use, thoroughly read and understand this manual before using this instrument.
- · This instrument is intended to be used for measuring equipment. Verify correct usage after purpose-of-use consultation with our agency or main office. (Never use this instrument for medical purposes with which human lives are involved.)
- External protection devices such as protective equipment against excessive temperature rise, etc. must be installed, as malfunction of this product could result in serious damage to the system or injury to personnel. Proper periodic maintenance is also required.
- This instrument must be used under the conditions and environment described in this manual. Shinko Technos Co., Ltd. does not accept liability for any injury, loss of life or damage occurring due to the instrument being used under conditions not otherwise stated in this manual.



Caution with Respect to Export Trade Control Ordinance

To avoid this instrument from being used as a component in, or as being utilized in the manufacture of weapons of mass destruction (i.e. military applications, military equipment, etc.), please investigate the end users and the final use of this instrument. In the case of resale, ensure that this instrument is not illegally exported.

PRECAUTIONS

1. Installation Precautions



Caution

This instrument is intended to be used under the following environmental conditions (IEC61010-1):

Overvoltage category II, Pollution degree 2

Ensure the mounting location corresponds to the following conditions:

- · A minimum of dust, and an absence of corrosive gases
- No flammable, explosive gases
- · No mechanical vibrations or shocks
- No exposure to direct sunlight, an ambient temperature of 0 to 50°C (32 to 122°F) that does not change rapidly, and no icing
- An ambient non-condensing humidity of 35 to 85%RH
- No large capacity electromagnetic switches or cables through which large current is flowing.
- · No water, oil, chemicals or the vapors of these substances can come into direct contact with the unit.
- If the WIL-102-DO is installed within a control panel, the ambient temperature of the unit not the ambient temperature of the control panel – must be kept under 50℃. Otherwise the life of electronic parts (especially electrolytic capacitors) of the unit will be shortened.

Note: Do not install this instrument on or near flammable material even though the case of this instrument is made of flame-resistant resin.

2. Wiring Precautions



Caution

- Do not leave wire remnants in the instrument, as they could cause a fire or a malfunction.
- Use a solderless terminal with an insulation sleeve in which the M3 screw fits when wiring the WIL-102-DO.
- Tighten the terminal screw using the specified torque. If excessive force is applied to the screw when tightening, the terminal screw may be damaged.
- This instrument does not have a built-in power switch, circuit breaker and fuse. It is necessary to install a power switch, circuit breaker and fuse near the instrument. (Recommended fuse: Time-lag fuse, rated voltage 250 V AC, rated current 2 A)
- For a 24 V AC/DC power source, do not confuse polarity when using direct current (DC).
- Do not apply a commercial power source to the DO Sensor which is connected to the input terminal nor allow the power source to come into contact with the sensor.
- Use the DO Sensor made by OPTEX Co., Ltd.
- Keep the input wires and power lines separate.

Note about the DO Sensor Cable

The DO Sensor cable is a highly-insulated (electrical) cable. Please handle it with utmost care as follows.

• Do not allow terminals and socket of the DO Sensor cable to come in contact with moisture or oil of any kind. Likewise, ensure fingers are clean, otherwise the insulation will deteriorate, resulting in unstable indication.

Be sure to keep the cable dry and clean at all times.

If the cable is stained, clean it with alcohol, and dry it completely.

- For calibration or checking/replacement, the DO Sensor cable should be wired with sufficient length.
- Keep the DO Sensor cable and junction cable away from electrical devices, such as motors or their power lines from which inductive interference emanates.

Connection

The DO Sensor cable has the following terminals.

Code	Terminal
RS-485 (SENSOR INPUT)	DO Sensor YB (+) input terminal (Blue)
RS-485 (SENSOR INPUT)	DO Sensor YA (-) input terminal (Green)
POWER FOR SENSOR	External power (+) terminal (Red)
POWER FOR SENSOR	External power (-) terminal (Black) and DO Sensor shield

White and brown cables of the DO Sensor are not used, so cut them off, and electrically insulate them. If they come in contact with other terminals, a malfunction will occur.

3. Operation and Maintenance Precautions



Caution

- Do not touch live terminals. This may cause an electrical shock or problems in operation.
- Turn the power supply to the instrument OFF when retightening the terminal or cleaning. Working on or touching the terminal with the power switched ON may result in severe injury or death due to electrical shock.
- Use a soft, dry cloth when cleaning the instrument.
 (Alcohol based substances may tarnish or deface the unit.)
- As the display section is vulnerable, be careful not to put pressure on, scratch or strike it with a hard object.

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1. Model

1.1 Model

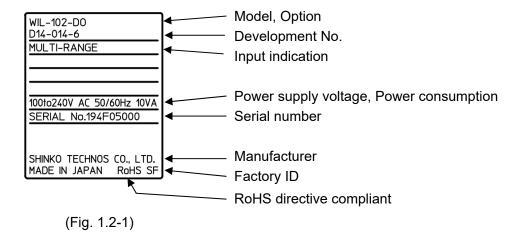
W I L - 10	2	-DO		, 🗆	
Input Points	2				2 points
Input		DO			Optical DO Sensor
Power supply voltage				100 to 240 V AC (standard)	
		1		24 V AC/DC (*)	
Option				EVT	EVT□ output (EVT3, EVT4, EVT5, EVT 6)

(*) Power supply voltage 100 to 240 V AC is standard.

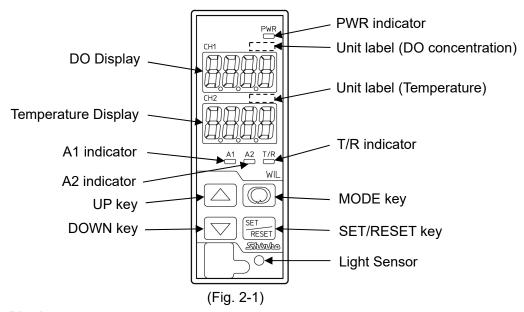
When ordering 24 V AC/DC, enter "1" in Power supply voltage, after 'DO'.

1.2 Model Label

The model label is attached to the left side of the case.



2. Names and Functions of Instrument



Displays

Displays	
DO Display In Display Mode, DO Concentration, DO % saturation or Oxygen part pressure is indicated in red.	
	In Setting mode, setting characters are indicated in red.
Temperature	In Display Mode, temperature is indicated in red.
Display	In Setting mode, set value (selected item) is indicated in red.

Unit Labels

Unit label	Attach the user's unit of DO concentration from the included unit labels if
(DO concentration)	necessary.
Unit label	Attach the user's unit of temperature from the included unit labels if necessary.
(Temperature)	

Action Indicators

PWR indicator	When power supply to the instrument is turned ON, the yellow LED lights up.
A1 indicator	When EVT1 output (Contact output 1) is ON, the red LED lights up.
A2 indicator	When EVT2 output (Contact output 2) is ON, the yellow LED lights up.
T/R indicator	The yellow LED lights up during Serial communication TX output (transmitting).

Keys

	Increases the numeric value, or progresses through the selection items.			
	Switches the Display Mode.			
◯ DOWN key	Decreases the numeric value, or progresses back through the selection items.			
MODE key	Selects a group.			
SET/RESET key	Switches the setting modes, and registers the set value (or selected item).			

Light Sensor	Automatically measures and controls brightness of the DO Display,
	Temperature Display and Action indicators.

∧ Notice

When setting the specifications and functions of this instrument, connect mains power cable to terminals 13 and 14 first, then set them referring to "6. Outline of Key Operation and Setting Groups" and "7. Setup (pp. 20 to 40)" before performing "3. Mounting to and Removal from the Control Panel (p.9)" and "5. Wiring (p.16)".

3. Mounting to and Removal from the Control Panel

3.1 Site Selection

⚠ Caution

Use within the following temperature and humidity ranges.

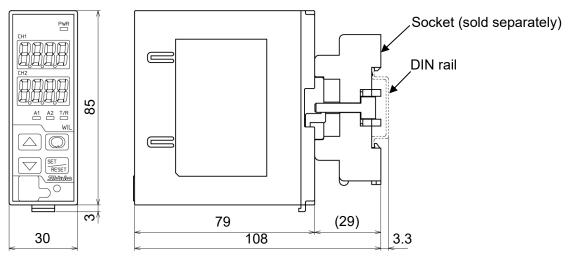
Temperature: 0 to 50°C (32 to 122°F) (No icing), Humidity: 35 to 85 %RH (Non-condensing) If the WIL-102-DO is installed within a control panel, the ambient temperature of the unit – not the ambient temperature of the control panel – must be kept under 50°C. Otherwise the life of electronic parts (especially electrolytic capacitors) of the unit will be shortened.

This instrument is intended to be used under the following environmental conditions (IEC61010-1): Overvoltage category I, Pollution degree 2

Ensure the mounting location corresponds to the following conditions:

- · A minimum of dust, and an absence of corrosive gases
- No flammable, explosive gases
- · No mechanical vibrations or shocks
- No exposure to direct sunlight, an ambient temperature of 0 to 50℃ (32 to 122°F) that does not change rapidly
- An ambient non-condensing humidity of 35 to 85 %RH
- · No large capacity electromagnetic switches or cables through which large current is flowing
- No water, oil, chemicals or the vapors of these substances can come into direct contact with the unit.

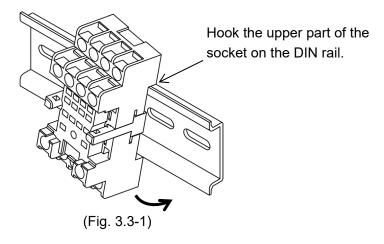
3.2 External Dimensions (Scale: mm)



(Fig. 3.2-1)

3.3 Mounting

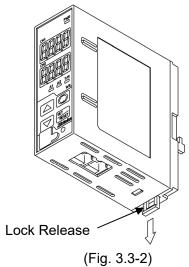
(1) Hook the upper part of the socket on the DIN rail, and mount it (A clicking sound is heard).



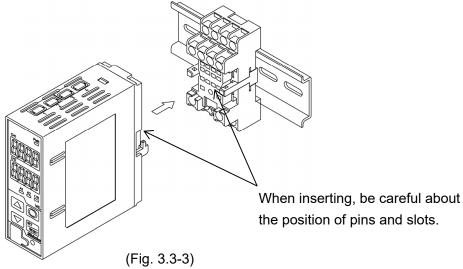
⚠ Caution

Before inserting the WIL-102-DO into the socket, wire the unit while referring to Section "5. Wiring" (p.16).

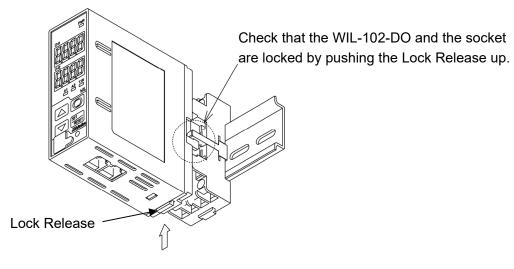
(2) Check that the Lock Release has been lowered.



(3) Insert the WIL-102-DO into the socket.



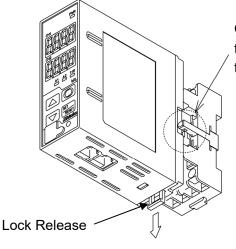
(4) Fix the WIL-102-DO and the socket by pushing the Lock Release up.



(Fig. 3.3-4)

3.4 Removal

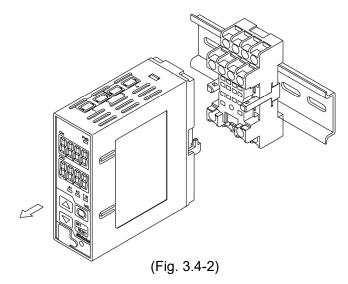
- (1) Turn the power supply to the unit OFF.
- (2) Pull the Lock Release down, and release the WIL-102-DO from the socket.



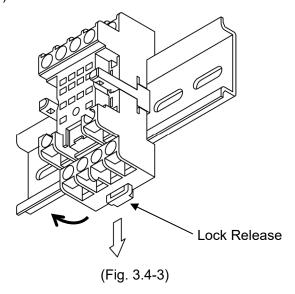
Check that the WIL-102-DO and the socket are unlocked by pulling the Lock Release down.

(Fig. 3.4-1)

(3) Separate the WIL-102-DO from the socket.



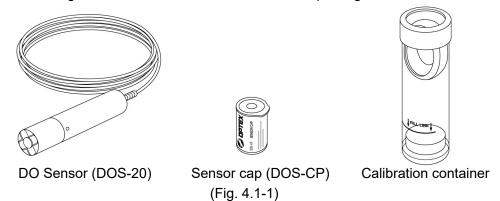
(4) Remove the socket from the DIN rail by pulling the socket Lock Release (at the bottom of the socket) down.



4. DO Sensor

4.1 Contents of Package

The following items are contained in the DO Sensor package.



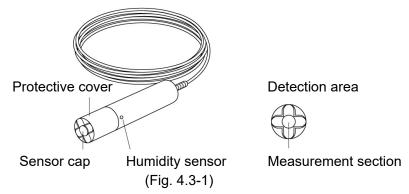
4.2 Caution when Using DO Sensor



Do not use the DO Sensor for any purposes other than water quality measurement.

	Do not disassemble or modify. The sensor contains a high voltage component which may cause fire or electrical shock. For internal inspection, maintenance or repair, please consult us or our agency.
(Fig. 4.2-1)	
	Do not subject the sensor to any rough treatment. Do not drop the unit. Handle with care.
(Fig. 4.0.0)	
(Fig. 4.2-2)	Do not tough the magazinement continuit it is not
(Fig. 4.2-3)	Do not touch the measurement section. If it is not clean, wipe it with a clean, soft cloth.
	Be careful not to damage the cable. Ensure that the cable is not tangled, nor caught or trapped in any way when installing and using the sensor.
	Use a spiral cable wrap to protect the cable. If the cable is damaged, it may malfunction when immersed, and fire or electrical shock will occur.
(Fig. 4.2-4)	

4.3 Name of Sections

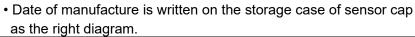


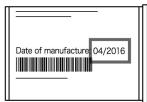
4.4 Attaching the Sensor Cap



- Before attaching, make sure that the O-ring of the sensor is not crooked or is in the right position in the groove.
- Take the sensor cap out from the package just before mounting, and mount it immediately.
- When mounting the sensor cap, keep the dust or water from entering into the cap.

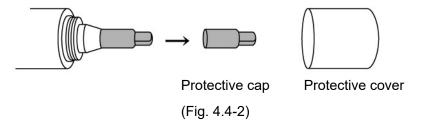
Otherwise correct measurement will not be performed.



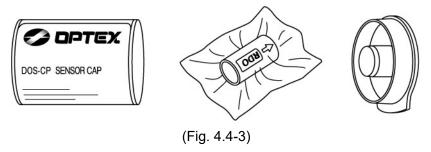


(Fig. 4.4-1)

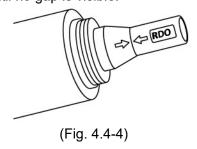
(1) Remove the protective cover from the sensor by rotating it, then remove the red protective cap. Please carefully set aside the protective cap.



(2) Take the provided sensor cap out from the storage case.



(3) Match the arrows on the sensor cap and on the sensor, then push the sensor cap straight onto it until no gap is visible.



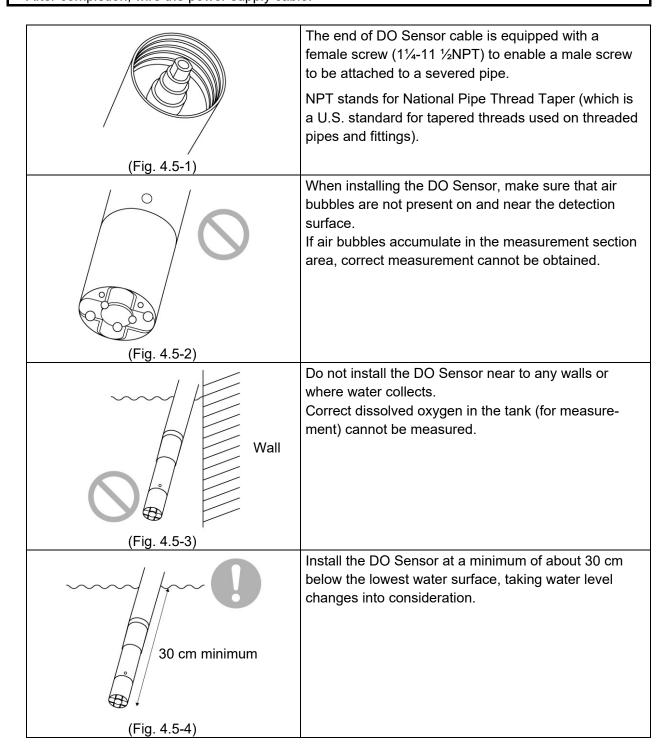
(4) Reattach the protective cover.

4.5 Installing the DO Sensor



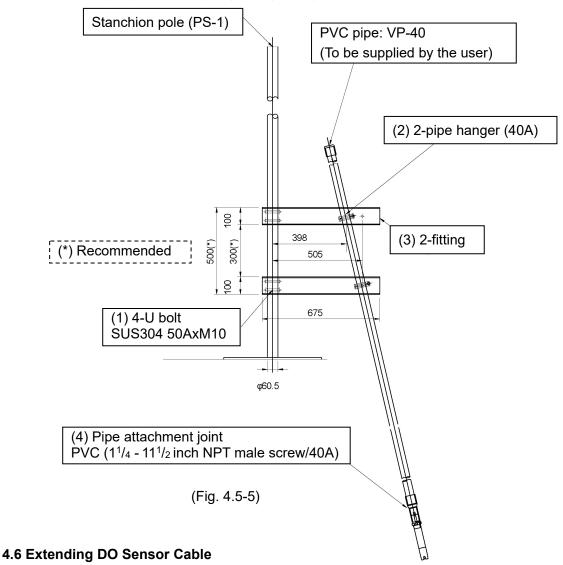
Caution

Before installation, remove the power supply cable from the power source. After completion, wire the power supply cable.

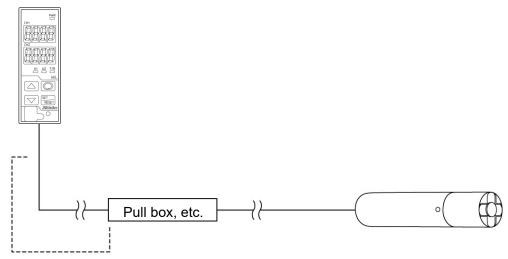


Recommendations

- As an accessory, the attachment (DA-1), sold separately, is recommended to use in a place where water currents are fast.
- The following (1) to (4) are included in the immersion holder.
- The Polyvinyl chloride (PVC) pipe (VP-40) is to be supplied by the user.



DO Sensor cable standard length is 10 m. To extend the cable, refer to the following diagram. Use a device such as a pull box if necessary.



Extendable cable length: 1200 m (Nominal cross-section area: 0.2 to 1.25 mm²)

(Fig. 4.6-1)

5. Wiring

Warning

Turn the power supply to the instrument off before wiring or checking.

Working on or touching the terminal with the power switched on may result in severe injury or death due to electrical shock.

Caution

- Do not leave wire remnants in the instrument, as they could cause a fire or a malfunction.
- Use a solderless terminal with an insulation sleeve in which the M3 screw fits when wiring the unit.
- Tighten the terminal screw using the specified torque. If excessive force is applied to the screw when tightening, the terminal screw may be damaged.
- This instrument does not have a built-in power switch, circuit breaker and fuse. It is necessary to install a power switch, circuit breaker and fuse near the instrument. (Recommended fuse: Time-lag fuse, rated voltage 250 V AC, rated current 2 A)
- For a 24 V AC/DC power source, do not confuse polarity when using direct current (DC).
- Do not apply a commercial power source to the DO Sensor which is connected to the input terminal nor allow the power source to come into contact with the sensor.
- Use the DO Sensor made by OPTEX Co., Ltd.
- Keep the input wires and power lines separate.

Note about the DO Sensor Cable

The DO Sensor cable is a highly-insulated (electrical) cable. Please handle it with utmost care as follows.

• Do not allow terminals and socket of the DO Sensor cable to come in contact with moisture or oil of any kind. Likewise, ensure fingers are clean, otherwise the insulation will deteriorate, resulting in unstable indication.

Be sure to keep the cable dry and clean at all times.

If the cable is stained, clean it with alcohol, and dry it completely.

- For calibration or checking/replacement, the DO Sensor cable should be wired with sufficient length.
- Keep the DO Sensor cable and junction cable away from electrical devices, such as motors or their power lines from which inductive interference emanates.

Connection

The DO Sensor cable has the following terminals.

Code	Terminal	
RS-485 (SENSOR INPUT)	DO Sensor YB (+) input terminal (Blue)	
RS-485 (SENSOR INPUT)	DO Sensor YA (-) input terminal (Green)	
POWER FOR SENSOR	External power (+) terminal (Red)	
POWER FOR SENSOR	External power (-) terminal (Black) and DO Sensor shield	

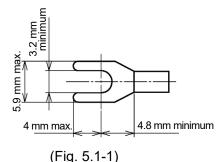
White and brown cables of the DO Sensor are not used, so cut them off, and electrically insulate them. If they come in contact with other terminals, a malfunction will occur.

5.1 Lead Wire Solderless Terminal

Use a solderless terminal with an insulation sleeve in which an M3 screw fits as follows.

The tightening torque should be 0.63 N·m.

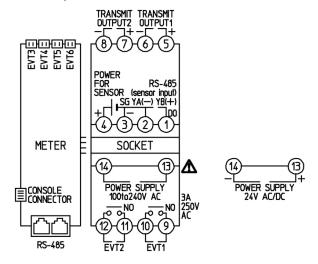
Solderles Terminal	Manufacturer	Model
Y-type	Nichifu Terminal	TMEV1.25Y-3S



5.2 Terminal Arrangement Standard specifications

TRANSMIT TRANSMIT DUTPUT2 DUTPUT3 8 7 6 5 POWER RS-485 SENSOR (sensor input) A 3 2 1 SOCKET 14 13 POWER SUPPLY 1001o240V AC 250V RS-485 EVT2 EVT1

EVT option

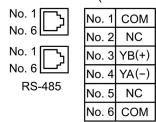


Modular Jack Pin (WIL-102-DO side arrangement)

No. 1	No. 1	СОМ
No. 6	No. 2	NC
No. 1	No. 3	YB(+)
No. 6	No. 4	YA(-)
RS-485	No. 5	NC
	No. 6	СОМ

(Fig. 5.2-1)

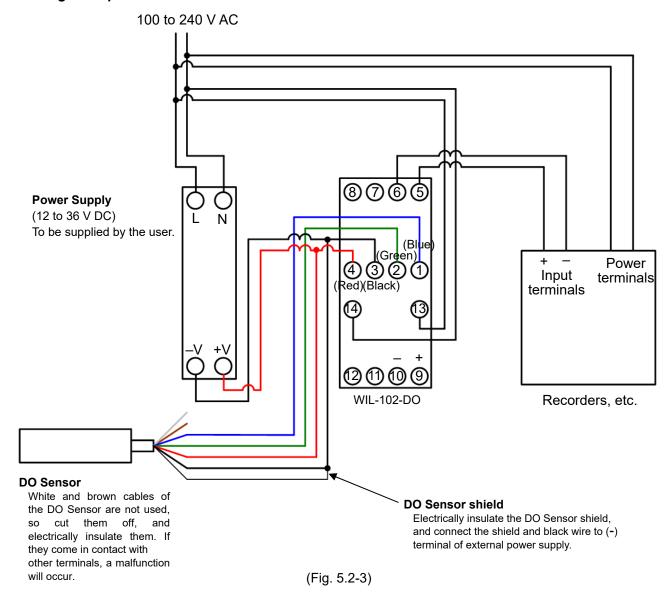
Modular Jack Pin (WIL-102-DO side arrangement)



(Fig. 5.2-2)

Code	Description	
DO RS-485 (sensor input)	DO Sensor YB(+) input terminal (Blue)	
DO RS-485 (sensor input)	DO Sensor YA(-) input terminal (Green)	
DO POWER FOR SENSOR	External power supply (-) terminal (Black) and DO Sensor shield	
DO POWER FOR SENSOR	External power supply (+) terminal (Red)	
TRANSMIT OUTPUT1	Transmission output 1	
TRANSMIT OUTPUT2	Transmission output 2	
EVT1	EVT1 output (Contact output 1)	
EVT2	EVT2 output (Contact output 2)	
EVT3	EVT3 output (Open collector output 3) (EVT option)	
	Use the included wire harnesses WJ.	
EVT4	EVT4 output (Open collector output 4) (EVT option)	
	Use the included wire harnesses WJ.	
EVT5	EVT5 output (Open collector output 5) (EVT option)	
	Use the included wire harnesses WJ.	
EVT6	EVT6 output (Open collector output 6) (EVT option)	
	Use the included wire harnesses WJ.	
POWER SUPPLY	Power supply voltage	
	100 to 240 V AC or 24 V AC/DC (when "1" is added after the model	
	name "DO")	
RS-485	24 V DC: Ensure polarity is correct.	
NO-400	Serial Communication modular jack	

Wiring Example

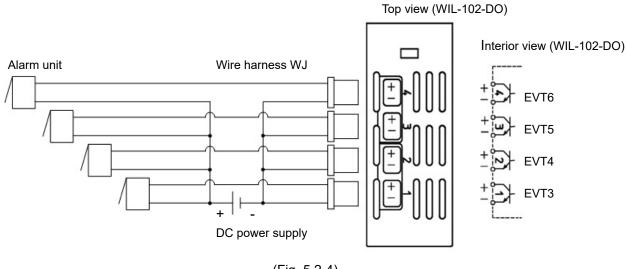


Wiring Example of EVT3 to EVT6

If EVT output (EVT option) is ordered, EVT3 to EVT6 output connectors are equipped on the top of this instrument. Use the included wire harnesses WJ.

Output specifications are shown below.

Open collector control capacity: 0.1 A 24 V DC

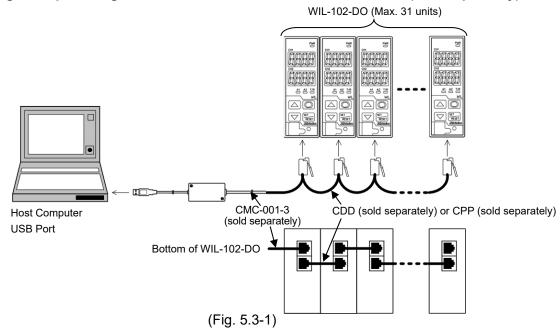


(Fig. 5.2-4)

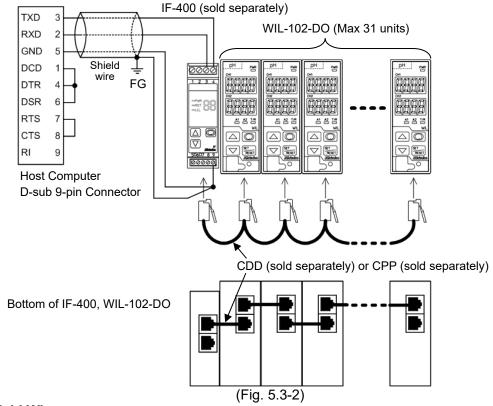
5.3 Wire the Communication Cable

Connect to the modular jack at the bottom of the instrument, using CDD (sold separately) or CPP (sold separately).

• Wiring Example Using the USB Communication Cable CMC-001-3 (sold separately)



Wiring Example Using the Communication Converter IF-400 (sold separately)



Shield Wire

Be sure to ground only one end of the shield wire so that current cannot flow to the shield wire. If both ends of the shield wire are grounded, the circuit will be closed, resulting in a ground loop. This may cause noise. Be sure to ground the FG.

Recommended cable: OTSC-VB 2PX0.5SQ (made by Onamba Co., Ltd.) or equivalent (Use a twisted pair cable.)

Terminator (Terminal Resistor)

The terminator is mounted at the end of the wire when connecting multiple peripheral devices to a personal computer. The terminator prevents signal reflection and disturbance.

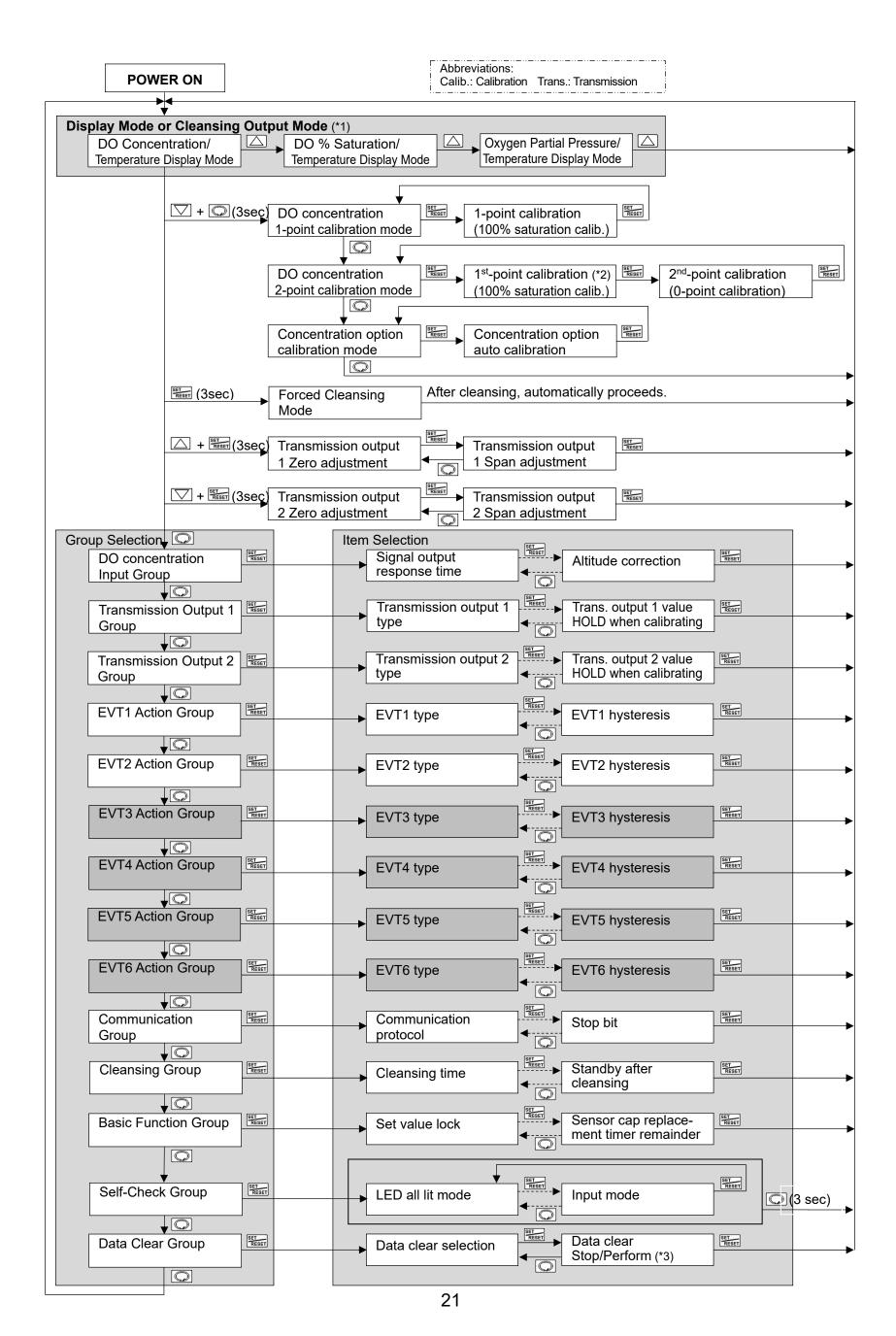
Do not connect a terminator with the communication line because each WIL-102-DO has built-in pull-up and pull-down resistors.

Communication converter IF-400 (sold separately) has a built-in terminal resistor.

6. Outline of Key Operation and Setting Groups

6.1 Outline of Key Operation

	Setting items are divided into groups, and group selection has to be made with keypads. Press the key in Display Mode or Cleansing Output Mode. The unit enters Group Selection Mode. Select a group with the key, and press the key. The unit enters each setting item. To set each setting item, use the or wey, and register the set value with the key. If the key is held down for 3 seconds at any setting item, the unit will revert to Display Mode or Cleansing Output Mode.
<u> </u>	2 Catting Crayes
ъ.	2 Setting Groups Setting groups are indicated on p.21.
	[About setting items] Setting group or setting item in shaded section will be displayed only when the corresponding option is ordered.
	 (*1) In Cleansing Output Mode, the measured value (DO concentration, DO % saturation, Oxygen partial pressure, Temperature) will be held during cleansing action (Cleansing time, Standby after cleansing). (*2) If errors occur during 1st-point calibration (100% saturation calibration) while in 2-point calibration mode, press the or less key. The unit will revert to Display Mode or Cleansing Output Mode. (*3) Depending on the selection in [Data clear Stop/Perform], the unit operates as follows. If 'Data clear Stop' is selected, data will not be cleared. The unit will revert to the mode prior to Data clear Stop (either Display Mode or Cleansing Output Mode). If 'Data clear Perform' is selected, data will be cleared. The unit will revert to the mode prior to Data clear Perform (either Display Mode or Cleansing Output Mode). (While data is being cleared, all indications are momentarily unlit.)
	About Key Operation
	• 🛆, 🔘, 🖼: Press the 🛆, 🔘 or 🗱 key. The unit will proceed to the next setting item,
	illustrated by an arrow. ———————————————————————————————————
	or : Press the or key until the desired setting mode appears.
	• ☑ + ☑ (3 sec): Press and hold the ☑ key and ☑ key (in that order) together for approx. 3 seconds. The unit will proceed to DO concentration 1-point Calibration mode.
	• [SEE] (3 sec), (3 sec): Press the [SEE] key or (3 key for approx. 3 seconds. The unit will proceed to the next setting mode, illustrated by an arrow.
	• 🛆 + 🖫 (3 sec): Press and hold the 🛆 key and 🖫 key (in that order) together for approx. 3 seconds. The unit will proceed to Transmission output 1 Zero adjustment.
	• 🔽 + 🖼 (3 sec): Press and hold the 🔽 key and 🖼 key (in that order) together for approx. 3 seconds. The unit will proceed to Transmission output 2 Zero adjustment.



7. Setup

Setup should be done before using this instrument according to the user's conditions:

Setting the DO concentration input, Transmission output 1, Transmission output 2, EVT1, EVT2, EVT3 to EVT6 (EVT option) types, Communication, Cleansing and Indication settings, etc.

Setup can be conducted in the groups below:

DO Concentration Input Group, Transmission Output 1 Group, Transmission Output 2 Group, EVT1 to EVT6 Action Groups, Communication Group, Cleansing Group, Basic Function Group If the user's specification is the same as the factory default value of the WIL-102-DO, or if setup has already been completed, it is not necessary to set up the instrument. Proceed to "8. Calibration (p.41)".

7.1 Turn the Power Supply to the WIL-102-DO ON.

For approx. 8 seconds after the power is switched ON, the following characters are indicated on the DO Display and Temperature Display.

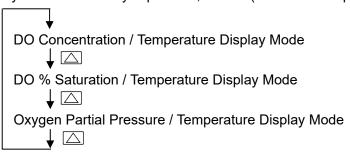
Display	Indication
DO Display	do
Temperature Display	☐ ば☐☐ [Version number (e.g.) 1.00]

During this time, all outputs are in OFF status, and action indicators except the PWR indicator turn off. After that, measurement starts, indicating DO concentration, DO % saturation or Oxygen partial pressure on the DO Display, and temperature on the Temperature Display.

This status is called Display Mode or Cleansing Output Mode.

Switching Between Modes

Every time the \(\triangle \) key is pressed, modes (on the DO Display) progress as follows.



7.2 DO Concentration Input Group

To enter the DO Concentration Input Group, follow the procedure below.

- 1 F.ac. Press the key once in Display Mode or Cleansing Output Mode.
- ② dfcl Press the key.

The unit enters the DO Concentration Input Group, and "Signal output response time" will appear.

Character	Setting Item, Function, Setting Range	Factory Default	
dFc[Signal output response time	60 seconds	
5 50	Sets the signal output response time.		
	Moving average is calculated from the set signal o	output response time, and the	
	resulting value is updated every Data update cycle	e (fixed at 5 seconds) as a	
	measurement value.		
	Moving average = Signal output response time	÷ Data update cycle (5 sec.)	
	(e.g.) If signal output response time is set to 50 s	econds, the Moving average will be:	
	50/5 = 10 (times)		
	However, signal output response time setting will be invalidated during DO		
	concentration calibration mode, Transmission output 1 adjustment mode, or		
	Transmission output 2 adjustment mode.		
	Setting range: 5 to 600 seconds		
58LF	Salinity correction	0 PSU	
	Sets the salinity concentration correction value.		
	Setting range: 0 to 42 PSU		
SEAL	Altitude correction	0 m	
	Sets altitude.		
	Setting range: 0 to 5000 m		

7.3 Transmission Output 1 Group

To enter the Transmission Output 1 Group, follow the procedure below.

- ① 「.r.a. ! Press the Display Mode or Cleansing Output Mode.
- ② 「「□ ! Press the RESET key.

The unit enters Transmission Output 1 Group, and "Transmission output 1 type" will appear.

Character	Setting Item, Function, Setting Range	Factory Default
[rol	Transmission output 1 type	DO concentration transmission
do	Selects Transmission output 1 type.	
	• ರಠ : DO concentration transmission	
	ฉีเรือีP : Water temperature transmission	
	」 ぱっぱ : DO % saturation transmission	
	ュアテト:Oxygen partial pressure transmission	
[-H	Transmission output 1 high limit	20.00 mg/L
20.00	Sets Transmission output 1 high limit value. (This '	value correponds to 20 mA DC
	output.)	
	If Transmission output 1 high limit and low limit a	are set to the same value,
	Transmission output 1 will be fixed at 4 mA DC.	
	Setting range: Transmission output 1 low limit to	Measurement range high limit
I-LI	Transmission output 1 low limit	0.00 mg/L
	Sets Transmission output 1 low limit value. (This v	alue correponds to 4 mA DC
	output.)	
	If Transmission output 1 high limit and low limit a	re set to the same value,
	Transmission output 1 will be fixed at 4 mA DC.	
_	Setting range: Measurement range low limit to Transport	ansmission output 1 high limit
[Transmission output 1 status when calibrating	Last value HOLD
• Selects Transmission output 1 output status when calibrating DO concentrate		en calibrating DO concentration.
	• Selection item: • EFH: Last value HOLD (Retains the last value)	hofore colibrating DO concentration
	and outputs it.)	e before calibrating DO concentration,
	ったい outputs the value set	in [Transmission output 1 value HOLD
	when calibrating].)	·
	FBH: Measured value (Outputs the measured value when calibrating DO	
<u> </u>	concentration.)	
[-5]	Transmission output 1 value HOLD when	0.00 mg/L
	calibrating	
	 Sets Transmission output 1 value HOLD. Available only when 「たけ」 (Set value HOLD) is selected in [Transmission output 1 	
	status when calibrating].	
	Setting range: Measurement range low limit to Measurement range high limit	
	• Setting range, Measurement range low limit to Measurement range night limit	

7.4 Transmission Output 2 Group

To enter the Transmission Output 2 Group, follow the procedure below.

- ி 「.r.a.d Press the 🔘 key 3 times in Display Mode or Cleansing Output Mode.
- 2 / r a d Press the RESET key.

The unit enters Transmission Output 2 Group, and "Transmission output 2 type" will appear.

Character	Setting Item, Function, Setting Range	Factory Default
[ro2	Transmission output 2 type	DO concentration transmission
do	Selects Transmission output 2 type.	
	• ರೆಡ್ : DO concentration transmission	
	ធំរី ភិទី : Water temperature transmission	
	ゴロウ「:DO % saturation transmission	
	<u> </u>	
[-H2	Transmission output 2 high limit	20.00 mg/L
20.00	Sets Transmission output 2 high limit value. (This \)	value correponds to 20 mA DC
	output.)	
	If Transmission output 2 high limit and low limit a	are set to the same value,
	Transmission output 2 will be fixed at 4 mA DC.	
	Setting range: Transmission output 2 low limit to	<u> </u>
[-L2	· · · · · · · · · · · · · · · · · · ·	0.00 mg/L
	Sets Transmission output 2 low limit value. (This value)	alue correponds to 4 mA DC
	output.)	
	If Transmission output 2 high limit and low limit are set to the same value,	
	Transmission output 2 will be fixed at 4 mA DC.	
r -	Setting range: Measurement range low limit to Tra	<u> </u>
[r.c2 bEFH	Transmission output 2 status when calibrating	Last value HOLD
	 Selects Transmission output 2 output status when calibrating DO concentration. Selection item: 	
	bEFH: Last value HOLD (Retains the last value	e before calibrating DO concentration.
	and outputs it.)	,,
	ったっと Set value HOLD (Outputs the value set in [Transmission output 2 value HOLD	
	when calibrating].)	
	PBH:: Measured value (Outputs the measured value when calibrating DO	
[- - -	concentration.) Transmission output 2 value HOLD when	0.00 mg/L
	calibrating	0.00 mg/L
	Sets Transmission output 2 value HOLD.	
	• Available only when 与后为 (Set value HOLD) is selected in [Transmission output 2	
	status when calibrating].	
	Setting range: Measurement range low limit to Measurement range high limit	

7.5 EVT1 Action Group

To enter the EVT1 Action Group, follow the procedure below.

- ① $\it EBF. \it I$ Press the $\it \Box$ key 4 times in Display Mode or Cleansing Output Mode.
- ② EFF! Press the key.

The unit proceeds to the EVT1 Action Group, and "EVT1 type" will appear.

Character	Setting Item, Function, Setting Range	Factory Default	
EFF !	EVT1 type	No action	
	• Selects an EVT1 output type.	The determ	
	Note: If EVT1 type is changed, EVT1 value defaults to 0.00 or 0.0.		
	• EEEE: No action		
	: DO concentration input high limit a	nction	
	ゴローム:DO concentration input low limit ad		
	ಫ್		
	นักกัน: Water temperature input low limit a	<u> </u>	
	ゴロウガ : DO % saturation input high limit ac	,	
	ゴロトに: DO % saturation input low limit act		
	ュラテH:Oxygen partial pressure input high	limit action	
	『『ローロー input low』 これ	limit action 💚	
	「こ号字:Sensor cap replacement timer (Fig	j. 7.5-3) (p.27)	
	っとした:Self-Check output (p.27)		
	ェレモム:Cleansing output (Fig. 7.5-4) (p.27)	
	ರಂಗ್ : DO concentration input High/Low I	, - , , , , , , , , , , , , , , , , , ,	
	ドラピン: Water temperature input High/Low		
	ログライル: DO % saturation input High/Low lir	, . ,	
	ュアガニ:Oxygen partial pressure input High/L	ow limits independent action (Fig.7.5-2) (p.27)	
	• EVT1 Action (Activated based on the ind	ication value.)	
	DO concentration input high limit	DO concentration input low limit	
	Water temperature input high limit	Water temperature input low limit	
	DO % saturation input high limit	DO % saturation input low limit	
	Oxygen partial pressure input high limit	Oxygen partial pressure input low limit	
	If Medium Value is selected in [EVT1 hysteresis	If Medium Value is selected in [EVT1 hysteresis	
	type]: EVT1 ON sides	type]: EVT1 ON sides	
		1. 613 1	
	ON	ON	
		T I I	
	OFF OFF	OFF	
	$\stackrel{\triangle}{\mid}$ EVT1 value	EVT1 value	
	If Reference Value is selected in [EVT1	If Reference Value is selected in [EVT1	
	hysteresis type]:	hysteresis type]:	
	EVT1 OFF side* EVT1 ON side*	EVT1 ON side* EVT1 OFF side*	
	ON	ON	
		T	
		OFF	
	EVT1 Value	EVT1 value	
	(Fig. 7		
	* Setting Example:		
	If [EVT1 ON side (dFa /)] is set to 0, I		
	at the value set in [EVT1 value (っぱ / に		
	If [EVT1 OFF side (ゴテレ /)] is set to 0,		
	at the value set in [EVT1 value (っぱ に	0].	

DO concentration input High/Low limits independent action
Water temperature input High/Low limits independent action
DO % saturation input High/Low limits independent action
Oxygen partial pressure input High/Low limits independent action

EVT1 hysteresis

EVT1 hysteresis

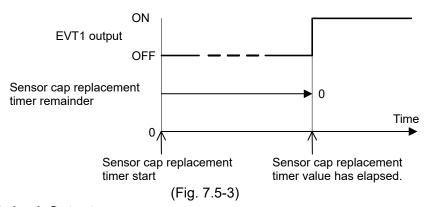
EVT1 High/Low limits
independent lower side value

EVT1 High/Low limits
independent upper side value

(Fig. 7.5-2)

Sensor Cap Replacement Timer Output

If the set Sensor cap replacement timer value has elapsed (when sensor cap replacement timer remainder is "0"), EVT1 output will be turned ON.



Self-check Output

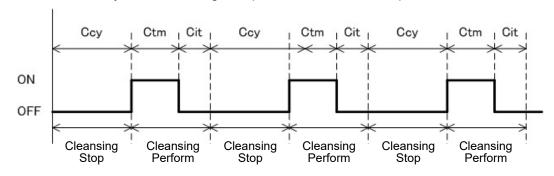
If the following error occurs, EVT1 output will be turned ON.

Error Code	Description
Err !	DO Sensor communication errors have occurred, or DO
	sensor is not connected.
Err2	DO Sensor cap is not attached, or it is incorrectly attached.
Err3	Calibration error (If input errors have occurred, or if calibration
	cannot be performed 30 minutes after starting calibration)

Cleansing Output

After 'Cleansing inactive interval' has elapsed, EVT1 output is turned ON during the configured 'Cleansing time'.

After 'Standby after Cleansing' has passed, this action is repeated.



Ccy: Cleansing inactive interval

Ctm: Cleansing time

Cit: Standby after cleansing

(Fig. 7.5-4)

Character	Setting Item, Function, Setting Range	Factory Default
58 I	EVT1 value	DO concentration input: 0.00 mg/L
		Water temperature input: 0.0℃
		DO % saturation input: 0.0%
		Oxygen partial pressure input: 0.0 kPa
	Sets EVT1 value.	
	• Not available for this setting item and all subsequ	uent items if [=[=]=] (No action),
	「こ吊尸 (Sensor cap replacement timer), 与とし方	(Self-check output), or $\sqsubseteq L \sqsubseteq \overline{L}$
	(Cleansing output) is selected in [EVT1 type].	
	Setting range:	
	DO concentration input: 0.00 to 20.00 mg/L	
	Water temperature input: 0.0 to 50.0°C	
	DO % saturation input: 0.0 to 200.0%	
	Oxygen partial pressure input: 0.0 to 150.0 kPa	
di Fi	EVT1 hysteresis type	Reference Value
5d1 F	• Selects EVT1 output hysteresis type (Medium or	,
	• Not available if ರಡ್ ಗಳ (DO concentration input F	• •
	ドゥピ (Water temperature input High/Low limits	• • • • • • • • • • • • • • • • • • • •
	saturation input High/Low limits independent action	on) or ឆ្នាំ
	input High/Low limits independent action) is select	cted in [EVT1 type].
	・ ヮゟ゚゛ゟ゙: Medium Value	
	Sets the same value for both ON and O	FF sides in relation to EVT1 value.
	Only ON side needs to be set.	
	っぱい F: Reference Value	
	Sets individual values for ON and OFF	
	Both ON and OFF sides need to be set	-
dFo!	EVT1 ON side	DO concentration input: 0.01 mg/L
		Water temperature input: 1.0°C DO % saturation input: 0.1%
		Oxygen partial pressure input: 0.1 kPa
	Sets the span of EVT1 ON side.	Oxygen partial pressure input. 0.1 ki a
	If	vsteresis type] the span of ON/OFF
	side will be the same value.	yetereele type], the span of enver
	• Not available if 💆 🖽 (DO concentration input F	High/Low limits independent action).
	「うだ」(Water temperature input High/Low limits	
	saturation input High/Low limits independent action) or $\bar{\omega} P H L$ (Oxygen partial pressure	
	input High/Low limits independent action) is selec	, , , , , ,
	• Setting range:	[=
	DO concentration input: 0.00 to 4.00 mg/L	
	Water temperature input: 0.0 to 10.0°ℂ	
	DO % saturation input: 0.0 to 40.0%	
	Oxygen partial pressure input: 0.0 to 30.0 kPa	
dFU!	EVT1 OFF side	DO concentration input: 0.01 mg/L
		Water temperature input: 1.0°C
		DO % saturation input: 0.1%
	0-4-46	Oxygen partial pressure input: 0.1 kPa
	• Sets the span of EVT1 OFF side.	ted in IEV/TA brokens 1 4 3
	• Not available if $rac{d!}{r}$ (Medium Value) is select	tea in [∟v i 1 nysteresis type].
	• Setting range:	
	DO concentration input: 0.00 to 4.00 mg/L	
	Water temperature input: 0.0 to 10.0°C	
	DO % saturation input: 0.0 to 40.0%	
	Oxygen partial pressure input: 0.0 to 30.0 kPa	

Character	Setting Item, Function, Setting Range	Factory Default	
on[EVT1 ON delay time	0 seconds	
	 Sets EVT1 ON delay time. The EVT1 output does not turn ON (under the conditions of turning ON) until the time set in [EVT1 ON delay time] elapses. Setting range: 0 to 9999 seconds 		
aff !	EVT1 OFF delay time	0 seconds	
<i>0</i>	 Sets EVT1 OFF delay time. The EVT1 output does not turn OFF (under the conditions of turning OFF) until the time set in [EVT1 OFF delay time] elapses. Setting range: 0 to 9999 seconds 		
		ets Output ON time when EVT1 output is ON. ON time and OFF time are set, EVT1 output can be turned ON/OFF in a configured	
	cycle when EVT1 output is turned ON. (Fig. 7.5-5 • Setting range: 0 to 9999 seconds)	
00F	Output OFF time when EVT1 output ON • Sets Output OFF time when EVT1 output is ON.	0 seconds	
	If ON time and OFF time are set, EVT1 output can be turned ON/OFF in a configured cycle when EVT1 output is turned ON. (Fig. 7.5-5) • Setting range: 0 to 9999 seconds		
	• Timing chart (Output ON time and OFF time when EVT1 output is ON)		
	Actual EVT1 output OFF ON EVT1 output to which ON time and OFF time are set. OFF ON (Fig. 7.5-5)	ON time is turned OFF, caused by the actual EVT1 output turning OFF.	
E_L !	EVT1 High/Low limits independent	OO concentration input: 0.00 mg/L	
<u> </u>		Vater temperature input: 0.0℃ DO % saturation input: 0.0% Dxygen partial pressure input: 0.0 kPa	
	 Sets the lower side value of EVT1 High/Low limits independent action. Available when ゴロガル (DO concentration input High/Low limits independent action), ローン Saturation input High/Low limits independent action) or ローン Concentration input High/Low limits independent action) or ローン Concentration input High/Low limits independent action) is selected in [EVT1 ty Setting range: DO concentration input: 0.00 to 20.00 mg/L Water temperature input: 0.0 to 50.0°C DO % saturation input: 0.0 to 200.0% Oxygen partial pressure input: 0.0 to 150.0 kPa 		

Character	Setting Item, Function, Setting Range	Factory Default
E_H !	EVT1 High/Low limits independent	DO concentration input: 0.00 mg/L
	upper side value	Water temperature input: 0.0℃
		DO % saturation input: 0.0%
		Oxygen partial pressure input: 0.0 kPa
	• Sets the upper side value of EVT1 High/Low lir	nits independent action.
	Setting range:	
	DO concentration input: 0.00 to 20.00 mg/L	
	Water temperature input: 0.0 to 50.0℃	
	DO % saturation input: 0.0 to 200.0%	
	Oxygen partial pressure input: 0.0 to 150.0 kPa	
EHY !	EVT1 hysteresis	DO concentration input: 0.01 mg/L
		Water temperature input: 1.0℃
		DO % saturation input: 0.1%
	Oxygen partial pressure input: 0.1 kPa	
	Sets hysteresis of EVT1 High/Low limits independent action.	
	Setting range:	
	DO concentration input: 0.01 to 2.00 mg/L	
	Water temperature input: 1.0 to 5.0℃	
	DO % saturation input: 0.1 to 20.0%	
	Oxygen partial pressure input: 0.1 to 15.0 kPa	

7.6 EVT2 Action Group

To enter EVT2 Action Group, follow the procedure below.

- 1 E.H.F.2 Press the key 5 times in Display Mode or Cleansing Output Mode.
- 2 EFFE Press the key.

The unit proceeds to EVT2 Action Group, and "EVT2 type" appears.

Action, indication condition and setting range of EVT2 Action Group are the same as those of EVT1 Action Group.

Substitute EVT1 with EVT2 ($\frac{1}{2}$ with $\frac{1}{2}$), and refer to EVT1 Action Group (pp. 26 to 30).

7.7 EVT3 Action Group

Available when EVT output (EVT option) is ordered.

To enter EVT3 Action Group, follow the procedure below.

- 1 ELL.3 Press the key 6 times in Display Mode or Cleansing Output Mode.
- ② *EFF∃* Press the key.

The unit proceeds to EVT3 Action Group, and "EVT3 type" appears.

Action, indication condition and setting range of EVT3 Action Group are the same as those of EVT1 Action Group.

Substitute EVT1 with EVT3 († with $\vec{\beta}$), and refer to EVT1 Action Group (pp. 26 to 30).

7.8 EVT4 Action Group

Available when EVT□ output (EVT option) is ordered.

To enter EVT4 Action Group, follow the procedure below.

- 1 E.B.T.Y Press the key 7 times in Display Mode or Cleansing Output Mode.
- ② EFFY Press the FEEF key.

The unit proceeds to EVT4 Action Group, and "EVT4 type" appears.

Action, indication condition and setting range of EVT4 Action Group are the same as those of EVT1 Action Group.

Substitute EVT1 with EVT4 ('with '), and refer to EVT1 Action Group (pp. 26 to 30).

7.9 EVT5 Action Group

Available when EVT output (EVT option) is ordered.

To enter the EVT5 Action Group, follow the procedure below.

- 1 E.B. . 5 Press the key 8 times in Display Mode or Cleansing Output Mode.
- 2 EFF5 Press the key.

The unit proceeds to EVT5 Action Group, and "EVT5 type" appears.

Action, indication condition and setting range of EVT5 Action Group are the same as those of EVT1 Action Group.

Substitute EVT1 with EVT5 (/ with 5), and refer to EVT1 Action Group (pp. 26 to 30).

7.10 EVT6 Action Group

Available when EVT output (EVT option) is ordered.

To enter the EVT6 Action Group, follow the procedure below.

- 1 E.B.F.5 Press the key 9 times in Display Mode or Cleansing Output Mode.
- 2 EFF5 Press the key.

The unit proceeds to EVT6 Action Group, and "EVT6 type" appears.

Action, indication condition and setting range of EVT6 Action Group are the same as those of EVT1 Action Group.

Substitute EVT1 with EVT6 (1 with 5), and refer to EVT1 Action Group (pp. 26 to 30).

7.11 Communication Group

To enter the Communication Group, follow the procedure below.

1 5,5,5,5	Press the key 6 times in Display Mode or Cleansing Output Mode.
	If EVT□ output (EVT option) is ordered, press the □ key 10 times in Display Mode
<u> </u>	or Cleansing Output Mode.

② cā'h' Press the RESET key.

The unit enters the Communication Group, and "Communication protocol" will appear.

Character	Setting Item, Function, Setting Range Communication protocol	Factory Default
<u>- </u>	Communication protocol	
		Shinko protocol
	Selects the communication protocol.	
	• กอกิไ: : Shinko protocol	
	ក್¤ದೆ∺ : MODBUS ASCII mode	
	ಗೆದರ್ದ : MODBUS RTU mode	
cōng H	nstrument number	0
	Sets the instrument number. (The instrument numbers should be set one by one when	
	multiple instruments are connected.)	
	Setting range: 0 to 95	
<u>-</u>	Communication speed	9600 bps
95 .	Selects a communication speed equal to that of t	he host computer.
	9600 bps	
	☐ <i>'月己</i> ': 19200 bps	
	□∃84 : 38400 bps	
<u>c </u>	Data bit/Parity	7 bits/Even
	Selects data bit and parity.	
	อิกอก:8 bits/No parity	
	ไก¤ก ∶ 7 bits/No parity	
	8ียีก : 8 bits/Even	
	፲ <i>E ዜ</i> : 7 bits/Even	
	ಶ್ವರದ : 8 bits/Odd	
	ೌರದ್ದ : 7 bits/Odd	
<u>-</u>	Stop bit	1 bit
iai	Selects the stop bit.	
-	/ : 1 bit	
	□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□	

7.12 Cleansing Group

To enter the Cleansing Group, follow the procedure below.

- 2 clin Press the key.

The unit enters the Cleansing Group, and "Cleansing time" will appear.

Character	Setting Item, Function, Setting Range	Factory Default
cLFA	Cleansing time	30 seconds
<i>□□∃□</i>	• Sets the time to perform cleansing. (Fig. 7.12-1)	
	Setting range: 10 to 120 seconds	
cLcY	Cleansing inactive interval	OFF (None)
oFF[]	Sets the cleansing inactive interval. (Fig. 7.12-1)	
	Setting range:	
	□FF□□ (None), 10 to 240 minutes	
<u> </u>	Standby after cleansing	0 seconds
	• Sets standby time after cleansing action. (Fig. 7.12-1)	
	Setting range: 0 to 60 seconds	

Cleansing Function

The selected EVT output is turned ON during 'cleansing time' after 'Cleansing inactive interval' has elapsed.

After 'Standby after cleansing' has passed, the above action is repeated.

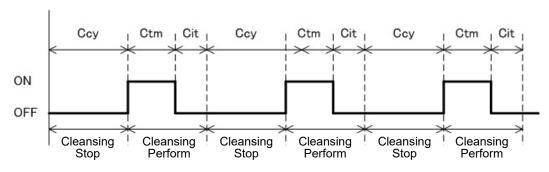
While cleansing action is performing using 'Cleansing time' and 'Standby after cleansing', other outputs are in OFF status.

Measured value (DO concentration, DO % saturation, Oxygen partial pressure, Water temperature) will be retained.

Normal programmed action will be performed, except during Cleansing Perform action.

If the power is turned on again, starts from 'Cleansing inactive interval'.

Cleansing Output Action



Ccy: Cleansing inactive interval

Ctm: Cleansing time Cit: Standby after cleansing

(Fig. 7.12-1)

• If abla
abla
abla
abla
abla
current setting values (Cleansing time, Standby after cleansing, Cleansing inactive interval) will be used for the selected cleansing output.

If cleansing action (caused by cleansing cycle) is activated in calibration mode, cleansing action will not be performed in the current session.

• If $\Box FF \Box$ (None) is selected in [Cleansing inactive interval], or if any item except $\Box LEG$ (Cleansing output) is selected in [EVT type], Cleansing Output Mode will end, and the unit will revert to Display Mode.

7.13 Basic Function Group

To enter the Basic Function Group, follow the procedure below.

- ① a.F.E.r Press the key 8 times in Display Mode or Cleansing Output Mode.

 If EVT output (EVT option) is ordered, press the key 12 times in Display Mode or Cleansing Output Mode.
- 2 Lack Press the set key.

The unit enters the Basic Function Group, and the "Set value lock" will appear.

Character	The unit enters the Basic Function Group, and the "Set va		
Character	Setting Item, Function, Setting Range	Factory Default	
Lock	Set value lock	Unlock	
	Locks the set values to prevent setting errors. The set values can be abanded.		
	• (Unlock): All set values can be changed.		
	Lock 1): None of the set values can be changed.		
	Lac 2 (Lock 2): Only EVT1 to EVT6 values can be changed.		
	Lロロヨ (Lock 3): All set values can be temporarily changed. However, they revert to their previous value after the power is turned		
	off because they are not saved in the	•	
	Do not change setting items (EVT1, EV	-	
	types). If they are changed, they will a		
	Be sure to select Lock 3 when changi	_	
	software communication. (If a value set via software communication is		
	the same as the value before the setti		
	in non-volatile IC memory.)		
1155	Auto-light function	Disabled	
[-]-[-]	Selects Auto-light Enabled/Disabled.		
	• ====: Disabled		
	IJっE⊡: Enabled		
r: AE	Indication time	00.00 (Remains lit)	
00.00	Sets the indication time of the displays after the last key	operation until displays turn	
	off while in Display Mode or Cleansing Output Mode.		
	Displays remain lit when set to 00.00.		
	Displays light up when any key is pressed while in unlit status.		
	Setting range: 00.00 (Remains lit.)		
	00.01 to 60.00 (Minutes.Seconds)	T	
1 Err	EVT output when input errors occur	Disabled	
off.	• If input errors occur, EVT output can be Enabled or Disa		
	If "Enabled" is selected, EVT output will be maintained when input errors occur.		
	If "Disabled" is selected, EVT output will be turned OFF	•	
	• Available when the following type is selected in [EVT type]:		
	□□□ H (DO concentration input high limit action)		
	ロローム (DO concentration input low limit action) エデガオ (Water temperature input high limit action) エデガム (Water temperature input low limit action)		
	리하는 (Maior temperature input for limit action)		
	ゴロケム (DO % saturation input low limit action)		
	교무다님 (Oxygen partial pressure input high limit action	n)	
	レディン (Oxygen partial pressure input low limit action)		
	• Selection item: prill: Enabled		
	<i>□FF</i> ∷ Disabled		
58 I	EVT1 value	365 days	
<u> </u>	Sets EVT1 value (Sensor cap replacement timer).		
	Available when ፲፰፰ੵ (Sensor cap replacement timer) is selected in [EVT1 type].		
	Setting range: 0 to 1095 days		

Character	Setting Item, Function, Setting Range	Factory Default	
on[EVT1 ON delay time	0 seconds	
	Sets EVT1 ON delay time.		
	The EVT1 output does not turn ON after the input value exceeds the EVT1 (Sensor		
	cap replacement timer) value until the time set in [EVT1 ON delay time] elapses.		
	• Available when ਿਛਜਿ (Sensor cap replacement timer) is selected in [EVT1 type].		
	Setting range: 0 to 9999 seconds		
□FΓ ¦	EVT1 OFF delay time	0 seconds	
	Sets EVT1 OFF delay time.		
	The EVT1 output does not turn OFF after the input value exceeds the EVT1 (Sen		
	cap replacement timer) value until the time set in [EVT1 0	- ·	
	・Available when ドロヨロ (Sensor cap replacement timer)	is selected in [EVT1 type].	
	Setting range: 0 to 9999 seconds		
'-820	EVT2 value	365 days	
<i>□3</i> 65	Sets EVT2 value (Sensor cap replacement timer).		
	Available when 「ロボラ (Sensor cap replacement timer)	is selected in [EVT2 type].	
	Setting range: 0 to 1095 days		
on[2	EVT2 ON delay time	0 seconds	
	Sets EVT2 ON delay time.		
	The EVT2 output does not turn ON after the input value e	exceeds the EVT2 (Sensor	
	cap replacement timer) value until the time set in [EVT2 0		
	• Available when 万⊑吊尸 (Sensor cap replacement timer)	is selected in [EVT2 type].	
	Setting range: 0 to 9999 seconds		
aFT2	EVT2 OFF delay time	0 seconds	
	Sets EVT2 OFF delay time.		
	The EVT2 output does not turn OFF after the input value exceeds the EVT2 (Ser		
	cap replacement timer) value until the time set in [EVT2 OFF delay time] elapses.		
	• Available when ドロオ (Sensor cap replacement timer)	is selected in [EVT2 type].	
, , , - ,;;	• Setting range: 0 to 9999 seconds		
483O	EVT3 value	365 days	
□385	 Sets EVT3 value (Sensor cap replacement timer). Available when EVT□ output (EVT option) is ordered. Available when □□□□ (Sensor cap replacement timer) is selected in [EVT3 type]. 		
r -,	• Setting range: 0 to 1095 days		
	EVT3 ON delay time	0 seconds	
	• Sets EVT3 ON delay time.		
	The EVT3 output does not turn ON after the input value exceeds the EVT3 (Sensor		
	cap replacement timer) value until the time set in [EVT3 ON delay time] elapses.		
	• Available when EVT output (EVT option) is ordered. Available when F = F = (Sensor cap replacement timer) is selected in [EVT3 type].		
r r =	• Setting range: 0 to 9999 seconds	0	
of:3	EVT3 OFF delay time	0 seconds	
	• Sets EVT3 OFF delay time.		
	The EVT3 output does not turn OFF after the input value exceeds the EVT3 (Sensor		
	cap replacement timer) value until the time set in [EVT3 OFF delay time] elapses.		
	• Available when EVT output (EVT option) is ordered.		
	Available when F = AP (Sensor cap replacement timer) is selected in [EVT3 type].		
	Setting range: 0 to 9999 seconds		

Character	Setting Item, Function, Setting Range	Factory Default
584	EVT4 value	365 days
<i>⊞36</i> 5	Sets EVT4 value (Sensor cap replacement timer).	
	Available when EVT□ output (EVT option) is ordered.	
	Available when 「ʿʿʿ Ḥ̄ Ḥ̄ ' (Sensor cap replacement timer) is selected in [EVT4 type].	
	Setting range: 0 to 1095 days	
on[4	EVT4 ON delay time	0 seconds
	Sets EVT4 ON delay time. The EVT4 output does not turn ON after the input value exceeds the EVT4 (Sensor).	
	cap replacement timer) value until the time set in [EVT4 ON delay time] elapses.	
	• Available when EVT output (EVT option) is ordered.	
	Available when $\Gamma \subset BP$ (Sensor cap replacement timer) is selected in [EVT4 type].
	Setting range: 0 to 9999 seconds	
off4	EVT4 OFF delay time	0 seconds
	Sets EVT4 OFF delay time.	
	The EVT4 output does not turn OFF after the input value	•
	cap replacement timer) value until the time set in [EVT4 OFF delay time] elapses.	
	• Available when EVT output (EVT option) is ordered.	
	Available when F = HP (Sensor cap replacement timer) is selected in [EVT4 type].	
, , , , , , , , , , , , , , , , , , , 	• Setting range: 0 to 9999 seconds	
<u>585</u>	EVT5 value 365 days	
<u> 3</u> 85	• Sets EVT5 value (Sensor cap replacement timer).	
	• Available when EVT output (EVT option) is ordered.	·
	Available when F = RP (Sensor cap replacement time)) is selected in [EV15 type].
on/5	Setting range: 0 to 1095 days EVT5 ON dalay time	0 seconds
	EVT5 ON delay time Sets EVT5 ON delay time.	U seconds
iiiii	,	eveneds the EVTE (Sensor
	The EVT5 output does not turn ON after the input value exceeds the EVT5 (Sensor cap replacement timer) value until the time set in [EVT5 ON delay time] elapses. • Available when EVT□ output (EVT option) is ordered. Available when 「□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□	
	Setting range: 0 to 9999 seconds	
oFF5	EVT5 OFF delay time	0 seconds
	• Sets EVT5 OFF delay time.	o coconido
·ii'='	The EVT5 output does not turn OFF after the input value exceeds the EVT5 (Sensor cap replacement timer) value until the time set in [EVT5 OFF delay time] elapses.	
	• Available when EVT□ output (EVT option) is ordered.	
	/ Wallable Wileli EV I = Catpat (EV I option) is cracica.	
	Available when 「□□□□ catput (□□□ option) to cracked.) is selected in [EVT5 type].

Character	Setting Item, Function, Setting Range	Factory Default	
585 <u></u>	EVT6 value	365 days	
<i>⊞365</i>	Sets EVT6 value (Sensor cap replacement timer).		
	• Available when EVT□ output (EVT option) is ordered.		
	Available when ドロピー (Sensor cap replacement timer	r) is selected in [EVT6 type].	
	Setting range: 0 to 1095 days		
on/5	EVT6 ON delay time	0 seconds	
	Sets EVT6 ON delay time.		
	The EVT6 output does not turn ON after the input value	exceeds the EVT6 (Sensor	
	cap replacement timer) value until the time set in [EVT6 ON delay time] elapses.		
	• Available when EVT□ output (EVT option) is ordered.		
	Available when ਿਟਸਿੰਸ (Sensor cap replacement timer) is selected in [EVT6 type].		
	Setting range: 0 to 9999 seconds		
oF15	EVT6 OFF delay time	0 seconds	
	Sets EVT6 OFF delay time.		
	The EVT6 output does not turn OFF after the input value	e exceeds the EVT6 (Sensor	
	cap replacement timer) value until the time set in [EVT6 OFF delay time] elapses.		
	• Available when EVT□ output (EVT option) is ordered.		
	Available when 「c ฅฅ (Sensor cap replacement timer) is selected in [EVT6 type].		
	Setting range: 0 to 9999 seconds		
rEFĀ	Sensor cap replacement timer remainder	365 days	
<i>□3</i> 55	Indicates the remaining time of the sensor cap replacen	nent timer.	
	Setting range: 0 to 1095 days		

7.14 Self-Check Group

To enter the Self-Check Group, follow the procedure below.

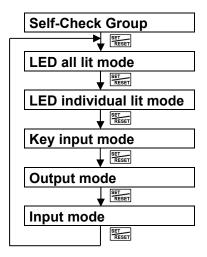
- ① ¬E.L.F Press the □ key 9 times in Display Mode or Cleansing Output Mode.

 If EVT□ output (EVT option) is ordered, press the □ key 13 times in Display Mode or Cleansing Output Mode.
- 2 888 Press the key.

The unit enters the Self-Check Group, and "LED all lit mode" will appear.

Every time the key is pressed, modes progress as follows.

If the key is held down for approx. 3 seconds in any setting mode, the unit will revert to the Display Mode or Cleansing Output Mode.



Following is a description of each mode.

Mode	Description		
LED all lit mode	All indications light up.		
	All displays and action indicators light up.		
LED individual lit	Each segm	ent lights up	sequentially every 0.5 seconds, in a cycle, as shown
mode	below.		
	1→ 2 → ···· → 11 → 1		
	Order		Contents
	1		'a' segment of DO Display, Temperature Display
	2		'b' segment of DO Display, Temperature Display
	3		'c' segment of DO Display, Temperature Display
	4		'd' segment of DO Display, Temperature Display
	5		'e' segment of DO Display, Temperature Display
	6		'f' segment of DO Display, Temperature Display
	7		'g' segment of DO Display, Temperature Display
	8		'dp' segment of DO Display, Temperature Display
	9	A1	A1 indicator
	10	A2	A2 indicator
	11	T/R	T/R indicator

Mode		Description	
Key input mode	Characters allocated to each key are indicated.		
	The DO Display indicates $\xi \xi \zeta$, and the Temperature Display indicates the		
	following characters.		
	If 2 or more keys are pressed simultaneously, db will be indicated.		
	Temperature Display	Key Input	
	nonE	When no key is pressed	
		When the key is pressed	
	doūn	When the W key is pressed	
	db	When 2 or more keys are pressed simultaneously	
Output mode	Each EVT output is turne		
	Transmission output 1 ar		
	The DO Display indicates	s ロビニ, and the Temperature Display indicates the	
	following characters.		
	Every time the 🛆 key i	s pressed, each output is turned ON sequentially after	
	being checked.		
	Temperature	Output	
	Display □FF	·	
		All EVT outputs OFF	
	EULI	Transmission output 1 and 2: 4 mA DC	
	E81.5	EVT1 output ON	
	<u> </u>	EVT2 output ON EVT3 output ON	
	<u> </u>	EVT4 output ON	
	EULZ	EVT5 output ON	
	<u> </u>	EVT6 output ON	
	r-ol	Transmission output 1: 20 mA DC	
	reg	Transmission output 2: 20 mA DC	
Input mode	Indicates each input.	Transmission surput 2. 20 m/ CDO	
mput mode		s pressed, input checking is performed, and the DO	
	1	onding input characters, and the Temperature Display	
	indicates corresponding measured value.		
	DO Display Temperature Display		
	do	DO concentration measured value	
	<u>J</u> [AP	Water temperature measured value	
	dohl	DO % saturation measured value	
	JP-5	Oxygen partial pressure measured value	
	nc8P	Sensor cap serial number	
	If a communication error	has occurred, or if the DO Sensor is not connected, the	
	Temperature Display indi	cates Err I.	
	I	not attached, or it is incorrectly attached, the	
	Temperature Display indi		
	-	r consists of 6 digits. Since Temperature Display of this	
		he DO Display indicates upper 2 figures,	
	_	play indicates the remaining 4 digits.	
	` ` ,	er is 123456, it is alternately indicated as follows.	
	$ \qquad \qquad$	11 12 1055	
		7458	

7.15 Data Clear Group

	If EVT \square output (EVT option) is ordered, press the \square key 14 times in Display Mode		
	or Cleansing Output Mode.		
2 = 1 -1	Press the set key.		
	The unit enters the Data Clear group, and the "Data clear selection" will appear.		
Character	Setting Item, Function, Setting Range Factory Default		
にとうと	Data clear selection	Calibration value	
∈RL□	Selects either Calibration value or Set value to clear.		
	• <i>⊏ឱL</i> ∷ Calibration value		
	っと「□: Set value		
cLr[]	Data clear Stop/Perform	Data clear Stop	
no			

Depending on the selection in [Data clear Stop/Perform], the unit operates as shown below.

1 c.L.r. Press the key 10 times in Display Mode or Cleansing Output Mode.

• When 'Data clear Stop' is selected:

Data clearing is not executed, and the unit returns to the mode prior to Data clear Stop (either Display Mode or Cleansing Output Mode).

• When 'Data clear Perform' is selected:

Data is cleared. The unit returns to the mode prior to Data clear Perform (either Display Mode or Cleansing Output Mode).

(While data is being cleared, all indications are momentarily unlit.)

To enter the Data Clear Group, follow the procedure below.

・ ヮヮ□□ : Data clear Stop 当を与□ : Data clear Perform

8. Calibration

The following are descriptions for DO concentration 1-point calibration mode, DO concentration 2-point calibration mode, Concentration option calibration mode, Transmission output 1 and 2 adjustment modes.

8.1 DO Concentration Calibration

8.1.1 Preparation

- (1) Clean the DO Sensor body and measurement section, and remove all moisture.
- (2) Remove the storage cap of the calibration container, and replace with a calibration cap (ventilating cap).





Calibration cap Storage cap (Fig. 8.1.1-1)

- (3) Keep the water, used for DO Sensor and calibration, at room temperature for approx. 30 minutes.
- (4) Select a mode from Sections 8.1.2 (DO Concentration 1-point Calibration Mode), 8.1.3 (DO Concentration 2-point Calibration Mode), and 8.1.4 (Concentration Option Calibration Mode), and perform calibration.

8.1.2 DO Concentration 1-point Calibration Mode



Caution

• If salinity concentration has been previously corrected, return the salinity concentration correction value to 0 PSU, then start calibration.

Refer to [Salinity correction (p.23)].

If calibration is performed with previously corrected salinity concentration, an error will occur, or calibration will not be performed normally.

• When using a sensor in geographically high elevation sites, perform altitude correction for accurate calibration, then start calibration.

Refer to [Altitude correction (p.23)].

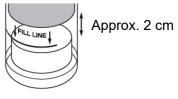
The unit cannot enter DO concentration 1-point calibration mode in the following cases.

- When $\angle \Box \Box \angle (\text{Lock 1})$, $\angle \Box \Box \Box \angle (\text{Lock 2})$ or $\angle \Box \Box \Box \angle (\text{Lock 3})$ is selected in [Set value lock (p.34)]
- When $\neg L E \Box$ (Cleansing output) is selected in any of [EVT1 to EVT6 types (pp. 26, 31)], and while cleansing action is performing using the 'Cleansing time' and 'Standby after cleansing'
- When the following errors have occurred.

Error Code	Description
ErrO	Non-volatile IC memory error
Err!	DO Sensor communication errors have occurred, or DO Sensor is not connected.
Err2	DO Sensor cap is not attached, or it is incorrectly attached.

The following outlines calibration procedure.

- (1) Pour approx. 10 mL of ion-exchanged water into the calibration container sponge.
- (2) Insert the DO Sensor into the calibration container until the measurement section of the sensor is situated approximately 2 cm away from the sponge.



(Fig. 8.1.2-1)

(3) Allow it to settle, undisturbed, for 5 to 10 minutes.



Caution

- Do not leave the sensor attached to the calibration container for more than 30 minutes. This will result in dew condensation in measurement section, which will affect measurement value. If dew condensation has occured, remove the moisture from the measurement section, then start calibration again.
- (4) Press and hold the \square and \square key (in that order) together for approx. 3 seconds in Display Mode or Cleansing Output Mode.

The unit moves to DO concentration 1-point calibration mode, and indicates the following.

Display	Indication Contents
DO Display	DO concentration measured value
Temperature Display	

(5) Press the key.

1-point calibration (100% saturation calibration) starts.

During calibration, the measurement value on the DO Display flashes.

Display	Indication Contents
DO Display	DO concentration measured value flashes.
Temperature Display	

- (6) Wait at least 10 seconds to stabilize the DO concentration measured value.
- (7) Press the FESET key.

The measured value will be fixed, and automatic calibration will be performed.

After calibration is finished. Displays show the following.

Display	Indication Contents
DO Display	cRL□
Temperature Display	Good

¹⁻point calibration (100% saturation calibration) is completed.

(8) Press the FESET key.

The unit returns to DO concentration 1-point calibration mode.

If calibration cannot be performed during 1-point calibration (100% saturation calibration) due to unstable DO concentration input or temperature correction error, etc., the DO Display turns off, and the Temperature Display indicates $\mathcal{E} \vdash \Gamma \supset \mathcal{E}$.

To release the error code, press the or key.

8.1.3 DO Concentration 2-point Calibration Mode



Caution

• When using a sensor in geographically high elevation sites, perform altitude correction for accurate calibration, then start calibration.

Refer to [Altitude correction (p.23)].

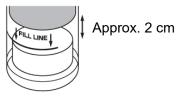
The unit cannot enter DO concentration 2-point calibration mode in the following cases.

- When $L \Box \Box L$ (Lock 1), $L \Box \Box \Box L$ (Lock 2) or $L \Box \Box D \Box L$ (Lock 3) is selected in [Set value lock (p.34)]
- When $\neg \bot \not \vdash \Box$ (Cleansing output) is selected in any of [EVT1 to EVT6 types (pp. 26, 31)], and while cleansing action is performing using the 'Cleansing time' and 'Standby after cleansing'.
- · When the following errors have occurred

Error Code	Description	
Err0	Non-volatile IC memory error	
Err !	DO Sensor communication errors have occurred, or DO Sensor is not	
	connected.	
Err2	DO Sensor cap is not attached, or it is incorrectly attached.	

The following outlines calibration procedure.

- (1) Pour approx. 10 mL of ion-exchanged water into the calibration container sponge.
- (2) Insert the DO Sensor into the calibration container until the measurement section of the sensor is situated approximately 2 cm away from the sponge.



(Fig. 8.1.3-1)

(3) Allow it to settle, undisturbed, for 5 to 10 minutes.



Caution

- Do not leave the sensor attached to the calibration container for more than 30 minutes. This will result in dew condensation in measurement section, which will affect measurement value. If dew condensation has occured, remove the moisture from the measurement section, then start calibration again.
- (4) Press and hold the \square and \square key (in that order) together for approx. 3 seconds in Display Mode or Cleansing Output Mode.
- (5) Press the key.

The unit moves to DO concentration 2-point calibration mode, and indicates the following.

Display	Indication Contents
DO Display	DO concentration measured value
Temperature Display	

(6) Press the key.

1st-point calibration (100% saturation calibration) starts.

During calibration, the measurement value on the DO Display flashes.

Display	Indication Contents
DO Display	DO concentration measured value flashes.
Temperature Display	

- (7) Wait at least 10 seconds to stabilize the DO concentration measured value.
- (8) Press the key.

The measured value will be fixed, and automatic calibration will be performed.

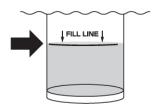
After 1st-point calibration (100% saturation calibration) is finished, Displays show the following.

Display	Indication Contents
DO Display	cRL□
Temperature Display	aeur

(9) Prepare a Zero standard solution.

Zero standard solution is 100 mL of ion-exchanged water into which 5 g or more of sodium sulfite has been added and completely dissolved.

(10) Take out the calibration container sponge used for 1st-point calibration, and pour the Zero standard solution into the calibration container up to the Fill Line.



(Fig. 8.1.3-2)

(11) Insert the temperature sensor of the DO Sensor until it is immersed in the prepared Zero standard solution.



Caution

- Insert the measurement section so that approximately 1 cm of gap is left between it and the bottom of the calibration container.
- Insert the measurement section so that air bubbles cannot attach to it.
- (12) Allow it to settle, undisturbed, for at least 5 minutes to stabilize the temperature.
- (13) Press the key.

2nd-point calibration (0-point calibration) starts.

During calibration, the measurement value on the DO Display flashes.

Display	Indication Contents
DO Display	DO concentration measured value flashes.
Temperature Display	

(14) Wait at least 10 seconds to stabilize the DO concentration measured value.

(15) Press the key.

The measured value will be fixed, and automatic calibration will be performed.

After 2nd-point calibration (0-point calibration) is finished, Displays show the following.

Display	Indication Contents
DO Display	cal
Temperature Display	Good

2-point calibration (both 100% saturation calibration and 0-point calibration) is completed.

(16) Press the key.

The unit returns to DO concentration 2-point calibration mode.

If calibration cannot be performed during DO concentration 2-point calibration due to unstable DO concentration input or temperature correction error, etc., the DO Display turns off, and the Temperature Display indicates $\mathcal{E} \vdash \mathcal{F} = \mathcal{F}$.

To release the error code, press the or key.

8.1.4 Concentration Option Calibration Mode

Immerse the DO Sensor in an aqueous solution (of which DO concentration is known), then the measurement value can be matched to the concentration.

Factory default value: 0.00 mg/L

DO concentration can be set within a range of 0.00 to 20.00 mg/L.

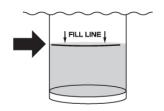
The unit cannot enter Concentration option calibration mode in the following cases.

- When $L \Box \Box \downarrow (Lock 1), L \Box \Box \Box \downarrow (Lock 2)$ or $L \Box \Box \Box \Box (Lock 3)$ is selected in [Set value lock (p.34)]
- When $\neg L E L$ (Cleansing output) is selected in any of [EVT1 to EVT6 types (pp. 26, 31)], and while cleansing action is performing using the 'Cleansing time' and 'Standby after cleansing'.
- When the following errors have occurred.

Error Code	Description
ErrO	Non-volatile IC memory error
Err 1	DO Sensor communication errors have occurred, or DO Sensor is not connected.
ErrZ	DO Sensor cap is not attached, or it is incorrectly attached.

The following outlines calibration procedure (Setting to a concentration of 7.77 mg/L).

(1) Pour the already-known concentration solution into the calibration container up to the Fill Line.



(Fig. 8 1 4-1)

(2) Insert the temperature sensor of the DO Sensor until it is immersed in the poured solution.



Caution

- Insert the measurement section so that approximately 1 cm of gap is left between it and the bottom of the calibration container.
- · Insert the measurement section without air bubbles being attached.

(3) Allow it to settle, undisturbed, for at least 5 minutes to stabilize the temperature.		
(4) Press and hold the and Mode or Cleansing Output M	key (in that order) together for approx. 3 seconds in Display lode.	
(5) Press the key twice.		
The unit moves to Concentration option calibration mode, and indicates the following.		
Display	Indication Contents	
DO Display	_cRdF	
Temperature Display	Concentration desired value	
(6) Set the concentration desired The following will be indicated	d value (7.77) with the $ riangle$ or $ riangle$ key, and press the $ riangle$ key.	
Display	Indication Contents	
DO Display	DO concentration measured value flashes.	
Temperature Display		
	ixed, and calibration will be performed. ation is finished, Displays show the following.	
Display	Indication Contents	
DO Display	<i>∈</i> ₽L□	
Temperature Display	Good	
Concentration option calibrati	ion is completed.	
(8) Press the RESET key. The unit reverts to Concentra	tion option calibration mode.	
(9) Press the key. The unit reverts to Display Mo	ode or Cleansing Output Mode.	
If errors occur during concentrat Temperature Display will indicate To release the error code, press		

8.2 Transmission Output 1 Adjustment Mode

Fine adjustment of Transmission output 1 is performed.

The WIL-102-DO is adjusted at the factory, however, differences may occur between the indication value of the connected equipment (recorders, etc.) and output value of this instrument. In this case, perform Transmission output 1 Zero adjustment and Span adjustment.

The unit cannot enter Transmission output 1 Zero adjustment mode in the following cases.

- When $\neg \vdash \vdash \vdash \vdash \vdash$ (Cleansing output) is selected in any of [EVT1 to EVT6 types (pp. 26, 31)], and cleansing action is performing using the 'Cleansing time' and 'Standby after cleansing'
- During DO concentration calibration

The following outlines the procedure for Transmission output 1 adjustment.

- (1) Press and hold the \triangle and $\stackrel{\blacksquare}{\sqsubseteq}$ key (in that order) together for approx. 3 seconds in Display Mode or Cleansing Output Mode.
- (2) The unit enters Transmission output 1 Zero adjustment mode, and indicates the following.

Display	Indication Contents
DO Display	RJE I
Temperature Display	Transmission output 1 Zero adjustment value

- (3) Set Transmission output 1 Zero adjustment value with the △ or ▽ key, while viewing the value indicated on the connected equipment (recorders, etc.). Setting range: ±5.00% of Transmission output 1 span
- (4) Press the key.

The unit enters Transmission output 1 Span adjustment mode, and indicates the following.

Display	Indication Contents	
DO Display	RJ5	
Temperature Display	Transmission output 1 Span adjustment value	

(5) Set Transmission output 1 Span adjustment value with the △ or ▽ key, while viewing the value indicated on the connected equipment (recorders, etc.).

Setting range: ±5.00% of Transmission output 1 span

Transmission output 1 adjustment is completed.

(6) Press the key.

The unit reverts to Display Mode or Cleansing Output Mode.

8.3 Transmission Output 2 Adjustment Mode

Fine adjustment of Transmission output 2 is performed.

The WIL-102-DO is adjusted at the factory, however, differences may occur between the indication value of the connected equipment (recorders, etc.) and output value of this instrument. In this case, perform Transmission output 2 Zero adjustment and Span adjustment.

The unit cannot enter Transmission output 2 Zero adjustment mode in the following cases.

- When $\neg \vdash \vdash \vdash \vdash \vdash$ (Cleansing output) is selected in any of [EVT1 to EVT6 types (pp. 26, 31)], and cleansing action is performing using the 'Cleansing time' and 'Standby after cleansing'
- During DO concentration calibration

The following outlines the procedure for Transmission output 2 adjustment.

- (1) Press and hold the \square and key (in that order) together for approx. 3 seconds in Display Mode or Cleansing Output Mode.
- (2) The unit enters Transmission output 2 Zero adjustment mode, and indicates the following.

Display	Indication Contents
DO Display	RJE2
Temperature Display	Transmission output 2 Zero adjustment value

- (3) Set Transmission output 2 Zero adjustment value with the △ or ▽ key, while viewing the value indicated on the connected equipment (recorders, etc.). Setting range: ±5.00% of Transmission output 2 span
- (4) Press the key.

The unit enters Transmission output 2 Span adjustment mode, and indicates the following.

Display	Indication Contents	
DO Display	Ruh2	
Temperature Display	Transmission output 2 Span adjustment value	

(5) Set Transmission output 2 Span adjustment value with the △ or ▽ key, while viewing the value indicated on the connected equipment (recorders, etc.).

Setting range: ±5.00% of Transmission output 2 span

Transmission output 2 adjustment is completed.

(6) Press the key.

The unit reverts to Display Mode or Cleansing Output Mode.

9. Measurement

9.1 Starting Measurement

For approx. 8 seconds after the power is switched ON, the following characters are indicated on the DO Display and Temperature Display.

Display	Indication Contents	
DO Display	doll	
Temperature Display	☐ ਫ਼ਿਊਊ [Version number (e.g.) 1.00]	

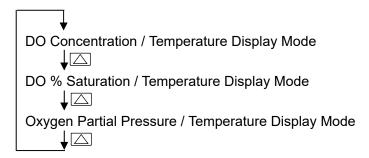
During this time, all outputs are in OFF status, and action indicators except the PWR indicator turn off.

After that, measurement starts, indicating DO concentration on the DO Display, and the measured temperature on the Temperature Display.

This status is called Display Mode or Cleansing Output Mode.

Switching Between Modes

Every time the \triangle key is pressed, modes on the DO Display progress as follows.



9.2 Outside Measurement Range

If DO concentration, DO % saturation, Oxygen partial pressure or temperature is outside the range, the following will be indicated.

	<u> </u>	
Input	DO Display	Temperature Display
DO concentration	Flashes at 20.00 or 0.00.	Measured value
DO % saturation	Flashes at 200.0 or 0.0.	Measured value
Oxygen partial pressure	Flashes at 150.0 or 0.0.	Measured value
Temperature	Measured value	Flashes at 50.0 or 0.0.

9.3 Error Code

When the following errors occur, the DO Display turns off, and the Temperature Display indicates corresponding error code.

Error Code	Description	Occurrence
Err0	Non-volatile IC memory error	Constantly
Err !	DO Sensor communication errors have occurred, or DO Sensor is	When
	not connected.	measuring and
	After a command is sent to the DO Sensor, if there is no response	calibrating
	for 500 ms, the command will be sent again.	
	If no response occurs 4 times consecutively, this error code will be	
	indicated. If communication status returns to normal, the error will	
	be released, and the unit will automatically return to normal status.	
	When this error code is indicated, the previous measured value	
	is retained.	
Err2	DO Sensor cap is not attached, or it is incorrectly attached.	
Err3	Calibration error (If input errors have occurred, or if calibration	When
	cannot be performed 30 minutes after starting calibration)	calibrating
Erry	DO Sensor internal memory deletion.	When
	Displayed when Quality ID3 is received from the DO Sensor.	measuring and
		calibrating

9.4 About Transmission Output 1 and 2

Converting DO concentration, water temperature, DO % saturation, or Oxygen partial pressure to analog signal every update cycle via communication, and outputs in current.

If Transmission output 1 high limit and low limit are set to the same value, Transmission output 1 will be fixed at 4 mA DC.

If Transmission output 2 high limit and low limit are set to the same value, Transmission output 2 will be fixed at 4 mA DC.

Resolution	12000
Current	4 to 20 mA DC (Load resistance: Max. 550 Ω)
Output accuracy	Within ±0.3% of Transmission output 1 or 2 span

For the following errors, Transmission output 1 or 2 will output 2 mA DC.

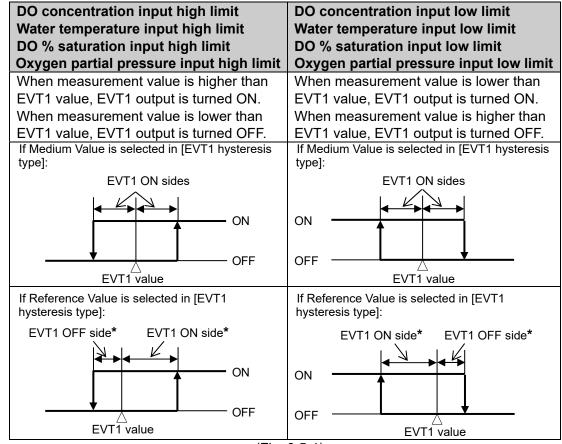
Error Code Description			
Err!	DO Sensor communication error, or DO Sensor is not connected.		
Err2	DO Sensor cap is not attached, or it is incorrectly attached.		
Err3	Calibration error (If input errors have occurred, or if calibration		
	cannot be performed 30 minutes after starting calibration)		

9.5 EVT1 to EVT6 Outputs

When any one of the following actions is selected in [EVT1 type (p.26)], it will perform as (Fig. 9.5-1). ゼロード (DO concentration input high limit action), ゼロード (DO concentration input low limit action), ボード (Water temperature input low limit action), ゼロード (DO % saturation input high limit action), ゼロード (DO % saturation input low limit action), ゼロード (Oxygen partial pressure input low limit action)

The same applies to EVT2, EVT3, EVT4, EVT5 and EVT6.

EVT1 Action (Activated based on the indication value)



(Fig. 9.5-1)

* Setting Example:

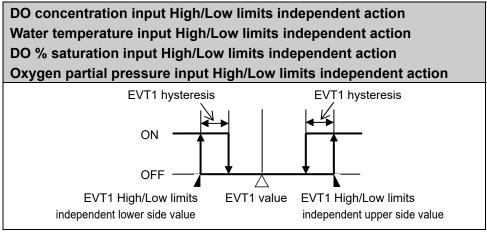
If [EVT1 ON side $(\not = \not = \not =)$] is set to 0, EVT1 output can be turned ON at the value set in [EVT1 value $(\not = \not = \not =)$].

If [EVT1 OFF side $(\not = F \cup f)$] is set to 0, EVT1 output can be turned OFF at the value set in [EVT1 value $(\vdash \mathcal{B} f)$].

When any one of the following actions is selected in [EVT1 type (p.26)], it will perform as (Fig. 9.5-2).

- ದರ್ಷ' (DO concentration input High/Low limits independent action),
- (Water temperature input High/Low limits independent action),
- ゴード (DO % saturation input High/Low limitsindependent action),
- ロード (Oxygen partial pressure input High/Low limits independent action)

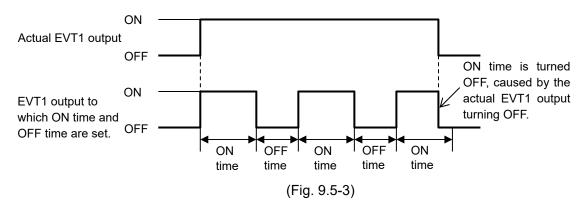
The same applies to EVT2, EVT3, EVT4, EVT5 and EVT6.



(Fig. 9.5-2)

When 'Output ON time and OFF time when EVT1 Output is ON' are set, the following action is performed.

• Timing chart (Output ON time and OFF time when EVT1 output is ON)



EVT output status can be read by reading Status flag 2 (EVT1 to EVT6 output flag bit) in Serial communication.

EVT output status, when input errors occur, differs depending on the selection in [EVT output when input errors occur (p.34)].

- If $\varphi F = \emptyset$ (Disabled) is selected: EVT output is turned OFF when input errors occur.
- If prill (Enabled) is selected: EVT output is maintained when input errors occur.

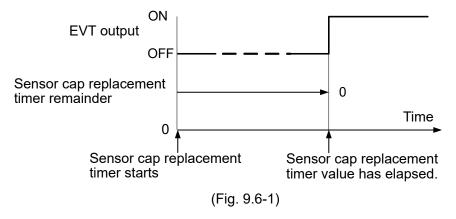
9.6 Sensor Cap Replacement Timer Output

When $\Gamma \subset \Pi^{\square}$ (Sensor cap replacement timer output) is selected in any of [EVT1 to EVT6 types (pp. 26, 31)], the unit operates as follows.

- (1) If Sensor cap replacement timer value has elapsed (when Sensor cap replacement timer remainder is "0"), the selected EVT output will be turned ON. (*1)
 - The DO Display indicates DO concentration measured value and $\Gamma \subseteq \Xi^{\square}$ alternately, informing the user to replace the sensor cap. (*2)
- (2) Replace the sensor cap.

After replacing the sensor cap, this unit automatically resets the Sensor cap replacement remainder to the Sensor cap replacement timer value.

Sensor Cap Replacement Timer Output



- (*1) Even if power to this instrument is turned OFF and ON, EVT output remains ON until the sensor cap is replaced.
- (*2) After Sensor cap replacement timer value has elapsed, and if Outside measurement range error has occurred simultaneously, FzBP and the Outside measurement range value will be displayed alternately.

9.7 Cleansing Output

If $\not\subset L \not\subset L$ (Cleansing output) is selected in any of [EVT1 to EVT6 types (pp. 26, 31)], the unit will enter Cleansing Output Mode.

After 'Cleansing inactive interval' has elapsed, the selected EVT output is turned ON during the 'Cleansing time'.

After 'Standby after cleansing' has passed, the above action is repeated.

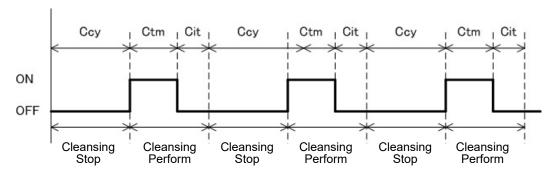
While cleansing is being performed using 'Cleansing time' and 'Standby after cleansing', other outputs are in OFF status.

Measured values (DO concentration, DO % saturation, Oxygen partial pressure, water temperature) are retained.

Normal programmed action will be performed, except during 'Cleansing Perform'.

When power is turned ON again, starts from 'Cleansing inactive interval'.

Cleansing Output Action



Ccy: Cleansing inactive interval

Ctm: Cleansing time

Cit: Standby after cleansing

• If $\neg \vdash \vdash \vdash \vdash \vdash$ (Cleansing output) is selected in any other [EVT type] during cleansing action, the current setting values (Cleansing time, Cleansing inactive interval, Standby after cleansing) will be used for the selected cleansing output.

If cleansing action (caused by cleansing cycle) is activated in calibration mode, cleansing action will not be performed in the current session.

• If $\varpi F F \square$ (None) is selected in [Cleansing inactive interval], or if any item except $\varpi L E \square$ (Cleansing output) is selected in [EVT1 to EVT6 types (pp. 26, 31)], Cleansing Output Mode will end, and the unit will revert to Display Mode.

If $\Box L E \Box$ (Cleansing output) is selected in any of [EVT1 to EVT6 types (pp. 26, 31)], and if $\Box F F \Box$ (None) is selected in [Cleansing inactive interval], only Forced cleansing mode will be enabled.

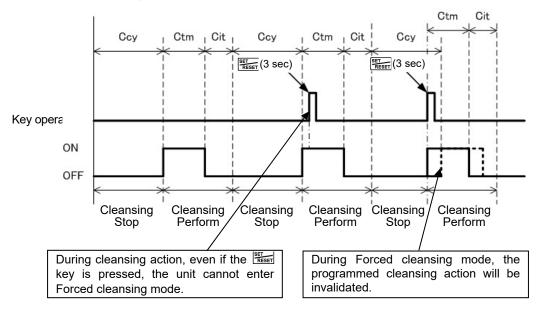
9.8 Forced Cleansing Mode

By pressing the key for approx. 3 seconds, the unit enters Forced cleansing mode. In Forced cleansing mode, cleansing is performed using 'Cleansing time' and 'Standby after cleansing'.

After cleansing action is finished, the unit automatically reverts to Cleansing Output Mode. This mode will not be accessible by the key if programmed cleansing is currently being performed.

During Forced cleansing mode, if programmed cleansing action initiates after 'Cleansing inactive interval' has passed, the programmed cleansing action will not be performed in the current session.

Forced Cleansing Mode Action



Ccy: Cleansing inactive interval

Ctm: Cleansing time

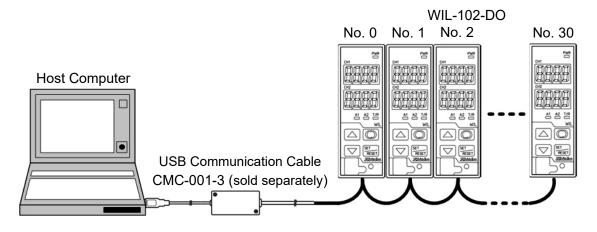
Cit: Standby after cleansing

(Fig. 9.8-1)

10. Communication

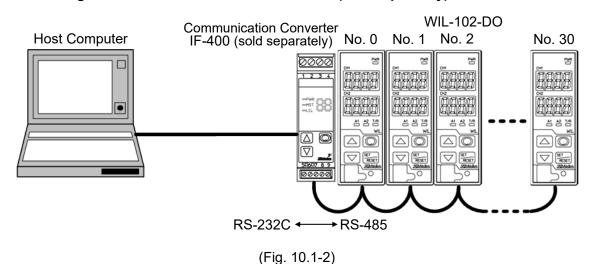
10.1 System Configuration Example

• When using the USB Communication Cable CMC-001-3 (sold separately)



(Fig. 10.1-1)

• When using the Communication Converter IF-400 (sold separately)



10.2 Setting Method of the Instrument

Communication parameters can be set in the Communication Group.

To enter the Communication Group, follow the procedure below.

- ① ເມເກັກ Press the ເພື key 6 times in Display Mode or Cleansing Output Mode.

 If EVT□ output (EVT option) is ordered, press the ເພື key 10 times in Display Mode or Cleansing Output Mode.
- 2 cā'n'. Press the key.

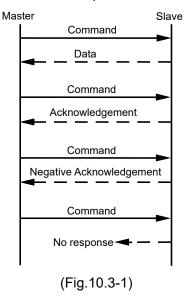
 The unit enters Communication Group, and 'Communication protocol' will appear.
- ③ Set each item. (Use the \triangle or ∇ key for settings, and register the value with the key.)

Character	Setting Item, Function, Setting Range	Factory Default
こうちに	Communication protocol	Shinko protocol
noñL	Selects communication protocol.	
	• กธกัL : Shinko protocol	
	កិច្ចជំងឺ : MODBUS ASCII mode	
	ก็อฮ่า : MODBUS RTU mode	
cīno	Instrument number	0
	Sets the instrument number.	
	The instrument numbers should be set one by	one when multiple instruments are
	connected in Serial communication, otherwise	communication is impossible.
	Setting range: 0 to 95	
c55P	Communication speed	9600 bps
1119 8	Selects a communication speed equal to that	of the host computer.
	• 🗆 35 : 9600 bps	
	☐ /월급 :19200 bps	
	□384 : 38400 bps	
cāF[Data bit/Parity	7 bits/Even
7 <i>E</i>	Selects data bit and parity.	
	• 💆 ת ב ת : 8 bits/No parity	
	ੋਰਕਰ : 7 bits/No parity	
	858n : 8 bits/Even	
	วิธียิก : 7 bits/Even	
	ಶ್ವರದ : 8 bits/Odd	
	ೌದರದ : 7 bits/Odd	
<u> </u>	Stop bit	1 bit
	Selects the stop bit.	
	•	

⁴ Press the key several times. The unit reverts to Display Mode or Cleansing Output Mode.

10.3 Communication Procedure

Communication starts with command transmission from the host computer (hereafter Master) and ends with the response of the WIL-102-DO (hereafter Slave).



Response with Data

When the master sends the reading command, the slave responds with the corresponding set value or current status.

Acknowledgement

When the master sends the setting command, the slave responds by sending acknowledgement after the processing is terminated.

Negative Acknowledgement

When the master sends a non-existent command or value out of the setting range, the slave returns a negative acknowledgement.

No Response

The slave will not respond to the master in the following cases:

- · Global address (Shinko protocol) is set.
- Broadcast address (MODBUS protocol) is set.
- Communication error (framing error, parity error)
- Checksum error (Shinko protocol), LRC discrepancy (MODBUS ASCII mode), CRC-16 discrepancy (MODBUS RTU mode)

Communication Timing of the RS-485

Master Side (Take note while programming)

When the master starts transmission through the RS-485 communication line, the master is arranged so as to provide an idle status (mark status) transmission period of 1 or more characters before sending the command to ensure synchronization on the receiving side.

Set the program so that the master can disconnect the transmitter from the communication line within a 1 character transmission period after sending the command in preparation for reception of the response from the slave.

To avoid collision of transmissions between the master and the slave, send the next command after carefully checking that the master has received the response.

If a response to the command is not returned due to communication errors, set the Retry Processing to send the command again. (It is recommended to execute Retry twice or more.)

Slave Side

When the slave starts transmission through the RS-485 communication line, the slave is arranged so as to provide an idle status (mark status) transmission period of 1 or more characters before sending the response to ensure synchronization on the receiving side.

The slave is arranged so as to disconnect the transmitter from the communication line within a 1 character transmission period after sending the response.

10.4 Shinko Protocol

10.4.1 Transmission Mode

Shinko protocol is composed of ASCII.

Hexadecimal (0 to 9, A to F), which is divided into high order (4-bit) and low order (4-bit) out of 8-bit binary data in command is transmitted as ASCII characters.

Data format Start bit: 1 bit

Data bit: 7 bits Parity: Even Stop bit: 1 bit

Error detection: Checksum

10.4.2 Command Configuration

All commands are composed of ASCII.

The data (set value, decimal number) is represented by hexadecimal numbers.

The negative numbers are represented in 2's complement.

Numerals written below the command represent the number of characters.

(1) Setting Command

٠,	County Co.							
	Header (02H)	Address	Sub address (20H)	Command type (50H)	Data item	Data	Checksum	Delimiter (03H)
	1	1	1	1	4	4	2	1

(2) Reading Command

Header (02H)	Address	Sub address (20H)	Command type (20H)	Data item	Checksum	Delimiter (03H)
1	1	1	1	4	2	1

(3) Response with Data

Header (06H)	Address	Sub address (20H)	Command type (20H)	Data item	Data	Checksum	Delimiter (03H)
1	1	1	1	4	4	2	1

(4) Acknowledgement

,		9			
	Header	Addross	Checksum	Delimiter	
	(06H)	Address	Checksum	(03H)	
	1	1	2	1	

(5) Negative Acknowledgement

,					
	Header (15H)	Address	Error code	Checksum	Delimiter (03H)
	1	1	1	2	1

Header: Control code to represent the beginning of the command or the response.

ASCII codes are used.

Setting command, Reading command: STX (02H) fixed. Response with data, Acknowledgement: ACK (06H) fixed. Negative acknowledgement: NAK (15H) fixed.

Instrument Number (Address): Numbers by which the master discerns each slave.

Instrument number 0 to 94 and Global address 95.

ASCII codes (20H to 7FH) are used by adding 20H to instrument numbers 0 to 95

(00H to 5FH).

95 (7FH) is called Global address, which is used when the same command is sent

to all the slaves connected. However, the response is not returned.

Sub Address: 20H fixed.

Command Type: Code to discern Setting command (50H) and Reading command (20H).

Data Item: Classification of the command object.

Composed of 4-digit hexadecimal numbers, using ASCII.

Refer to "10.6. Communication Command Table". (pp. 64 to 72)

Data: The contents of data (set value) differ depending on the setting command.

Composed of 4-digit hexadecimal numbers, using ASCII.

Refer to "10.6. Communication Command Table". (pp. 64 to 72)

Checksum: 2-character data to detect communication errors.

Refer to "10.4.3 Checksum Calculation".

Delimiter: Control code to represent the end of command.

ASCII code ETX (03H) fixed.

Error Code: Represents an error type using ASCII.

1 (31H)----Non-existent command

2 (32H)----Not used

3 (33H)-----Value outside the setting range

4 (34H)-----Status unable to be set (e.g. During calibration)

5 (35H)-----During setting mode by keypad operation

10.4.3 Checksum Calculation

Checksum is used to detect receiving errors in the command or data.

Set the program for the master side as well to calculate the checksum of the response data from the slaves so that communication errors can be checked.

The ASCII code (hexadecimal) corresponding to the characters which range from the address to that before the checksum is converted to binary notation, and the total value is calculated.

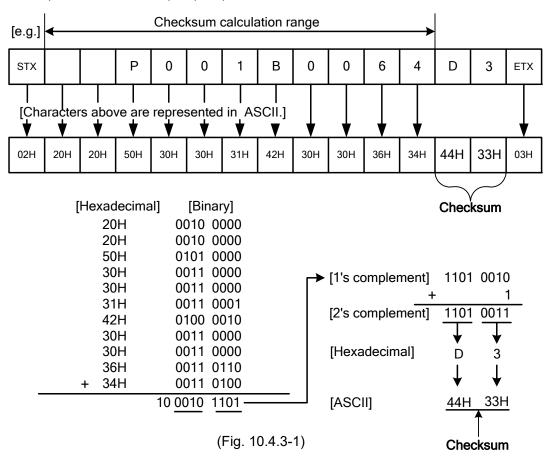
The lower one byte of the total value is converted to 2's complement, and then to hexadecimal numbers, that is, ASCII code for the checksum.

- 1's complement: Reverse each binary bit. 0 will become 1 and vice versa.
- 2's complement: Add 1 to 1's complement.

Checksum Calculation Example

Data item 001BH (EVT1 ON delay time): 100 seconds (0064H)

Address (instrument number): 0 (20H)



10.5 MODBUS Protocol

10.5.1 Transmission Mode

There are 2 transmission modes (ASCII and RTU) in MODBUS protocol.

ASCII Mode

Hexadecimal (0 to 9, A to F), which is divided into high order (4-bit) and low order (4-bit) out of 8-bit binary data in command is transmitted as ASCII characters.

Data format Start bit: 1 bit

Data bit: 7 bits (8 bits) (Selectable)

Parity: Even (No parity, Odd) (Selectable)

Stop bit: 1 bit (2 bits) (Selectable)

Error detection: LRC (Longitudinal Redundancy Check)

RTU Mode

8-bit binary data in command is transmitted as it is.

Data format Start bit: 1 bit

Data bit: 8 bits

Parity: No parity (Even, Odd) (Selectable)

Stop bit: 1 bit (2 bits) (Selectable)

Error detection: CRC-16 (Cyclic Redundancy Check)

10.5.2 Data Communication Interval

ASCII Mode

Max.1 second of interval between ASCII mode characters

RTU Mode

Communication speed 9600 bps, 19200 bps:

To transmit continuously, an interval between characters which consist of one message, must be within 1.5-character transmission times.

Communication speed 38400 bps:

To transmit continuously, an interval between characters which consist of one message, must be within 750 μ s.

If an interval lasts longer than 1.5-character transmission times or 750 $\,\mu$ s, the WIL-102-DO assumes that transmission from the master is finished, which results in a communication error, and will not return a response.

10.5.3 Message Configuration

ASCII Mode

ASCII mode message is configured to start by Header [: (colon) (3AH)] and end by Delimiter [CR (carriage return) (0DH) + LF (Line feed) (0AH)].

Header	Slave	Function	Dete	Error check	Delimiter	Delimiter
(:)	address	code	Data	LRC	(CR)	(LF)

RTU Mode

Communication speed 9600 bps, 19200 bps: RTU mode is configured to start after idle time is processed for more than 3.5-character transmissions, and end after idle time is processed for more than 3.5-character transmissions.

Communication speed 38400 bps: RTU mode is configured to start after idle time is processed for more than 1.75 ms, and end after idle time is processed for more than 1.75 ms.

3.5 idle	Slave	Function	Doto	Error check	3.5 idle
characters	address	code	Data	CRC-16	characters

(1) Slave Address

Slave address is an individual instrument number on the slave side, and is set within the range 0 to 95 (00H to 5FH). The master identifies slaves by the slave address of the requested message.

The slave informs the master which slave is responding to the master by placing its own address in the response message.

Slave address 00H (Broadcast address) can identify all the slaves connected. However, slaves do not respond.

(2) Function Code

The function code is the command code for the slave to undertake one of the following actions.

(Table 10.5.3-1)

Function Code	Contents
03 (03H)	Reading the set value and information from slaves
06 (06H)	Setting to slaves

The Function code is used to discern whether the response is normal (acknowledgement) or if any error (negative acknowledgement) has occurred when the slave returns the response message to the master.

When acknowledgement is returned, the slave simply returns the original function code.

When negative acknowledgement is returned, the MSB of the original function code is set as 1 for the response.

(For example, if the master sends request message setting 10H to the function code by mistake, slave returns 90H by setting the MSB to 1, because the former is an illegal function.)

For negative acknowledgement, the exception codes below are set to the data of the response message, and returned to the master in order to inform it of what kind of error has occurred. (Table 10.5.3-2)

(Table 10.5.3-2)

Exception Code	Contents		
1 (01H)	Illegal function (Non-existent function)		
2 (02H)	2 (02H) Illegal data address (Non-existent data address)		
3 (03H)	Illegal data value (Value out of the setting range)		
17 (11H)	Shinko protocol error code 4 [Status unable to be set. (e.g.) During calibration]		
18 (12H)	Shinko protocol error code 5 (During setting mode by keypad operation)		

(3) Data

Data differs depending on the function code.

A request message from the master is composed of a data item, amount of data and setting data. A response message from the slave is composed of the byte count, data and exception codes in negative acknowledgements.

The effective range of data is -32768 to 32767 (8000H to 7FFFH).

(4) Error Check

ASCII Mode

After calculating LRC (Longitudinal Redundancy Check) from the slave address to the end of data, the calculated 8-bit data is converted to two ASCII characters, and are appended to the end of message.

How to calculate LRC

- ① Create a message in RTU mode.
- ② Add all the values from the slave address to the end of data. This is assumed as X.
- Make a complement for X (bit reverse). This is assumed as X.
- 4 Add a value of 1 to X. This is assumed as X.
- ⑤ Set X as an LRC to the end of the message.
- 6 Convert the whole message to ASCII characters.

RTU Mode

After calculating CRC-16 (Cyclic Redundancy Check) from the slave address to the end of the data, the calculated 16-bit data is appended to the end of message in sequence from low order to high order.

How to calculate CRC-16

In the CRC-16 system, the information is divided by the polynomial series. The remainder is added to the end of the information and transmitted. The generation of a polynomial series is as follows. (Generation of polynomial series: $X^{16} + X^{15} + X^2 + 1$)

- 1 Initialize the CRC-16 data (assumed as X) (FFFFH).
- ② Calculate exclusive OR (XOR) with the 1st data and X. This is assumed as X.
- Shift X one bit to the right. This is assumed as X.
- 4 When a carry is generated as a result of the shift, XOR is calculated by X of 3 and the fixed value (A001H). This is assumed as X. If a carry is not generated, go to step 5.
- 5 Repeat steps 3 and 4 until shifting 8 times.
- 6 XOR is calculated with the next data and X. This is assumed as X.
- 7 Repeat steps 3 to 5.
- 8 Repeat steps 3 to 5 up to the final data.
- 9 Set X as CRC-16 to the end of message in sequence from low order to high order.

10.5.4 Message Example

ASCII Mode

Numerals written below the command represent the number of characters.

① Reading [Slave address 1, Data item 0080H (DO concentration)]

A request message from the master

Amount of data means how many data items are to be read. It is fixed as (30H 30H 30H 31H).

Header	Slave	Function	Data item	Amount of data	Error check	Delimiter
	address	code	[0080H]	[0001H]	LRC	
(3AH)	(30H 31H)	(30H 33H)	(30H 30H 38H 30H)	(30H 30H 30H 31H)	(37H 42H)	(0DH 0AH)
1	2	2	4	4	2	2

Response message from the slave in normal status [When DO concentration is 1.00 mg/L (0064H)]
 The response byte count means the byte count of data which have been read. It is fixed as (30H 32H).

Header (3AH)	address	Function code (30H 33H)	Response byte count [02H] (30H 32H)	Data [0064H] (30H 30H 36H 34H)	Error check LRC (39H 36H)	Delimiter (0DH 0AH)
1	2	2	2	4	2	2

• Response message from the slave in exception (error) status (When a data item is incorrect) The function code MSB is set to 1 for the response message in exception (error) status (83H is returned). The exception code 02H (Non-existent data address) is returned (error).

	,				
Header	Slave	Function	Exception code	Error check	Delimiter
	address	code	[02H]	LRC	
(3AH)	(30H 31H)	(38H 33H)	(30H 32H)	(37H 41H)	(0DH 0AH)
1	2	2	2	2	2

② Setting [Slave address 1, Data item 001BH (EVT1 ON delay time)

• A request message from the master [When EVT1 ON delay time is set to 100 seconds (0064H)]

Header	Slave	Function	Data item	Data	Error check	Delimiter
	address	code	[001BH]	[0064H]	LRC	
(3AH)	(30H 31H)	(30H 36H)	(30H 30H 31H 42H)	(30H 30H 36H 34H)	(44H 45H)	(0DH 0AH)
1	2	2	4	4	2	2

Response message from the slave in normal status

Header	Slave	Function	Data item	Data	Error check	Delimiter
	address	code	[001BH]	[0064H]	LRC	
(3AH)	(30H 31H)	(30H 36H)	(30H 30H 31H 42H)	(30H 30H 36H 34H)	(44H 45H)	(0DH 0AH)
1	2	2	4	4	2	2

• Response message from the slave in exception (error) status (When a value out of the setting range is set.)

The function code MSB is set to 1 for the response message in exception (error) status (86H is returned). The exception code 03H (Value out of the setting range) is returned (error).

	Header	Slave	Function	Exception code	Error check	Delimiter
		address	code	[03H]	LRC	
	(3AH)	(30H 31H)	(38H 36H)	(30H 33H)	(37H 36H)	(0DH 0AH)
_	1	2	2	2	2	2

RTU Mode

Numerals written below the command represent number of characters.

① Reading [Slave address 1, Data item 0080H (DO concentration)]

• A request message from the master

Amount of data means how many data items are to be read. It is fixed as (0001H).

3.5 idle	Slave	Function	Data item	Amount of data	Error check	3.5 idle
	address	code			CRC-16	
:characters	(01H)	(03H)	(H0800)	(0001H)	(85E2H)	characters
	1	1	2	2	2	

• Response message from the slave in normal status [When DO concentration is 1.00 mg/L (0064H)] The response byte count means the byte count of data which has been read. It is fixed as (02H).

	(02.1).							
3.5 idle	Slave	Function	Response	Data	Error check	2 E idlo		
i .	address	code	byte count		CRC-16	3.5 idle		
characters	(01H)	(03H)	(02H)	(0064H)	(B9AFH)	characters		
	1	1	1	2	2			

• Response message from the slave in exception (error) status (When a data item is incorrect)
The function code MSB is set to 1 for the response message in exception (error) status (83H is returned).

The exception code (02H: Non-existent data address) is returned (error).

THE EXCEPT	The exception code (ozn. Non-existent data address) is returned (error).							
3.5 idle	Slave address	Function code	Exception code	Error check CRC-16	3.5 idle			
Cilaracters	(01H)	(83H)	(02H)	(C0F1H)	Cilaracters			
	1	1	1	2				

2 Setting (Slave address 1, Data item 001BH (EVT1 ON delay time)

• A request message from the master [When EVT1 ON delay time is set to 100 seconds (0064H)]

Trioquost mossage nom the master [Trinen EVTT ort dota) time to set to Tee essente (eve 117)]							
3.5 idle	Slave	Function	Data item	Data	Error check	3.5 idle	
characters	address	code			CRC-16	characters	
Characters	(01H)	(06H)	(001BH)	(0064H)	(F826H)	Cilaracters	
	1	1	2	2	2		

Response message from the slave in normal status

3.5 idle	Slave	Function	Data item	Data	Error check	3.5 idle
	address	code			CRC-16	1.
characters	(01H)	(06H)	(001BH)	(0064H)	(F826H)	characters
	1	1	2	2	2	

• Response message from the slave in exception (error) status (When a value out of the setting range is set)

The function code MSB is set to 1 for the response message in exception (error) status (86H is returned.).

The exception code (03H: Value out of the setting range) is returned (error).

3.5 idle	Slave address	code	Exception code	CRC-16	3.5 idle
i	(01H)	(86H)	(03H)	(0261H)	onaraotoro:
	1	1	1	2	

10.6 Communication Command Table

10.6.1 Notes about Setting/Reading Command

- The data (set value, decimal) is converted to hexadecimal numbers. Negative numbers are represented in 2's complement.
- When connecting multiple slaves, the address (instrument number) must not be duplicated.
- Data items 0200H to 0209H (User save area 1 to 10) can be read or set in 1 word units. Effective range of data is -32768 to 32767 (8000H to 7FFFH).
- MODBUS protocol uses Holding Register addresses. The Holding Register addresses are created as follows. A Shinko command data item is converted to decimal number, and the offset of 40001 is added. The result is the Holding Register address.
 - Using Data item 0001H (Signal output response time) as an example: Data item in the sending message is 0001H, however, MODBUS protocol Holding Register address is 40002 (1 + 40001).
- Even if EVT output (EVT option) is not ordered, setting or reading via software communication will be possible. However, EVT3 to EVT6 command contents will not function.

(1) Setting Command

- Up to 1,000,000 (one million) entries can be stored in non-volatile IC memory.
 If the number of settings exceeds the limit, the data will not be saved. So, do not change the set values frequently via software communication. (If a value set via software communication is the same as the value before the setting, the value will not be written in non-volatile IC memory.)
- Be sure to select Lock 3 when changing the set value frequently via software communication. If Lock 3 is selected, all set values can be temporarily changed. However, they revert to their previous value after the power is turned off because they are not saved in the non-volatile IC memory.
 Do not change setting items (EVT1, EVT2, EVT3, EVT4, EVT5, EVT6 types). If they are changed, they will affect other setting items.
- Setting range of each item is the same as that of keypad operation.
- When the data (set value) has a decimal point, a whole number (hexadecimal) without a decimal point is used.
- If EVT type is changed in [EVT1 type] to [EVT6 type], EVT1 to EVT6 value will default to 0 (zero). The output status of EVT1 to EVT6 will also be initialized.
- Settings via software communication are possible while in Set value lock status.
- Communication parameters such as Instrument Number, Communication Speed of the slave cannot be set by software communication. They can only be set via the keypad. (p.56)
- When sending a command by Global address [95 (7FH), Shinko protocol] or Broadcast address [(00H), MODBUS protocol], the same command is sent to all the slaves connected. However, the response is not returned.

(2) Reading Command

• When the data (set value) has a decimal point, a whole number (hexadecimal) without a decimal point is used for a response.

10.6.2 Sett	10.6.2 Setting/Reading Command							
	MODBUS		5					
Command Type	Code		Data Item	Data				
50H/20H		0001H	Signal output response	Set value (1 to 120)				
001.,,2011	001 11 001 1		time	'1' corresponds to 5 seconds, and				
				'120' corresponds to 600 seconds.				
50H/20H	06H/03H	0003H	Salinity correction	Set value				
50H/20H	06H/03H	0004H	Altitude correction	Set value				
50H	06H	0005H	DO concentration	0000H: Display Mode				
			calibration mode	0001H: DO concentration 1-point calibration				
			; ! !	mode				
				0002H: DO concentration 2-point calibration				
				mode 0003H: Concentration option calibration mode				
50H	06H	0006H	DO concentration	DO concentration 1-point calibration:				
3011	0011	000011	calibration start	0000H: DO concentration 1-point calibration				
			:	mode				
				0001H: 1-point calibration (100% saturation				
				calibration) start				
				0003H: Measured value fixed				
			· ·	DO concentration 2 naint calibration.				
				DO concentration 2-point calibration: 0000H: DO concentration 2-point calibration				
			:	mode				
				0001H: 1 st -point calibration (100% saturation				
				calibration) start				
				0002H: 2 nd -point calibration (0-point calibration)				
				start 0003H: Measured value fixed				
				Concentration option calibration: 0000H: Concentration option calibration mode				
				0001H: Concentration option calibration start				
				0003H: Measured value fixed				
50H/20H	06H/03H	0007H	Concentration desired	Set value (Decimal point ignored.)				
			value	, , ,				
50H/20H	06H/03H	0008H	Transmission output 1 type	0000H: DO concentration transmission				
				0001H: Water temperature transmission				
				0002H: DO % saturation transmission				
50H/20H	U8H/U3H	0000H	Transmission output 1 high	0003H: Oxygen partial pressure transmission Set value (Decimal point ignored.)				
30H/20H	001/0311	ОООЭП	limit	Set value (Declinal point ignored.)				
50H/20H	06H/03H	000AH	Transmission output 1 low	Set value (Decimal point ignored.)				
001.1,2011			limit	, , ,				
50H/20H	06H/03H	000BH	Transmission output 2 type	0000H: DO concentration transmission				
				0001H: Water temperature transmission				
			1 1 1	0002H: DO % saturation transmission				
5011/0011	0011/0011	000011	Tours and a discount of the last	0003H: Oxygen partial pressure transmission				
50H/20H	06H/03H		Transmission output 2 high	Set value (Decimal point ignored.)				
50H/20H	U8H/U3H		limit Transmission output 2 low	Set value (Decimal point ignored.)				
300/200	001/0311	חסטטח	limit	Set value (Declinal point ignored.)				
50H	06H	000EH	Transmission output 1	0000H: Display Mode				
]		adjustment mode	0001H: Transmission output 1 Zero				
			i	adjustment mode				
				0002H: Transmission output 1 Span				
E011/25::	0011/65::	000=::	-	adjustment mode				
50H/20H	06H/03H	000FH	Transmission output 1	Set value (Decimal point ignored.)				
E011/2011	0611/0011	004011	Zero adjustment value	Cat value (Dagings) = sint is never 1)				
50H/20H	U0H/U3H		Transmission output 1 Span adjustment value	Set value (Decimal point ignored.)				
		J	Opan aujustilient value					

Shinko	MODBUS	Data Itam		Dete
Command Type	Code	Data Item		Data
50H	06H		Transmission output 2 adjustment mode	0000H: Display Mode 0001H: Transmission output 2 Zero adjustment mode 0002H: Transmission output 2 Span adjustment mode
50H/20H	06H/03H		Transmission output 2 Zero adjustment value	Set value (Decimal point ignored.)
50H/20H	06H/03H	0013H	Transmission output 2 Span adjustment value	Set value (Decimal point ignored.)
50H/20H	06H/03H		EVT1 type	0000H: No action 0001H: DO concentration input high limit action 0002H: DO concentration input low limit action 0003H: Water temperature input high limit action 0004H: Water temperature input low limit action 0005H: DO % saturation input high limit action 0006H: DO % saturation input low limit action 0007H: Oxygen partial pressure input high limit action 0008H: Oxygen partial pressure input low limit action 0009H: Sensor cap replacement timer 000AH: Self-check output 000BH: Cleansing output 000CH: DO concentration input High/Low limits independent action 000DH: Water temperature input High/Low limits independent action 000EH: DO % saturation input High/Low limits independent action 000FH: Oxygen partial pressure input High/Low limits independent action
50H/20H	06H/03H	0015H	EVT1 value	Set value (Decimal point ignored.)
50H/20H			EVT1 hysteresis type	0000H: Medium Value 0001H: Reference Value
50H/20H	06H/03H	0019H	EVT1 ON side	Set value (Decimal point ignored.)
50H/20H	06H/03H	001AH	EVT1 OFF side	Set value (Decimal point ignored.)
50H/20H	06H/03H	001BH	EVT1 ON delay time	Set value
50H/20H	06H/03H	001CH	EVT1 OFF delay time	Set value
50H/20H		0020H	Output ON Time when EVT1 Output ON	Set value
50H/20H			Output OFF Time when EVT1 Output ON	Set value
50H/20H	06H/03H	10022H	EVT2 type	0000H: No action 0001H: DO concentration input high limit action 0002H: DO concentration input low limit action 0003H: Water temperature input high limit action 0004H: Water temperature input low limit action 0005H: DO % saturation input high limit action 0006H: DO % saturation input low limit action 0007H: Oxygen partial pressure input high limit action 0008H: Oxygen partial pressure input low limit action 0009H: Sensor cap replacement timer 000AH: Self-check output 000BH: Cleansing output 000CH: DO concentration input High/Low limits independent action 000DH: Water temperature input High/Low limits independent action 000FH: DO % saturation input High/Low limits independent action

Command	MODBUS Function	Data Item	Data
Type	Code	002011/57/72 volve	Cativalia (Dasimal mainting and)
50H/20H		0023H EVT2 value	Set value (Decimal point ignored.)
50H/20H	000/030	0026H EVT2 hysteresis type	0000H: Medium Value
50H/20H	06H/03H	0027H EVT2 ON side	0001H: Reference Value
50H/20H		0028H EVT2 OFF side	Set value (Decimal point ignored.) Set value (Decimal point ignored.)
50H/20H		0029H EVT2 ON delay time	Set value (Decimal point ignored.)
50H/20H		002AH EVT2 OFF delay time	Set value
50H/20H	000/030	002EH Output ON Time when	Set value
50H/20H	06H/03H	EVT2 Output ON 002FH Output OFF Time when	Set value
300/200	000/030	EVT2 Output ON	Set value
50H/20H	UEH/U3H	0030H EVT3 type	0000H: No action
300/200	000/030	UUSUH EV 13 type	
			0001H: DO concentration input high limit action
		: : :	0002H: DO concentration input low limit action
		† •	0003H: Water temperature input high limit action
		; ; ;	0004H: Water temperature input low limit action
			0005H: DO % saturation input high limit action
		· · ·	0006H: DO % saturation input low limit action
		:	0007H: Oxygen partial pressure input high limit action
		, ;	0008H: Oxygen partial pressure input low limit action
		; ;	0009H: Sensor cap replacement timer
		,	000AH: Self-check output
		•	000BH: Cleansing output
		; ; ;	000CH: DO concentration input High/Low limits
			independent action
		: : :	000DH: Water temperature input High/Low limits
		; ;	independent action
		:	000EH: DO % saturation input High/Low limits
		, , ;	independent action
			000FH: Oxygen partial pressure input High/Low
			limits independent action
50H/20H	06H/03H	0031H EVT3 value	Set value (Decimal point ignored.)
50H/20H	06H/03H	0034H EVT3 hysteresis type	0000H: Medium Value
			0001H: Reference Value
50H/20H	06H/03H	0035H EVT3 ON side	Set value (Decimal point ignored.)
50H/20H	06H/03H	0036H EVT3 OFF side	Set value (Decimal point ignored.)
50H/20H	06H/03H	0037H EVT3 ON delay time	Set value
50H/20H	06H/03H	0038H EVT3 OFF delay time	Set value
50H/20H	06H/03H	003CH Output ON Time when	Set value
		EVT3 Output ON	
50H/20H	06H/03H	003DH Output OFF Time when	Set value
		EVT3 Output ON	

Shinko Command Type	MODBUS Function Code	Data Item		Data
50H/20H		003EH	EVT4 type	0000H: No action
			71° =	0001H: DO concentration input high limit action
				0002H: DO concentration input low limit action
			: : :	0003H: Water temperature input high limit action
			· ·	0004H: Water temperature input low limit action
			: :	0005H: DO % saturation input high limit action
			• •	0006H: DO % saturation input low limit action
			· ·	0007H: Oxygen partial pressure input high limit action
			· ·	0008H: Oxygen partial pressure input low limit action
			•	0009H: Sensor cap replacement timer
			· · ·	000AH: Self-check output
			! !	000BH: Cleansing output
			• • •	000CH: DO concentration input High/Low limits
			· · ·	independent action
			· · · · ·	000DH: Water temperature input High/Low limits
				independent action
			· · ·	000EH: DO % saturation input High/Low limits
			•	independent action
			: : :	000FH: Oxygen partial pressure input High/Low
				limits independent action
50H/20H	06H/03H	003FH	EVT4 value	Set value (Decimal point ignored.)
50H/20H	06H/03H	0042H	EVT4 hysteresis type	0000H: Medium Value
				0001H: Reference Value
50H/20H	06H/03H	0043H	EVT4 ON side	Set value (Decimal point ignored.)
50H/20H	06H/03H	0044H	EVT4 OFF side	Set value (Decimal point ignored.)
50H/20H	06H/03H	0045H	EVT4 ON delay time	Set value
50H/20H	06H/03H	0046H	EVT4 OFF delay time	Set value
50H/20H	06H/03H	004AH	Output ON Time when	Set value
			EVT4 Output ON	
50H/20H	06H/03H		Output OFF Time when EVT4 Output ON	Set value
50H/20H	06H/03H	004CH	EVT5 type	0000H: No action
			· · ·	0001H: DO concentration input high limit action
				0002H: DO concentration input low limit action
			· · ·	0003H: Water temperature input high limit action
			· · ·	0004H: Water temperature input low limit action
			•	0005H: DO % saturation input high limit action
				0006H: DO % saturation input low limit action
			· · ·	0007H: Oxygen partial pressure input high limit action
			· ·	0008H: Oxygen partial pressure input low limit action
				0009H: Sensor cap replacement timer
			· · ·	000AH: Self-check output
				000BH: Cleansing output
			•	000CH: DO concentration input High/Low limits
			· · ·	independent action
			• • •	000DH: Water temperature input High/Low limits
				independent action
				000EH: DO % saturation input High/Low limits
			•	independent action
			•	000FH: Oxygen partial pressure input High/Low
				limits independent action

Shinko Command Type	MODBUS Function Code	Data Item		Data
50H/20H	06H/03H	004DH	EVT5 value	Set value (Decimal point ignored.)
50H/20H	06H/03H	0050H	EVT5 hysteresis type	0000H: Medium Value
			 	0001H: Reference Value
50H/20H	06H/03H	0051H	EVT5 ON side	Set value (Decimal point ignored.)
50H/20H	06H/03H	0052H	EVT5 OFF side	Set value (Decimal point ignored.)
50H/20H	06H/03H	0053H	EVT5 ON delay time	Set value
50H/20H	06H/03H	0054H	EVT5 OFF delay time	Set value
50H/20H	06H/03H	0058H	Output ON Time when EVT5 Output ON	Set value
50H/20H	06H/03H		Output OFF Time when EVT5 Output ON	Set value
50H/20H	06H/03H	005AH	EVT6 type	0000H: No action 0001H: DO concentration input high limit action 0002H: DO concentration input low limit action 0003H: Water temperature input high limit action 0004H: Water temperature input low limit action 0005H: DO % saturation input high limit action 0006H: DO % saturation input low limit action 0007H: Oxygen partial pressure input high limit action 0008H: Oxygen partial pressure input low limit action 0009H: Sensor cap replacement timer 000AH: Self-check output 000BH: Cleansing output 000CH: DO concentration input High/Low limits independent action 000DH: Water temperature input High/Low limits independent action 000EH: DO % saturation input High/Low limits independent action 000FH: Oxygen partial pressure input High/Low limits independent action
50H/20H	06H/03H	005BH	EVT6 value	Set value (Decimal point ignored.)
50H/20H	06H/03H	005EH	EVT6 hysteresis type	0000H: Medium Value
				0001H: Reference Value
50H/20H	06H/03H	005FH	EVT6 ON side	Set value (Decimal point ignored.)
50H/20H	06H/03H	0060H	EVT6 OFF side	Set value (Decimal point ignored.)
50H/20H	06H/03H	0061H	EVT6 ON delay time	Set value
50H/20H	06H/03H	0062H	EVT6 OFF delay time	Set value
50H/20H	06H/03H		Output ON Time when EVT6 Output ON	Set value
50H/20H	06H/03H	0067H	Output OFF Time when EVT6 Output ON	Set value
50H/20H	06H/03H	0068H	Cleansing time	Set value
50H/20H			Cleansing inactive interval	Set value
50H	06H		Forced cleansing mode	0001H: Forced cleansing mode
50H/20H			Set value lock	0000H: Unlock 0001H: Lock 1 0002H: Lock 2 0003H: Lock 3
50H/20H	06H/03H	006CH	Auto-light function	0000H: Disabled 0001H: Enabled
50H/20H	06H/03H	006DH	Indication time	Set value
50H/20H			EVT output when input errors occur	0000H: Enabled 0001H: Disabled

Shinko Command Type	MODBUS Function Code			Data
50H/20H		0075H	Data clear selection	0000H: Calibration value 0001H: Set value
50H	06H		Data clear Stop/Perform	0000H: Data clear Stop 0001H: Data clear Perform
50H/20H	06H/03H	0077H	Standby after cleansing	Set value
50H	06H	007FH	clearing	0001H: Clear change flag
50H/20H			EVT1 High/Low limits independent lower side value	Set value (Decimal point ignored.)
50H/20H	06H/03H		independent lower side value	Set value (Decimal point ignored.)
50H/20H	06H/03H	0102H	EVT3 High/Low limits independent lower side value	Set value (Decimal point ignored.)
50H/20H	06H/03H	0103H	EVT4 High/Low limits independent lower side value	Set value (Decimal point ignored.)
50H/20H	06H/03H	0104H	EVT5 High/Low limits independent lower side value	Set value (Decimal point ignored.)
50H/20H	06H/03H	0105H	EVT6 High/Low limits independent lower side value	Set value (Decimal point ignored.)
50H/20H	06H/03H	0106H	EVT1 High/Low limits independent upper side value	Set value (Decimal point ignored.)
50H/20H	06H/03H	0107H	EVT2 High/Low limits independent upper side value	Set value (Decimal point ignored.)
50H/20H	06H/03H	0108H	EVT3 High/Low limits independent upper side value	Set value (Decimal point ignored.)
50H/20H	06H/03H		independent upper side value	Set value (Decimal point ignored.)
50H/20H			EVT5 High/Low limits independent upper side value	Set value (Decimal point ignored.)
50H/20H	06H/03H	010BH	EVT6 High/Low limits independent upper side value	Set value (Decimal point ignored.)
50H/20H	06H/03H	010CH	EVT1 hysteresis	Set value (Decimal point ignored.)
50H/20H	06H/03H	010DH	EVT2 hysteresis	Set value (Decimal point ignored.)
50H/20H	06H/03H	010EH	EVT3 hysteresis	Set value (Decimal point ignored.)
50H/20H	06H/03H	010FH	EVT4 hysteresis	Set value (Decimal point ignored.)
50H/20H	06H/03H	0110H	EVT5 hysteresis	Set value (Decimal point ignored.)
50H/20H			EVT6 hysteresis	Set value (Decimal point ignored.)
50H/20H	06H/03H			0000H: Last value HOLD
001,,,_011			when calibrating	0001H: Set value HOLD 0002H: Measured value
50H/20H			Transmission output 1 value HOLD when calibrating	Set value (Decimal point ignored.)
50H/20H	06H/03H	0114H	Transmission output 2 status when calibrating	0000H: Last value HOLD 0001H: Set value HOLD 0002H: Measured value
50H/20H	06H/03H	0115H	Transmission output 2 value HOLD when calibrating	Set value (Decimal point ignored.)
50H/20H	06H/03H	0200H	User save area 1	-32768 to 32767 (8000H to 7FFFH)
50H/20H	06H/03H	0201H	User save area 2	-32768 to 32767 (8000H to 7FFFH)
50H/20H	06H/03H	0202H	User save area 3	-32768 to 32767 (8000H to 7FFFH)
50H/20H	06H/03H	0203H	User save area 4	-32768 to 32767 (8000H to 7FFFH)
50H/20H	06H/03H	0204H	User save area 5	-32768 to 32767 (8000H to 7FFFH)
50H/20H	06H/03H	,		-32768 to 32767 (8000H to 7FFFH)
50H/20H	06H/03H			-32768 to 32767 (8000H to 7FFFH)
50H/20H	06H/03H	· · · · · · · · · · · · · · · · · · ·		-32768 to 32767 (8000H to 7FFFH)
50H/20H			User save area 9	-32768 to 32767 (8000H to 7FFFH)
50H/20H	06H/03H	0209H	User save area 10	-32768 to 32767 (8000H to 7FFFH)

10.6.3 Read Only Command

10.6.3 Rea				
Shinko Command Type	MODBUS Function Code		ta Item	Data
20H	03H	0080H DO conc	entration	DO concentration (Decimal point ignored.)
20H	03H	0081H DO % sa	turation	DO % saturation (Decimal point ignored.)
20H	03H	0082H Oxygen i	partial pressure	Oxygen partial pressure (Decimal point ignored.)
20H	03H	0083H Status fla	ag 1	
		0000 0	000 0000 000	
		2 ¹⁵	to 2	0
		2º digit: (Dutside measurer	nent range of DO concentration (high limit)
		:		0: Normal 1: Error
		2 ¹ digit: (Dutside measurer	nent range of DO concentration (low limit)
				0: Normal 1: Error
		2 ² digit: (Outside measurer	nent range of DO % saturation (high limit)
		-0		0: Normal 1: Error
		2 ³ digit: 0	Outside measurer	nent range of DO % saturation (low limit)
		64	~	0: Normal 1: Error
		2 ⁴ digit: (Outside measurer	nent range of Oxygen partial pressure (high limit)
		05 11 11	2	0: Normal 1: Error
		2° algit: (Jutside measurer	nent range of Oxygen partial pressure (low limit)
		Of digit. (Campunication or	0: Normal 1: Error
		Z° digit. (Johnnunication er	ors have occurred or DO Sensor is not connected. 0: Normal 1: Error
		2 ⁷ digit: [OO Sensor can is	not attached, or it is incorrectly attached.
		Z digit. I	oo oensor cap is	0: Normal 1: Error
		28 digit. (Calibration error	
		, ,	Jnit status flag	0: Display Mode 1: Setting mode
		:	_	
			ligits: Calibration	
		211	210	Status
		0	0 Display Mo	
		0		tration 1-point calibration mode
		1	<u> </u>	tration 2-point calibration mode
		1	1 Concentra	ion option calibration mode
			igits: Calibration	status flag
		2 ¹³	2 ¹²	Status
		0	0 Standby	
		0	1 During 1 st -բ	oint calibration (100% saturation calibration)
		1	0 During 2 nd -	point calibration (0-point calibration)
		1	1 During cor	centration option calibration
			DO Sensor interr Change in key or	al memory deletion 0: No 1: Yes eration 0: No 1: Yes
		ı ;z uigit.	Change in Key Op	Gradion V. NO 1. 163

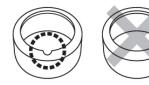
Shinko Command Type	MODBUS Function Code	Data Item	Data
20H	03H	0090H Temperature	Temperature (Decimal point ignored.)
20H	03H	0091H Sensor cap replace	ment timer Sensor cap replacement timer
		remainder	remaining time
20H	03H	0093H Status flag 2	
		0000 0000 0000	
		2 ¹⁵ to	2^0
		2º digit: Outside me	asurement range of temperature (high limit)
		21 11 11 2 4 1 1	0: Normal 1: Error
		2' digit: Outside me	asurement range of temperature (low limit)
		Ω ² digit, Γ\/T1 quito	0: Normal 1: Error it 0: OFF 1: ON
		2² digit: EVT1 outpu 2³ digit: EVT2 outpu	
		2 ⁴ digit: EVT3 outpu	
		2 ⁵ digit: EVT4 outpu	
		2 ⁶ digit: EVT5 outpu	
		2 ⁷ digit: EVT6 outpu	
		:	
			nission output 1 adjustment status flag
		29 28	Status
		: -	hisplay Mode
			uring Transmission output 1 Zero adjustment
			Transmission output 1 adjustment mode
		•	uring Transmission output 1 Span adjustment Transmission output 1 adjustment mode
		: -	<u> </u>
			mission output 2 adjustment status flag
		211 210	Status
			Display Mode
			During Transmission output 2 Zero adjustment
			n Transmission output 2 adjustment mode
			During Transmission output 2 Span adjustment
			n Transmission output 2 adjustment mode
		2 ¹² , 2 ¹³ digits: Clear	sing status flag
		2 ¹³ 2 ¹²	Status
		0 0	Display Mode
		0 1 [Ouring cleansing inactive interval
		1 0 [Ouring cleansing time
		1 1 [Ouring standby after cleansing
		2 ¹⁴ , 2 ¹⁵ digits: Not u	sed (Always 0)

10.7 DO Concentration Calibration by Communication Command

There are 3 calibration methods (like a key operation) for DO concentration calibration via communication: DO concentration 1-point calibration mode, DO concentration 2-point calibration mode, Concentration option calibration mode

10.7.1 Preparation

- (1) Clean the DO Sensor body and measurement section, and remove all moisture.
- (2) Remove the storage cap of the calibration container, and replace with a calibration cap (ventilating cap).



Calibration cap Storage cap (Fig. 10.7.1-1)

- (3) Keep the water, used for DO Sensor and calibration, at room temperature for approx. 30 minutes.
- (4) Select a mode from Sections 10.7.2 (DO Concentration 1-point Calibration Mode), 10.7.3 (DO Concentration 2-point Calibration Mode) and 10.7.4 (Concentration Option Calibration Mode), and perform calibration.

10.7.2 DO Concentration 1-point Calibration Mode



Caution

• If salinity concentration has been previously corrected, return the salinity concentration correction value to 0 PSU, then start calibration.

[Data item 0003H (Salinity correction)]

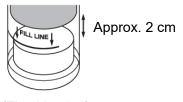
If calibration is performed with previsously corrected salinity concentration, an error will occur, or calibration will not be performed normally.

• When using a sensor in geographically high elevation sites, perform altitude correction for accurate calibration, then start calibration.

[Data item 0004H (Altitude correction)]

The following outlines calibration procedure.

- (1) Pour approx. 10 mL of ion-exchanged water into the calibration container sponge.
- (2) Insert the DO Sensor into the calibration container until the measurement section of the sensor is situated approximately 2 cm away from the sponge.



(Fig. 10.7.2-1)

(3) Allow it to settle, undisturbed, for 5 to 10 minutes.



Caution

• Do not leave the sensor attached to the calibration container for more than 30 minutes. This will result in dew condensation in measurement section, which will affect measurement value. If dew condensation has occured, remove the moisture from the measurement section, then start calibration again.

- (4) Set Data item 0005H (DO concentration calibration mode) to 0001H. The unit moves to DO concentration 1-point calibration mode. If 2¹¹, 2¹⁰ digits are read at Data item 0083H (Status flag 1), 01 (DO concentration 1-point calibration mode) will be returned.
- (5) Set Data item 0006H (DO concentration calibration start) to 0001H.
 1-point calibration (100% saturation calibration) starts.
 If 2¹³, 2¹² digits are read at Data item 0083H (Status flag 1), 01 [During 1st-point calibration (100% saturation calibration)] will be returned.
- (6) Set Data item 0006H (DO concentration calibration start) to 0003H.
 The measured value will be fixed, and automatic calibration will be performed.
 If 2¹³, 2¹² digits are read at Data item 0083H (Status flag 1), 00 (Standby) will be returned.
 1-point calibration (100% saturation calibration) is completed.
- (7) Set Data item 0006H (DO concentration calibration start) to 0000H. The unit reverts to DO concentration 1-point calibration mode.
- (8) Set Data item 0005H (DO concentration calibration mode) to 0000H. The unit reverts to Display Mode or Cleansing Output Mode.

If calibration cannot be performed during 1-point calibration (100% saturation calibration) due to unstable DO concentration input or temperature correction error, etc., and if 2⁸ digit is read at Data item 0083H (Status flag 1), 1 (Error) will be returned.

To release the error, set Data item 0005H (DO concentration calibration mode) to 0000H. The unit reverts to Display Mode or Cleansing Output Mode.

10.7.3 DO Concentration 2-point Calibration Mode



Caution

• When using a sensor in geographically high elevation sites, perform altitude correction for accurate calibration, then start calibration.

[Data item 0004H (Altitude correction)]

The following outlines calibration procedure.

- (1) Pour approx. 10 mL of ion-exchanged water into the calibration container sponge.
- (2) Insert the DO Sensor into the calibration container until the measurement section of the sensor is situated approximately 2 cm away from the sponge.



Approx. 2 cm

(Fig. 10.7.3-1)

(3) Allow it to settle, undisturbed, for 5 to 10 minutes.



Caution

- Do not leave the sensor attached to the calibration container for more than 30 minutes. This will result in dew condensation in measurement section, which will affect measurement value. If dew condensation has occured, remove the moisture from the measurement section, then start calibration again.
- (4) Set Data item 0005H (DO concentration calibration mode) to 0002H.

The unit moves to DO concentration 2-point calibration mode.

If 2¹¹, 2¹⁰ digits are read at Data item 0083H (Status flag 1), 10 (DO concentration 2-point calibration mode) will be returned.

- (5) Set Data item 0006H (DO concentration calibration start) to 0001H.
 - 1st-point calibration (100% saturation calibration) starts.
 - If 2¹³, 2¹² digits are read at Data item 0083H (Status flag 1), 01 [During 1st-point calibration (100% saturation calibration)] will be returned.
- (6) Set Data item 0006H (DO concentration calibration start) to 0003H.

The measured value will be fixed, and automatic calibration will be performed.

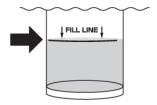
If 2¹³, 2¹² digits are read at Data item 0083H (Status flag 1), 00 (Standby) will be returned.

1st-point calibration (100% saturation calibration) is completed.

(7) Prepare a zero standard solution.

Zero standard solution is 100 mL of ion-exchanged water into which 5 g or more of sodium sulfite has been added and completely dissolved.

(8) Take out the calibration container sponge used for 1st-point calibration, and pour the zero standard solution into the calibration container up to the Fill Line.



(Fig. 10.7.3-2)

(9) Insert the temperature sensor of the DO Sensor until it is immersed in the prepared zero standard solution.



Caution

- Insert the measurement section so that approximately 1 cm of gap is left between it and the bottom of the calibration container.
- Insert the measurement section so that air bubbles cannot attach to it.
- (10) Allow it to settle, undisturbed, for at least 5 minutes to stabilize the temperature.
- (11) Set Data item 0006H (DO concentration calibration start) to 0002H.
 2nd-point calibration (0-point calibration) starts.
 If 2¹³, 2¹² digits are read at Data item 0083H (Status flag 1), 10 [During 2nd-point calibration (0-point calibration)] will be returned.
- (12) Set Data item 0006H (DO concentration calibration start) to 0003H.

The measured value will be fixed, and automatic calibration will be performed.

If 2¹³, 2¹² digits are read at Data item 0083H (Status flag 1), 00 (Standby) will be returned.

2nd-point calibration (0-point calibration) is completed.

2-point calibration (both 100% saturation calibration and 0-point calibration) is completed.

(13) Set Data item 0006H (DO concentration calibration start) to 0000H.

The unit reverts to DO concentration 2-point calibration mode.

(14) Set Data item 0005H (DO concentration calibration mode) to 0000H.

The unit reverts to Display Mode or Cleansing Output Mode.

If calibration cannot be performed during DO concentration 2-point calibration due to unstable DO concentration input or temperature correction error, etc., and if 2⁸ digit is read at Data item 0083H (Status flag 1), 1 (Error) will be returned.

To release the error, set Data item 0005H (DO concentration calibration mode) to 0000H.

The unit reverts to Display Mode or Cleansing Output Mode.

10.7.4 Concentration Option Calibration Mode

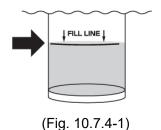
Immerse the DO Sensor in an aqueous solution (of which DO concentration is known), then the measured value can be matched to the concentration.

Factory default value: 0.00 mg/L

DO concentration can be set within a range of 0.00 to 20.00 mg/L.

The following outlines calibration procedure.

- (e.g.) Setting to a (already-known) concentration of 7.77 mg/L
- (1) Pour the already-known concentration solution into the calibration container up to the Fill Line.



(2) Insert the temperature sensor of the DO Sensor until it is immersed in the poured solution.



Caution

- Insert the measurement section so that approximately 1 cm of gap is left between it and the bottom of the calibration container.
- Insert the measurement section so that air bubbles cannot attach to it.
- (3) Allow it to settle, undisturbed, for at least 5 minutes to stabilize the temperature.
- (4) Set Data item 0005H (DO concentration calibration mode) to 0003H. The unit moves to Concentration option calibration mode. If 2¹¹, 2¹⁰ digits are read at Data item 0083H (Status flag 1), 11 (Concentration option calibration mode) will be returned.
- (5) Set Data item 0007H (Concentration desired value) to the desired value (7.77).
- (6) Set Data item 0006H (DO concentration calibration start) to 0001H. Concentration option calibration starts. If 2¹³, 2¹² digits are read at Data item 0083H (Status flag 1), 11 (During concentration option calibration) will be returned.
- (7) Set Data item 0006H (DO concentration calibration start) to 0003H.
 The measured value will be fixed, and calibration will be performed.
 If 2¹³, 2¹² digits are read at Data item 0083H (Status flag 1), 00 (Standby) will be returned.
 Concentration option calibration is completed.
- (8) Set Data item 0006H (DO concentration calibration start) to 0000H. The unit reverts to Concentration option calibration mode.
- (9) Set Data item 0005H (DO concentration calibration mode) to 0000H. The unit reverts to Display Mode or Cleansing Output Mode.

If errors occur during concentration option calibration, and if 2⁸ digit is read at Data item 0083H (Status flag 1), 1 (Error) will be returned.

To release the error, set Data item 0005H (DO concentration calibration mode) to 0000H.

The unit reverts to Display Mode or Cleansing Output Mode.

10.8 Transmission Output 1 and 2 Adjustment

10.8.1 Transmission Output 1 Adjustment Mode

Fine adjustment of Transmission output 1 is performed.

WIL-102-DO is adjusted at the factory, however, differences may occur between the indication value of the connected equipment (recorders, etc.) and the output value of this unit. In this case, perform Transmission output 1 Zero adjustment and Span adjustment.

The following outlines the procedure for Transmission output 1 adjustment.

- (1) Set Data item 000EH (Transmission output 1 adjustment mode) to 0001H. The unit moves to Transmission output 1 Zero adjustment mode. If 29, 28 digits are read at Data item 0093H (Status flag 2), 01 (During Transmission output 1 Zero adjustment in Transmission output 1 adjustment mode) will be returned.
- (2) Set Transmission output 1 Zero adjustment value at Data item 000FH (Transmission output 1 Zero adjustment value), while viewing the value indicated on the connected equipment (recorders, etc.). Setting range: ±5.00% of Transmission output 1 span
- (3) Set Data item 000EH (Transmission output 1 adjustment mode) to 0002H.

 The unit moves to Transmission output 1 Span adjustment mode.

 If 2⁹, 2⁸ digits are read at Data item 0093H (Status flag 2), 10 (During Transmission output 1 Span adjustment in Transmission output 1 adjustment mode) will be returned.
- (4) Set Transmission output 1 Span adjustment value at Data item 0010H (Transmission output 1 Span adjustment value), while viewing the value indicated on the connected equipment (recorders, etc.). Setting range: ±5.00% of Transmission output 1 span
- (5) Repeat steps (1) to (4) if necessary.
- (6) Set Data item 000EH (Transmission output 1 adjustment mode) to 0000H. The unit reverts to Display Mode or Cleansing Output Mode.

10.8.2 Transmission Output 2 Adjustment Mode

Fine adjustment of Transmission output 2 is performed.

WIL-102-DO is adjusted at the factory, however, differences may occur between the indication value of the connected equipment (recorders, etc.) and the output value of this unit. In this case, perform Transmission output 2 Zero adjustment and Span adjustment.

The following outlines the procedure for Transmission output 2 adjustment.

- (1) Set Data item 0011H (Transmission output 2 adjustment mode) to 0001H. The unit moves to Transmission output 2 Zero adjustment mode. If 2¹¹, 2¹⁰ digits are read at Data item 0093H (Status flag 2), 01 (During Transmission output 2 Zero adjustment in Transmission output 2 adjustment mode) will be returned.
- (2) Set Transmission output 2 Zero adjustment value at Data item 0012H (Transmission output 2 Zero adjustment value), while viewing the value indicated on the connected equipment (recorders, etc.). Setting range: ±5.00% of Transmission output 2 span
- (3) Set Data item 0011H (Transmission output 2 adjustment mode) to 0002H.

 The unit moves to Transmission output 2 Span adjustment mode.

 If 2¹¹, 2¹⁰ digits are read at Data item 0093H (Status flag 2), 10 (During Transmission output 2 Span adjustment in Transmission output 2 adjustment mode) will be returned.
- (4) Set Transmission output 2 Span adjustment value at Data item 0013H (Transmission output 2 Span adjustment value), while viewing the value indicated on the connected equipment (recorders, etc.). Setting range: ±5.00% of Transmission output 2 span
- (5) Repeat steps (1) to (4) if necessary.
- (6) Set Data item 0011H (Transmission output 2 adjustment mode) to 0000H. The unit reverts to Display Mode or Cleansing Output Mode.

10.9 Notes on Programming Monitoring Software

10.9.1 How to Speed up the Scan Time

When monitoring multiple units of WIL-102-DO, set the program so that the requisite minimum pieces of data such as Data item 0080H (DO concentration), Data item 0090H (Temperature), Data item 0083H (Status flag 1), Data item 0093H (Status flag 2) can be read. For other data, set the program so that they can be read only when their set value has been changed. This will speed up the scan time.

10.9.2 How to Read the Set Value Changes Made by the Front Keypad Operation

If any set value is changed by keypad operation, the WIL-102-DO will set [0083H (Status flag 1) 2¹⁵: Change in key operation] to 1 (Yes).

There are 2 methods of reading the set value changes made by the front keypad.

(1) Reading method 1

- ① On the monitoring software side, check that [0083H (Status flag 1) 2¹⁵: Change in key operation] has been set to 1 (Yes), then read all set values.
- © Clear the [0083H (Status flag 1) 2¹⁵: Change in key operation], by setting Data item 007FH (Key operation change flag clearing) to 0001H (Clear change flag).
 If [007FH (Key operation change flag clearing)] is set to [Clear change flag (0001H)] during setting mode of this instrument, Error code 5 (35H, Shinko protocol) or Exception Code 18 (12H, MODBUS protocol) will be returned as a negative acknowledgement. And [0083H (Status flag 1) 2¹⁵: Change in key operation] cannot be cleared.
 - Set a program so that all set values can be read when a negative acknowledgement is returned.
- ③ Read all set values again after acknowledgement is returned.

(2) Reading method 2

- ① On the monitoring software side, check that [0083H (Status flag 1) 2¹⁵: Change in key operation] has been set to 1 (Yes), then set 007FH (Key operation change flag clearing) to 0001H (Clear change flag).
- ② Set the program depending on acknowledgement or negative acknowledgement as follows. When acknowledgement is returned:

Consider it as settings completed, and read all set values.

When Error code 5 (35H, Shinko protocol) or Exception code 18 (12H, MODBUS protocol) is returned as a negative acknowledgement:

Consider it as still in setting mode, and read the requisite minimum pieces of data such as 0080H (DO concentration), 0090H (Temperature), 0083H (Status flag 1), 0093H (Status flag 2), then return to step 1.

Thus, programs which do not affect the scan time can be created using the methods described above, even if set values on the monitoring software will not be updated until settings are complete.

10.9.3 Note when sending all set values at one time

• If EVT1, EVT2, EVT3, EVT4, EVT5 or EVT6 type is changed at Data items 0014H (EVT1 type), 0022H (EVT2 type), 0030H (EVT3 type), 003EH (EVT4 type), 004CH (EVT5 type) or 005AH (EVT6 type), the EVT1, EVT2, EVT3, EVT4, EVT5 or EVT6 value will default to 0 (zero). Output status of EVT1, EVT2, EVT3, EVT4, EVT5 or EVT6 will also be initialized.

First, send the EVT1, EVT2, EVT3, EVT4, EVT5 or EVT6 type, then send the EVT1, EVT2, EVT3, EVT4, EVT5 or EVT6 value set at Data items 0015H (EVT1 value), 0023H (EVT2 value), 0031H (EVT3 value), 003FH (EVT4 value), 004DH (EVT5 value) or 005BH (EVT6 value).

11. Specifications

11.1 Specification of WIL-102-DO

11.1.1 Standard Specifications

Rating

Rated scale	Input	Input Range Resolu		solution				
	DO concentration	•		0.00 to 20.00 mg/L			0.01 mg/L	
	DO % saturation			0.1%				
	Oxygen partial press	Oxygen partial pressure 0.0 to 150.0 kPa			0.1 kPa		⊃a	
	Temperature			0.0 to 50.0°C		0.1℃		
Input	Optical DO Sensor							
Power supply	Model		WIL-102-	DO	W	WIL-102-DO 1		
	Power supply	100 to 240 V AC 50/60		50/60 Hz	24 V A	C/DC	50/60 Hz	
	Allowable voltage fluctuation range	85 to 264 V AC		20 to 28 V AC/DC				

General Structure

External dimensions	30 x 88 x 108 mm (W x	30 x 88 x 108 mm (W x H x D, including socket)		
Mounting	DIN rail	DIN rail		
Case	Material: Flame-resist	tant resin, Color: Light gray		
Front panel	Membrane sheet			
Indicating structure	Display			
	DO Display	Red LED 4-digits		
		Character size: 10 x 4.6 mm (H x W)		
	Temperature Display Red LED 4-digits			
	Character size: 10 x 4.6 mm (H x W)			
	Action indicators			
	PWR (Yellow)	Instrument Power ON: Lit		
	A1 (Red)	EVT1 output (Contact output 1) ON: Lit		
	A2 (Yellow) EVT2 output (Contact output 2) ON: Lit			
	T/R (Yellow) Serial communication TX output (transmitting): Lit			
Setting structure	Setting method: Input system using membrane sheet key			

Indication Performance

Indication accuracy	Depends on the accuracy of the Optical DO Sensor.
Time accuracy	Within ±1% of setting time
Data update cycle	5 seconds

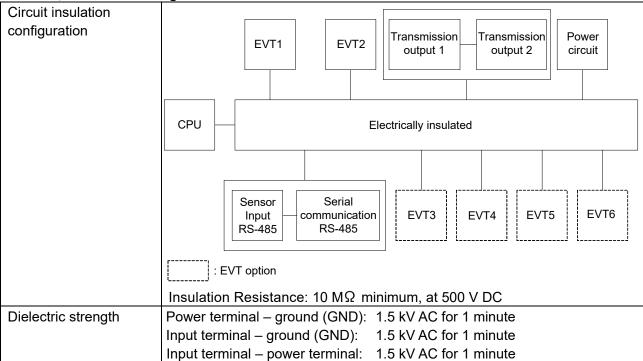
Standard Function

tar	idard Function					
С	alibration	DO concentration 1-point calibration, DO concentration 2-point calibration,				
		Concentration option calibration				
S	ignal output response	Moving average is	calculated from the set signal output response time, and			
tir	me	the resulting value	e is updated every Data update cycle (5 seconds) as a			
		measurement value. However, signal output response time will be				
		invalidated during DO concentration calibration mode, Transmission output 1				
		or 2 adjustment mode.				
Т	ransmission output 1		of – DO concentration, water temperature, DO %			
	ľ	saturation, or Oxyg	tion, or Oxygen partial pressure – to an analog signal every update			
		cycle, and outputs	in current.			
		If Transmission out	tput 1 high limit and low limit are set to the same value,			
		Transmission outpo	ut 1 will be fixed at 4 mA DC.			
		Resolution	12000			
		Current	4 to 20 mA DC (Load resistance: Max. 550 Ω)			
		Output accuracy	Within ±0.3% of Transmission output 1 span			
	Transmission output		the Transmission output 1 is performed via			
	1 adjustment	_	ut 1 Zero and Span adjustments.			
	Transmission	Selects Transmissi	on output 1 output status when calibrating DO			
	output 1 status	concentration.				
	when calibrating	Last value HOLD	Retains the last value before DO concentration			
			calibration, and outputs it.			
		Set value HOLD	Outputs the value set in [Transmission output 1 value HOLD when calibrating].			
		Measured value	Outputs the measured value when calibrating DO concentration.			
Т	ransmission output 2		Converts any one of – DO concentration, water temperature, DO %			
			en partial pressure – to an analog signal every update			
		cycle, and outputs				
			tput 2 high limit and low limit are set to the same value,			
		Transmission outp	ut 2 will be fixed at 4 mA DC.			
		Resolution	12000			
		Current	4 to 20 mA DC (Load resistance: Max. 550 Ω)			
		Output accuracy	Within ±0.3% of Transmission output 2 span			
	Transmission output	Fine adjustment of	the Transmission output 2 is performed via			
	2 adjustment	Transmission output 2 Zero and Span adjustments.				
	Transmission output Selects Transmission output 2 output status when calibrating DO					
	2 status when calibrating	concentration.				
Calibrating		Last value HOLD	Retains the last value before DO concentration calibration, and outputs it.			
		Set value HOLD	Outputs the value set in [Transmission output 2 value HOLD when calibrating].			
		Measured value	Outputs the measured value when calibrating DO concentration.			

EVT□ output				
(Contact output)				
Action	ON/OFF control action			
EVT□ ON side	DO concentration input: 0.00 to 4.00 mg/L			
EVT□ OFF side	Water temperature input: 0.0 to 10.0℃			
	DO % saturation input: 0.0 to 40.0%			
	Oxygen partial pressure input: 0.0 to 30.0 kPa			
EVT□ High/Low	DO concentration input: 0.00 to 20.00 mg/L			
limits independent	Water temperature input: 0.0 to 50.0℃			
upper side value,	DO % saturation input: 0.0 to 200.0%			
EVT□ High/Low	Oxygen partial pressure input: 0.0 to 150.0 kPa			
limits independent	, , , , , , , , , , , , , , , , , , , ,			
lower side value				
EVT□ hysteresis	DO concentration input: 0.01 to 2.00 mg/L			
,	Water temperature input: 1.0 to 5.0℃			
	DO % saturation input: 0.1 to 20.0%			
	Oxygen partial pressure input: 0.1 to 15.0 kPa			
Туре	Selectable by keypad operation			
	No action			
	DO concentration input high limit action			
	DO concentration input low limit action			
	Water temperature input high limit action			
	Water temperature input low limit action			
	• DO % saturation input high limit action			
	DO % saturation input low limit action Overgon partial procesure input high limit action			
	Oxygen partial pressure input high limit actionOxygen partial pressure input low limit action			
	Sensor cap replacement timer			
	Self-check output			
	Cleansing output			
	DO concentration input High/Low limits independent action			
	Water temperature input High/Low limits independent action			
	DO % saturation input High/Low limits independent action			
	Oxygen partial pressure input High/Low limits independent action			
Output	Relay contact 1a			
	Control 3 A 250 V AC (resistive load)			
	capacity 1 A 250 V AC (inductive load cos ϕ =0.4)			
	Electrical life 100,000 cycles			
EVT□ ON delay	0 to 9999 seconds			
time				
EVT□ OFF delay	0 to 9999 seconds			
time	KONE LOFFE CONTRACTOR			
Output ON Time/ OFF Time when	If ON time and OFF time are set, the output can be turned ON/OFF in a			
	configured cycle when EVT output is ON.			
EVT Output ON	The selected EVT output is turned ON offer sensor can replacement times			
Sensor cap replacement timer	The selected EVT output is turned ON after sensor cap replacement timer value has elapsed (Sensor cap replacement timer remainder is "0").			
output	DO concentration measured value and \(\sigma \beta \beta \beta \beta \beta \cdot \beta \end{area} \) are alternately indicated			
Jacpac	· · · · · · · · · · · · · · · · · · ·			
	on the DO Display.			

	0 15 1 1 1	T	/T 1 1 1 1	10016 (1 6 11 1	
	Self-check output			urned ON for the following	
		_		mmunication errors have	occurred, or DO
			ensor is not		in correctly attached
				p is not attached, or it is	
				or (If input errors have oc not be performed 30 mir	
			alibration)	not be periorned 30 mil	iules aller starting
				ernal memory deletion.	
				en Quality ID3 is received	d from the DO Sensor.
	Cleansing output	Cleansing Outp		•	
				erval' has elapsed, the	selected EVT output is
				'Cleansing time'.	
		While cleansing	g is being p	g' has passed, the above erformed_using 'Cleansi	
				ts are in OFF status.	
		pressure, water		concentration, DO % sat) are retained.	turation, Oxygen partial
		Normal prograr Perform'.	mmed action	will be performed, ex-	cept during 'Cleansing
		When power is		gain, starts from 'Cleansi	ng inactive interval'.
		Forced Cleans		2	9 (- 1
				approx. 3 seconds, the leansing mode, cleansing	
				y after cleansing'.	g is periorified using
				hed, the unit automatica	llv reverts to Cleansing
		Output Mode.			
				sible by the 🚟 key if pr	ogrammed cleansing
		is currently bein			
				de, if programmed clean	
				val' has passed, the proo n the current session.	grammed cleansing
9	erial communication			be carried out from an e	external computer
0				arious set values	ontomar compater.
				entration, DO % saturation	n, Oxygen partial
		•	mperature ar		
		(3) Function cha			
	0.11.1	(4) Reading and			natora ara nat
	Cable length			nce: Within 50 Ω (Termi 20 Ω minimum on both	
	Communication line	EIA RS-485	i useu, use i	20 St Hillilling OH DOUL	sides.)
	Communication method		um unication		
		Half-duplex com			
	Communication speed			lectable by keypad)	
	Synchronization method	Start-stop synch	IIOIIIZALION		
	Communication	ASCII, Binary	MODDIIO	COIL MODDUO DTU (C	ala atalala lecelese (1)
	Communication protocol	Sninko protocol	, MODBUS A	SCII, MODBUS RTU (Se	electable by keypad)
	Data bit/Parity	8 bits/No parity	7 bits/No par	rity, 8 bits/Even, 7 bits/Ev	/en. 8 bits/Odd.
	_ sta sivi anty	7 bits/Odd (Sele	•	•	,,
	Stop bit	1 bit, 2 bits (Sel	ectable by ke	eypad)	
	Error correction	Command requ			
	Error detection		•	inko protocol), LRC (MO	DBUS protocol ASCII),
		CRC-16 (MODE		,	
	Data format	Communication	Shinko	MODBUS	MODBUS
		Protocol	Protocol	ASCII	RTU
		Start bit	1	7 (2) 2 1 1 1	1
		Data bit	7	7 (8) Selectable	No parity (Evan Odd)
		Parity	Even	Even (No parity, Odd) Selectable	No parity (Even, Odd) Selectable
		Stop bit	1	1 (2) Selectable	1 (2) Selectable
		· · ·		(-) - 510010010	(-, -:::::::::::::::::::::::::::::::::::

Insulation, Dielectric Strength



Attached Function

Attached Function							
Set value lock	Lock 1: None of the set values can be changed.						
		Lock 2: Only EVT1 to EVT6 values can be changed.					
		Lock 3: All set values can be temporarily changed.					
	However, they revert to their previous value after the power is turned						
					volatile IC memory.		
Outside measurement					/gen partial pressure,		
range		Temperature) are outside the measurement range, the following will be					
	indicated.						
	Input		DO Displa	y	Temperature Display		
	DO concentration	Flashes	at 20.00 or	0.00.	Measured value		
	DO % saturation	Flashes	at 200.0 or	0.0.	Measured value		
	Oxygen partial pressure	Flashes	at 150.0 or	0.0.	Measured value		
	Temperature	Measure			Flashes at 50.0 or 0.0.		
Power failure countermeasure	The setting data is	backed u	o in the nor	n-volatile l	C memory.		
Self-diagnosis	The CPU is monit occurs, the WIL-10				nd if an abnormal status status.		
Warm-up Indication	For approx. 8 seco	nds after	the power	is switche	d ON, characters below		
	are indicated on th	e DO Dis	olay and Te	mperature	Display.		
	Display			C	ontents		
	DO Display		do				
	Temperature Displa	ay	/J ### [V	ersion nur	mber (e.g.) 1.00]		
Display sleep function	-		e duration	of the prev	viously set indication time,		
	the displays will go off.						
	By pressing any key, the display re-lights. If the Indication time is set to						
	00.00, the displays remain lit, and this function is disabled.						
Auto-light function	Automatically measures and controls brightness of the DO Display,						
	Temperature Displa	Temperature Display and action indicators.					

Error indication	Error Code	Description	Occur- rence
	ErrO	Non-volatile IC memory error	Constantly
	Err I	DO Sensor communication errors have occurred, or DO Sensor is not connected. After a command is sent to the DO Sensor, if there is no response for 500 ms, the command will be sent again. If no response occurs 4 times consecutively, this error code will be indicated. If communication status returns to normal, the unit will automatically return to normal status. When this error code is displayed, the previous measured value is retained. DO Sensor cap is not attached, or it is incorrectly	When measuring and calibrating
		attached.	
	Err3	Calibration error (when input errors have occurred, or when calibration cannot be performed 30 minutes after starting calibration)	When calibrating
	Erry	DO Sensor internal memory deletion. Displayed when Quality ID3 is received from the DO Sensor.	When measuring and calibrating

Other

Power consumption	Approx. 10 VA
Ambient temperature	0 to 50°C
Ambient humidity	35 to 85 %RH (Non-condensing)
Weight	Approx. 200 g (including socket)
Environmental spec	RoHS directive
Accessories included	Unit label: 1 sheet
	Instruction manual: 1 copy
	Wire harness WJ (3 m): 4 lengths (when the EVT option is ordered)
Accessories sold	Socket ASK-001-1 (Finger-safe, terminal screw fall prevention)
separately	

11.1.2 Optional Specifications

EVT□ Output (Option Code: EVT)

EV	T□ output	Same as standard EVT□ except the 'output'.		
	Output	Open collector		
		Control capacity	0.1 A 24 V DC	

11.2 DO Sensor Specifications

Model	DOS-20	
Power supply	12 to 36 V DC	
Sensor cap	One (1) year after installing the DO Sensor (F	Recommended)
replacement frequency		
Sensor cap storage	Two (2) years from the date of manufacture (\	When storing in the
period	designated container)	
	Storage temperature: 1 to 60°C	
Measuring water	0 to 50 [°] C (Not freezing)	
temperature		
Material	ABS	
External dimensions	Approx. <i>Φ</i> 44 x 203 mm	
Weight	Approx. 850 g (including 10 m cable)	
Degree of protection	IP68 (Underwater type, maximum depth of 20	00 m)
Accessories sold	DO Sensor attachment: DA-1	
separately	Sensor cap for replacement: DOS-CP	
	Stanchion pole: PS-1	
	Fixing bracket for stanchion pole: PS-TK	

12. Troubleshooting

Error codes and solutions to problems are described below.

12.1 Error Codes

Error Code	Description	Occur- rence
Err0	Non-volatile IC memory error	Constantly
Err I	DO Sensor communication errors have occurred, or DO Sensor is not connected. After a command is sent to the DO Sensor, if there is no response for 500 ms, the command will be sent again. If no response occurs 4 times consecutively, this error code will be indicated. If communication status returns to normal, the unit will automatically return to normal status. When this error code is displayed, the previous measured value is retained. DO Sensor cap is not attached, or it is incorrectly attached.	When measuring and calibrating
Err3	Calibration error (when input errors have occurred, or when calibration cannot be performed 30 minutes after starting calibration)	When calibrating
Erry	DO Sensor internal memory deletion. Displayed when Quality ID3 is received from the DO Sensor.	When measuring and calibrating

12.2 Solutions to Problems

If any malfunction occurs, refer to the following items after checking that power is being supplied to the WIL-102-DO.

12.2.1 Indication

Problem	Possible Cause	Solution
The DO Display/	The time set in [Indication time (p.34)]	If any key is pressed while displays
Temperature Display	has passed.	are unlit, it will re-light.
are unlit.		Set the Indication time to a suitable
		time-frame.
The DO Display/	□□ (Enabled) is selected in	Select [Disabled).
Temperature Display	[Auto-light function (p.34)].	
are dark.		
Indication of the DO	DO concentration calibration may not	Perform DO concentration
Display/Temperature	have finished.	calibration.
Display is unstable or	Specification of DO Sensor may not	Replace the sensor with a suitable
irregular.	be suitable.	one.
	There may be equipment that	Keep WIL-102-DO clear of any
	interferes with or makes noise near	potentially disruptive equipment.
	the WIL-102-DO.	
<i>Err ∤</i> is flashing	DO Sensor communication errors	Turn the power OFF, and check the
on the Temperature	have occurred, or the DO Sensor is	wiring of the DO Sensor.
Display.	not connected.	If the DO Sensor is malfunctioning,
		repair or replace the sensor.
をこっさ is flashing	This occurs when DO Sensor cap is	For correct attachment, refer to
on the Temperature	not attached, or when it is incorrectly	Section "4.4 Attaching the Sensor
Display.	attached.	Cap" (p.13).

Problem	Possible Cause	Solution
Err∃ is flashing on the Temperature Display.	Calibration error	Remove dirt or air bubbles from the measurement section, and calibrate again. If errors occur again, repair or replace the DO Sensor. If salinity concentration correction has been performed, return the salinity concentration correction value to 0 PSU, and calibrate again.
Err : is flashing on the Temperature Display.	Internal memory is defective.	Contact our agency or us.

12.2.2 Key Operation

Problem	Possible Cause	Solution
Unable to set values. The values do not change by △, ▽ keys.	Lロロ / (Lock 1) is selected in [Set value lock (p. 34)].	Select (Unlock).
Settings are impossible except EVT□ value. The values do not change by □, □ keys	L ロロゼ (Lock 2) is selected in [Set value lock (p. 34)].	Select [(Unlock).
Unable to enter Forced cleansing mode.	c L E Ω (Cleansing output) is not selected in any of [EVT1 to EVT6 types (pp. 26, 31)].	Select
	Cleansing action is performing using the 'Cleansing time' and 'Standby after cleansing'.	Execute Forced cleansing after cleansing action is completed.
Unable to enter a calibration mode.	Lロロ / (Lock 1), Lロロゼ (Lock 2) or Lロロゴ (Lock 3) has been selected in [Set value lock (p.34)].	Select [[(Unlock).
	cLEω (Cleansing output) has been selected in any of [EVT1 to EVT6 types (pp. 26, 31)], and cleansing action is performing using the 'Cleansing time' and 'Standby after cleansing'.	Perform calibration after cleansing action is completed.

12.2.3 Communication

Check that power is being supplied to the master and slave that customers use. If communication failure still occurs, check the following.

Problem	Possible Cause	Solution
Communication failure	Communication cable is not securely connected, or is disconnected/ defective.	Check the communication cable and connector.
	Incorrect wiring of the communication cable and/or connector	Check the communication cable and connector.
	Imperfect contact between the communication cable and the connector, or between the communication connector and instrument port	Check the communication cable and connector.
	Communication speed of the slave does not match that of the master.	Check the communication speed of the slave and master.
	The data bit, parity and stop bit of the master do not correspond to those of	Check the data bit, parity and stop bit of the master and the
	the slave.	slave.
	The instrument number (address) of the slave does not correspond to that of the command.	Check the instrument number (address) of the slave.
	The instrument numbers (addresses)	Check the instrument numbers
	are duplicated in multiple slaves.	(addresses) of the slave.
	Make sure that the program is appropriate for the transmission timing.	Check the program.
Although communication is occurring, the	A non-existent command code has been sent.	Check the command code.
response is negative acknowledgement.	The setting command data exceeds the setting range of the slave.	Check the setting range.
	The WIL-102-DO cannot be set while calibration is being performed.	Check the slave status.
	The WIL-102-DO is in front keypad operation setting mode.	Return the unit to Display Mode or Cleansing Output Mode.

13. Character Tables

The following shows our character tables. Use data column for your reference.

Setting Groups

Character	Setting Group
F.n.c.	DO Concentration Input Group
[.r.a.	Transmission Output 1 Group
	Transmission Output 2 Group
E.H.F. I	EVT1 Action Group
<i>E.K.T.2</i>	EVT2 Action Group
E.H.F.3	EVT3 Action Group (*)
E.H.T.H	EVT4 Action Group (*)
E.H.T.5	EVT5 Action Group (*)
E.H.F.5	EVT6 Action Group (*)
	Communication Group
c.L.E.G	Cleansing Group
οΓ.Ε.r	Basic Function Group
'4.E.L.F	Self-Check Group
c.L.r.	Data Clear Group

^(*) Available only when EVT output (EVT option) is ordered.

DO Concentration Calibration

Character	Setting Item, Setting Range	Factory Default	Data
Measured	DO concentration 1-point calibration		
value (*)	mode		
Measured	DO concentration 2-point calibration		
value (*)	mode		
c8dF	Concentration option calibration	0.00 mg/L	
Concentration	mode		
desired value	Setting range: 0.00 to 20.00 mg/L		

^(*) DO concentration measured value flashes.

Transmission Output 1 Adjustment

Character	Setting Item, Setting Range	Factory Default	Data
RJ∃ I	Transmission output 1 Zero	0.00 mg/L	
	adjustment		
	Setting range: ±5.00% of Transmission	n output 1 span	
RJ5 !	Transmission output 1 Span	0.00 mg/L	
	adjustment		
	Setting range: ±5.00% of Transmission	n output 1 span	

Transmission Output 2 Adjustment

***************************************	itput = / tajuotinont		
Character	Setting Item, Setting Range	Factory Default	Data
RJE2	Transmission output 2 Zero	0.00 mg/L	
	adjustment		
	Setting range: ±5.00% of Transmission	า output 2 span	
RJ'-2	Transmission output 2 Span	0.00 mg/L	
	adjustment		
	Setting range: ±5.00% of Transmission	n output 2 span	

DO Concentration Input Group

Character	Setting Item, Setting Range	Factory Default	Data
dFcT	Signal output response time	60 seconds	
<u> </u>	Setting range: 5 to 600 seconds		
58LF	Salinity correction	0 PSU	
	Setting range: 0 to 42 PSU		
SERL	Altitude correction	0 m	
	Setting range: 0 to 5000 m		

Transmission Output 1 Group

Character	Setting Item, Setting Range	Factory Default	Data
r-p !	Transmission output 1 type	DO concentration transmission	
do	ರಂದ : DO concentration transmissio	n	
	<i>ิ้มโ กิP</i> : Water temperature transmissi	on	
	ぱヮ゚ヮ゚゙ : DO % saturation transmission		
	- デァウ:Oxygen partial pressure trans	mission	
[-H	Transmission output 1 high limit	20.00 mg/L	
20.00	Setting range:		
	Transmission output 1 low limit to Mea	surement range high limit	
[- L	Transmission output 1 low limit	0.00 mg/L	
□000	Setting range:		
	Measurement range low limit to Transı	mission output 1 high limit	
17-c 1	Transmission output 1 status	Last value HOLD	
6EFH	when calibrating		
	<i>₽₽₽</i> : Last value HOLD (Retains the	last value before calibrating DO	
	concentration, and outputs it.)		
	与EFH: Set value HOLD (Outputs the v		
	1 value HOLD when calibrating PBH Measured value (Outputs the n	- /	
	DO concentration.)	lleasured value when calibrating	
5-51	Transmission output 1 value HOLD	0.00 mg/L	
	when calibrating	0.00 mg/L	
	Setting range:		
	Measurement range low limit to Measu	rement range high limit	

Transmission Output 2 Group

Character	Setting Item, Setting Range	Factory Default	Data
[ro2	Transmission output 2 type	DO concentration transmission	
do	ರಂದ : DO concentration transmissio	n	
	- 応じずど:Water temperature transmissi	on	
	ぱヮ゚ヮ゚゙ : DO % saturation transmission	1	
	ンディウ:Oxygen partial pressure trans	mission	
[r-H2	Transmission output 2 high limit	20.00 mg/L	
20.00	Setting range:		
	Transmission output 2 low limit to Mea	surement range high limit	
[-12	Transmission output 2 low limit	0.00 mg/L	
	Setting range:		
	Measurement range low limit to Trans	mission output 2 high limit	
[re2	Transmission output 2 status	Last value HOLD	
bEFH	when calibrating		
	bEFH: Last value HOLD (Retains the	last value before calibrating DO	
	concentration, and outputs it.)		
	ったけ: Set value HOLD (Outputs the value HOLD when calibrating		
	FBH: Measured value (Outputs the r	- /	
	DO concentration.)	neasured value when calibrating	
[-52	Transmission output 2 value HOLD	0.00 mg/L	
	when calibrating	3, =	
	Setting range:		
	Measurement range low limit to Measu	ırement range high limit	

EVT1 Action Group

No action	EVT1 type
	==== : No action
action	ರ್ಷ- ೫ : DO concentration input high limit
	ರ್ಷ-ಓ : DO concentration input low limit
	ฉั/ ีกั∺ : Water temperature input high lim
	นักกัน : Water temperature input low limi
	ゴロケ岩 : DO % saturation input high limit
	ゴロウム : DO % saturation input low limit a
	ュラー片:Oxygen partial pressure input hig
	立デァム:Oxygen partial pressure input lov
	「ロボラ : Sensor cap replacement timer
v limits independent action	.
•	「ゔ゚゚゚゚゚゚゚゚゚゚゚゚゚゚゚゚゚゚゚゙゚゚゚゚゚゚゚゙゚゚゚゚゚゚゚゚゚゚
limits independent action	ゴ'っぱ」:DO % saturation input High/Low
gh/Low limits independent	ュ゙゚゚PH' ∴: Oxygen partial pressure input Hi
	action
entration input: 0.00 mg/L	, ,
-	
•	
g/L	•
	·
0 kPa	•
	· · · · · · · · · · · · · · · · · · ·
	೯ರ್ಟ್ : Medium Value
	누리 두 : Reference Value
entration input: 0.01 mg/L	EVT1 ON side (*2) DO conce
nperature input: 1.0℃	
•	
/L	•
	·
kPa	
entration input: 0.01 mg/L	
nperature input: 1.0℃	
•	
/L	•
	· · · · · · · · · · · · · · · · · · ·
kPa	•
ow limits independent action limits independent action gh/Low limits independent entration input: 0.00 mg/L operature input: 0.0°C curation input: 0.0% artial pressure input: 0.0 kPa g/L O kPa e Value entration input: 0.01 mg/L operature input: 1.0°C curation input: 0.1% operature input: 0.1 kPa // kPa entration input: 0.01 mg/L operature input: 0.1 kPa // kPa entration input: 0.01 mg/L operature input: 1.0°C curation input: 0.1% operature input: 1.0°C curation input: 0.1% operature input: 0.1% operature input: 0.1% operature input: 0.1% operatial pressure input: 0.1 kPa // // // // // // // // //	#### DO % saturation input High/Low action EVT1 value (*1) DO concert Water term DO % saturation input: 0.00 to 20.00 mm Water temperature input: 0.0 to 50.0°C DO % saturation input: 0.0 to 200.0% Oxygen partial pressure input: 0.0 to 150. EVT1 hysteresis type (*2) □□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□

^(*1) If $\Box\Box\Box\Box$ (No action), $\Box\Box\Box\Box$ (Sensor cap replacement timer), $\Box\Box\Box\Box$ (Self-check output) or $\Box\Box\Box\Box$ (Cleansing output) is selected in [EVT1 type], this setting item and all subsequent items will not be available.

^(*2) Not available if ロロド (DO concentration input High/Low limits independent action), 「うせん (Water temperature input High/Low limits independent action), ロロード (DO % saturation input High/Low limits independent action) or ロード (Oxygen partial pressure input High/Low limits independent action) is selected in [EVT1 type].

Character	Setting Item, Setting Range	Factory Default	Data
on[!	EVT1 ON delay time	0 seconds	
	Setting range: 0 to 9999 seconds		
off!	EVT1 OFF delay time	0 seconds	
	Setting range: 0 to 9999 seconds		
oon l	Output ON Time when EVT1	0 seconds	
	Output ON		
	Setting range: 0 to 9999 second	ds	
oof !	Output OFF Time when EVT1	0 seconds	
	Output ON		
	Setting range: 0 to 9999 second	ds	
E_L !	EVT1 High/Low limits	DO concentration input: 0.00 mg/L	
	independent lower side value	Water temperature input: 0.0℃	
	(*)	DO % saturation input: 0.0%	
		Oxygen partial pressure input: 0.0 kPa	
	•	to 20.00 mg/L	
	Water temperature input: 0.0 to		
	DO % saturation input: 0.0 to 200.0%		
E_H :	Oxygen partial pressure input: 0	I	
	EVT1 High/Low limits	DO concentration input: 0.00 mg/L	
	independent upper side value	Water temperature input: 0.0°C	
		DO % saturation input: 0.0% Oxygen partial pressure input: 0.0 kPa	
	DO concentration input: 0.00 t	to 20.00 mg/L	
	Water temperature input: 0.00 to	U	
		200.0%	
	Oxygen partial pressure input: 0		
EHY !	EVT1 hysteresis	DO concentration input: 0.01 mg/L	
		Water temperature input: 1.0℃	
		DO % saturation input: 0.1%	
	Oxygen partial pressure input: 0.1 kPa		
	DO concentration input: 0.01 to 2.00 mg/L		
	Water temperature input: 1.0 to		
	DO % saturation input: 0.1 to 20.0%		
	Oxygen partial pressure input: 0	0.1 to 15.0 kPa	

^(*) If \(\sigma \sigma HL \) (DO concentration input High/Low limits independent action), \(\int \sigma HL \) (Water temperature input High/Low limits independent action) or \(\sigma PHL \) (Oxygen partial pressure input High/Low limits independent action) is selected in [EVT1 type], this setting item and all subsequent items will be available.

EVT2 Action Group

Character	Setting Item, Setting Rang	ge Factory Default	Data
EFF2	EVT2 type	No action	
	: No action]
	ರ್ಷ_∺ : DO concentration input	t high limit action	
	ದ್ದು: DO concentration input	3	
	- - ぶこうど:Water temperature inpu		
	ี่มีเก็น : Water temperature input low limit action		
	ロロート : DO % saturation input high limit action		
	ี่ ฮือ ี่ L : DO % saturation input low limit action		
	ュアテH: Oxygen partial pressure		
	ンドーム:Oxygen partial pressure		
	「ローラー: Sensor cap replacement		
	っという: Self-check output	in timor	
	□ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □		
		t High/Low limits independent action	
		ut High/Low limits independent action	
	l	High/Low limits independent action	
		re input High/Low limits independent	
	action		
5820	EVT2 value (*1)	DO concentration input: 0.00 mg/L	
		Water temperature input: 0.0℃	
		DO % saturation input: 0.0%	
	_	Oxygen partial pressure input: 0.0 kPa	_
	DO concentration input: 0.00 to	•	
	Water temperature input: 0.0 to 50.0°C		
	DO % saturation input: 0.0 to 200.0% Oxygen partial pressure input: 0.0 to 150.0 kPa		
d: F2		Reference Value	
Sal F	EV12 Hysteresis type (2)	Reference value	-
1.2	ープリア : Nedium value		
dFoZ		DO concentration input: 0.01 mg/L	
	` ,	Water temperature input: 1.0°C	
		DO % saturation input: 0.1%	
		Oxygen partial pressure input: 0.1 kPa	<u> </u>
	·	o 4.00 mg/L	
	Water temperature input: 0.0 to		
	·	40.0%	
dFU2	Oxygen partial pressure input: 0		
@ruc @QO !		DO concentration input: 0.01 mg/L Water temperature input: 1.0°C	
		DO % saturation input: 0.1%	
		Oxygen partial pressure input: 0.1 kPa	
	DO concentration input: 0.00 to	o 4.00 mg/L	
	•	10.0℃	
	·	40.0%	
	Oxygen partial pressure input: 0	.0 to 30.0 kPa	

^(*1) If $\Box\Box\Box\Box$ (No action), $\Box\Box\Box\Box$ (Sensor cap replacement timer), $\Box\Box\Box\Box$ (Self-check output) or $\Box\Box\Box\Box$ (Cleansing output) is selected in [EVT2 type], this setting item and all subsequent items will not be available.

^(*2) Not available if ロロド (DO concentration input High/Low limits independent action), 「こだし (Water temperature input High/Low limits independent action), ロロード (DO % saturation input High/Low limits independent action) or ロード (Oxygen partial pressure input High/Low limits independent action) is selected in [EVT2 type].

Character	Setting Item, Setting Range	Factory Default	Data	
an[2	EVT2 ON delay time	0 seconds		
	Setting range: 0 to 9999 seconds			
off2	EVT2 OFF delay time	0 seconds		
	Setting range: 0 to 9999 second	ls		
oond	Output ON Time when EVT2	0 seconds		
	Output ON			
	Setting range: 0 to 9999 second	ls		
ooF2	Output OFF Time when EVT2	0 seconds		
	Output ON			
	Setting range: 0 to 9999 second	ls		
ELLZ	EVT2 High/Low limits	DO concentration input: 0.00 mg/L		
	independent lower side value	Water temperature input: 0.0℃		
	(*)	DO % saturation input: 0.0%		
		Oxygen partial pressure input: 0.0 kPa		
	· ·	to 20.00 mg/L		
	Water temperature input: 0.0 to			
	•	DO % saturation input: 0.0 to 200.0% Oxygen partial pressure input: 0.0 to 150.0 kPa		
E_H2	EVT2 High/Low limits	DO concentration input: 0.00 mg/L		
làaaa	independent upper side value	Water temperature input: 0.0°C		
	macpenaem apper side value	DO % saturation input: 0.0%		
		Oxygen partial pressure input: 0.0 kPa		
	DO concentration input: 0.00 t	to 20.00 mg/L		
	Water temperature input: 0.0 to	50.0℃		
	•	200.0%		
	Oxygen partial pressure input: 0			
EH92	EVT2 hysteresis	DO concentration input: 0.01 mg/L		
		Water temperature input: 1.0°C		
		DO % saturation input: 0.1%		
	Oxygen partial pressure input: 0.1 kPa			
	DO concentration input: 0.01 to 2.00 mg/L Water temperature input: 1.0 to 5.0°C			
	DO % saturation input: 0.1 to 20.0%			
	Oxygen partial pressure input: 0			

^(*) If doHL (DO concentration input High/Low limits independent action), foHL (Water temperature input High/Low limits independent action), doHL (DO % saturation input High/Low limits independent action) or up HL (Oxygen partial pressure input High/Low limits independent action) is selected in [EVT2 type], this setting item and all subsequent items will be available.

EVT3 Action Group

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^(*1) If $\Box\Box\Box\Box$ (No action), $\Box\Box\Box\Box$ (Sensor cap replacement timer), $\Box\Box\Box\Box$ (Self-check output) or $\Box\Box\Box\Box$ (Cleansing output) is selected in [EVT3 type], this setting item and all subsequent items will not be available.

^(*2) Not available if ロロド (DO concentration input High/Low limits independent action), 「うせん (Water temperature input High/Low limits independent action), ロロード (DO % saturation input High/Low limits independent action) or ロード (Oxygen partial pressure input High/Low limits independent action) is selected in [EVT3 type].

Character	Setting Item, Setting Range	Factory Default	Data
on[3	EVT3 ON delay time	0 seconds	
	Setting range: 0 to 9999 seconds		
oFſ∃	EVT3 OFF delay time	0 seconds	
	Setting range: 0 to 9999 second	ds	
oon3	Output ON Time when EVT3	0 seconds	
	Output ON		
	Setting range: 0 to 9999 second	ds	
00F3	Output OFF Time when EVT3	0 seconds	
	Output ON		
	Setting range: 0 to 9999 second	ds	
E_L3	EVT3 High/Low limits	DO concentration input: 0.00 mg/L	
	independent lower side value	Water temperature input: 0.0℃	
	(*)	DO % saturation input: 0.0%	
		Oxygen partial pressure input: 0.0 kPa	
	· ·	to 20.00 mg/L	
	Water temperature input: 0.0 to		
	DO % saturation input: 0.0 to Oxygen partial pressure input: 0	0 200.0%	
E_H3	EVT3 High/Low limits	DO concentration input: 0.00 mg/L	
làaaa	independent upper side value	Water temperature input: 0.0°C	
	macpondent apper olde value	DO % saturation input: 0.0%	
		Oxygen partial pressure input: 0.0 kPa	
	DO concentration input: 0.00 t	to 20.00 mg/L	
	Water temperature input: 0.0 to	50.0℃	
	•	200.0%	
	Oxygen partial pressure input: 0		
EH43	EVT3 hysteresis	DO concentration input: 0.01 mg/L	
□ <i>□□□□ ।</i>		Water temperature input: 1.0°C	
		DO % saturation input: 0.1%	
	Oxygen partial pressure input: 0.1 kPa		
	DO concentration input: 0.01 to 2.00 mg/L Water temperature input: 1.0 to 5.0°C		
	DO % saturation input: 0.1 to 20.0%		
	Oxygen partial pressure input: 0		

^(*) If doHL (DO concentration input High/Low limits independent action), foHL (Water temperature input High/Low limits independent action), doHL (DO % saturation input High/Low limits independent action) or up HL (Oxygen partial pressure input High/Low limits independent action) is selected in [EVT3 type], this setting item and all subsequent items will be available.

EVT4 Action Group

Setting Item, Setting Rang	ge	Factory Default	Data
EVT4 type		No action	
: No action			
ರ್ಷ_∺ : DO concentration inpu	t high limit	action	
-	_		
·			
มีเก็บ : Water temperature input low limit action			
•	•		
	-		
<u> </u>	ıt High/Low	/ limits independent action	
	-	•	
ゴウガに:DO % saturation input	High/Low	limits independent action	
ュアガレ:Oxygen partial pressui	re input Hi	gh/Low limits independent	
action			
EVT4 value (*1)			
•		g/L	
· · · · · · · · · · · · · · · · · · ·			
•) kPa	
ದರ್ಚ ೯ : Medium Value			
与点にF:Reference Value			
EVT4 ON side (*2)	DO conce	entration input: 0.01 mg/L	
		·	
		•	
•	•	/L	
·			
		kPa	
EVT4 OFF side (*3)			
		·	
		•	
DO concentration is not a 2001			
•	•	'L	
· ·			
•		kPa	
	EVT4 type □□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□	EVT4 type ELECT: No action da_H: DO concentration input high limit da_L: DO concentration input low limit da_L: Water temperature input high limit da_H: Water temperature input low limit da_H: DO % saturation input high limit da_H: DO % saturation input low limit da_H: Oxygen partial pressure input low [ERP: Self-check output elect: Cleansing output da_H: DO concentration input High/Low dh_H: Water temperature input High/Low dh_H: DO % saturation input High/Low dh_H: DO % saturation input High/Low dh_H: DO % saturation input: 0.00 to 20.00 mg Water temperature input: 0.0 to 50.0℃ DO % saturation input: 0.0 to 150.0€ EVT4 hysteresis type (*2) cdl F: Medium Value ddl F: Reference Value EVT4 ON side (*2) DO concentration input: 0.00 to 4.00 mg Water temperature input: 0.0 to 10.0℃ DO % saturation input: 0.0 to 10.0℃ DO % saturation input: 0.00 to 4.00 mg Water temperature input: 0.00 to 4.00 mg Water tempera	No action Interest No action Interest No action Interest No action Interest Inter

^(*1) If $\Box\Box\Box\Box$ (No action), $\Box\Box\Box\Box$ (Sensor cap replacement timer), $\Box\Box\Box\Box$ (Self-check output) or $\Box\Box\Box\Box$ (Cleansing output) is selected in [EVT4 type], this setting item and all subsequent items will not be available.

^(*2) Not available if ロロド (DO concentration input High/Low limits independent action), 「ロド (Water temperature input High/Low limits independent action), ロロード (DO % saturation input High/Low limits independent action) or ロード (Oxygen partial pressure input High/Low limits independent action) is selected in [EVT4 type].

Character	Setting Item, Setting Range	Factory Default	Data
onf4	EVT4 ON delay time	0 seconds	
	Setting range: 0 to 9999 second	9999 seconds	
off4	EVT4 OFF delay time	0 seconds	
	Setting range: 0 to 9999 second	ds	
oon4	Output ON Time when EVT4	0 seconds	
	Output ON		
	Setting range: 0 to 9999 second	ds	
00FY	Output OFF Time when EVT4	0 seconds	
	Output ON		
_	Setting range: 0 to 9999 second	ds	
ELLY	EVT4 High/Low limits	DO concentration input: 0.00 mg/L	
	independent lower side value	Water temperature input: 0.0℃	
	(*)	DO % saturation input: 0.0%	
		Oxygen partial pressure input: 0.0 kPa	
	•	to 20.00 mg/L	
	Water temperature input: 0.0 to DO % saturation input: 0.0 to	200.0%	
	Oxygen partial pressure input: 0		
E_HY	EVT4 High/Low limits	DO concentration input: 0.00 mg/L	
	independent upper side value	Water temperature input: 0.0°C	
		DO % saturation input: 0.0%	
		Oxygen partial pressure input: 0.0 kPa	
	DO concentration input: 0.00 to	to 20.00 mg/L	
	Water temperature input: 0.0 to		
	•	200.0%	
T 1 11 11 1	Oxygen partial pressure input: (
£#¥4 □00 ;	EVT4 hysteresis	DO concentration input: 0.01 mg/L Water temperature input: 1.0°C	
		DO % saturation input: 0.1%	
		Oxygen partial pressure input: 0.1 kPa	
	DO concentration input: 0.01 to 2.00 mg/L		
	Water temperature input: 1.0 to 5.0°C		
	DO % saturation input: 0.1 to 20.0%		
	Oxygen partial pressure input: (0.1 to 15.0 kPa	

^(*) If \(\sigma \sigma HL \) (DO concentration input High/Low limits independent action), \(\int \sigma HL \) (Water temperature input High/Low limits independent action) or \(\sigma PHL \) (Oxygen partial pressure input High/Low limits independent action) is selected in [EVT4 type], this setting item and all subsequent items will be available.

EVT5 Action Group

Character	Setting Item, Setting Rang	е	Factory Default	Data
EFFS	EVT5 type		No action	
	Section : No action	L		
	ぱヮ_廾 : DO concentration input	high limit	action	
	dロ_L: DO concentration input	•		
	ធ្វើក្ដី : Water temperature input high limit action			
	ฉัก ัก่⊾ : Water temperature input low limit action			
	コット : Water temperature impa			
	カロール : DO % saturation input low limit action			
	。 こと が saturation input in 「アード : Oxygen partial pressure			
	「アート: Oxygen partial pressure			
	「ころ? : Sensor cap replacemen		mint dollon	
	っという : Self-check output	it tillioi		
	ことに : Self-check output			
	ರಂಗ್ರ : DO concentration input	: High/Low	limits independent action	
	「元光」: Water temperature input			
	ゴラピ : DO % saturation input I	_		
	ュアHL:Oxygen partial pressure	•	•	
	action		· · · · · · · · · · · · · · · · · · ·	
585	EVT5 value (*1)	DO conce	ntration input: 0.00 mg/L	
			perature input: 0.0℃	
			uration input: 0.0%	
			artial pressure input: 0.0 kPa	
		ა 20.00 mg 50.0°C	J/L	
	Water temperature input: 0.0 to 50.0°C DO % saturation input: 0.0 to 200.0%			
	Oxygen partial pressure input: 0.		kPa	
d: F5		Reference		
5d1 F	೯ರ್ಟ್ : Medium Value			
	ちぱげ: Reference Value			
dFo5	` '		ntration input: 0.01 mg/L	
			perature input: 1.0°C	
			uration input: 0.1%	
	I —	Oxygen page 4.00 mg/	artial pressure input: 0.1 kPa	
	DO concentration input: 0.00 to Water temperature input: 0.0 to		L	
	DO % saturation input: 0.0 to			
	Oxygen partial pressure input: 0.		кРа	
arus	` '		ntration input: 0.01 mg/L	
<u> </u>			perature input: 1.0°C	
			uration input: 0.1%	
			artial pressure input: 0.1 kPa	
	DO concentration input: 0.00 to Water temperature input: 0.0 to	o 4.00 mg/ 10.0°C	L	
	DO % saturation input: 0.0 to			
	Oxygen partial pressure input: 0.		кРа	

^(*1) If $\Box\Box\Box\Box$ (No action), $\Box\Box\Box\Box$ (Sensor cap replacement timer), $\Box\Box\Box\Box$ (Self-check output) or $\Box\Box\Box\Box$ (Cleansing output) is selected in [EVT5 type], this setting item and all subsequent items will not be available.

^(*2) Not available if ロロド (DO concentration input High/Low limits independent action), 「うせん (Water temperature input High/Low limits independent action), ロロード (DO % saturation input High/Low limits independent action) or ロード (Oxygen partial pressure input High/Low limits independent action) is selected in [EVT5 type].

Character	Setting Item, Setting Range	Factory Default	Data
on/5	EVT5 ON delay time	0 seconds	
	Setting range: 0 to 9999 seconds		
oFF5	EVT5 OFF delay time	0 seconds	
	Setting range: 0 to 9999 second	ls	
oon5	Output ON Time when EVT5	0 seconds	
	Output ON		
	Setting range: 0 to 9999 second	ls	
00F5	Output OFF Time when EVT5	0 seconds	
	Output ON		
	Setting range: 0 to 9999 second	ls	
E_L5	EVT5 High/Low limits	DO concentration input: 0.00 mg/L	
	independent lower side value	Water temperature input: 0.0℃	
	(*)	DO % saturation input: 0.0%	
		Oxygen partial pressure input: 0.0 kPa	
	· ·	to 20.00 mg/L	
	Water temperature input: 0.0 to		
	DO % saturation input: 0.0 to Oxygen partial pressure input: 0	200.0%	
E_HS	EVT5 High/Low limits	DO concentration input: 0.00 mg/L	
làaaa	independent upper side value	Water temperature input: 0.0°C	
	macpenaem apper side value	DO % saturation input: 0.0%	
		Oxygen partial pressure input: 0.0 kPa	
	DO concentration input: 0.00 t	to 20.00 mg/L	
	Water temperature input: 0.0 to	50.0℃	
	•	200.0%	
	Oxygen partial pressure input: 0		
EHUS	EVT5 hysteresis	DO concentration input: 0.01 mg/L	
□ <i>□□□□ ।</i>		Water temperature input: 1.0°C	
		DO % saturation input: 0.1%	
	Oxygen partial pressure input: 0.1 kPa		
	DO concentration input: 0.01 to 2.00 mg/L Water temperature input: 1.0 to 5.0°C		
	DO % saturation input: 0.1 to 20.0%		
	Oxygen partial pressure input: 0		

^(*) If \$\delta \delta H \text{L}\$ (DO concentration input High/Low limits independent action), \$\int \bar{a} \delta H \text{L}\$ (Water temperature input High/Low limits independent action) or \$\bar{a} \beta H \text{L}\$ (Oxygen partial pressure input High/Low limits independent action) is selected in [EVT5 type], this setting item and all subsequent items will be available.

EVT6 Action Group

Character	Setting Item, Setting Range	Factory Default	Data	
EFF5	EVT6 type	No action		
[-]-]-]-	Section : No action			
	dロ_H: DO concentration input	high limit action		
	dロ_L : DO concentration input	_		
	ធ្វើក្ដី : Water temperature input high limit action			
	มีเก็น : Water temperature input low limit action			
	コット : Water temperature impa			
	ロロール : DO % saturation input low limit action			
	。 こと が saturation input in 「アード : Oxygen partial pressure			
	エピーと: Oxygen partial pressure	. •		
	「로위우 : Sensor cap replacemen			
	っという consor cap replacement っとした : Self-check output	t unioi		
	ことに : Gen-check output			
		High/Low limits independent action	n	
		t High/Low limits independent action		
		ligh/Low limits independent action		
	l	e input High/Low limits independen	t	
	action			
485	EVT6 value (*1)	OO concentration input: 0.00 mg/	L	
		Vater temperature input: 0.0℃		
		OO % saturation input: 0.0%		
	<u> </u>	Oxygen partial pressure input: 0.0 k	(Pa	
		20.00 mg/L		
	Water temperature input: 0.0 to 50.0°C DO % saturation input: 0.0 to 200.0%			
	Oxygen partial pressure input: 0.			
d: F5		Reference Value		
5d1 F	೯ರ್ಟ್ : Medium Value			
	ちぱげ: Reference Value			
dFo5	` '	OO concentration input: 0.01 mg/	L	
□ <i>0.0 +</i>		Vater temperature input: 1.0°C		
		OO % saturation input: 0.1%	√De	
	<u> </u>	Oxygen partial pressure input: 0.1 l 4.00 mg/L	KPa	
	Water temperature input: 0.00 to			
	DO % saturation input: 0.0 to			
	Oxygen partial pressure input: 0.			
dFU5	EVT6 OFF side (*3)	OO concentration input: 0.01 mg/	L	
<u> </u>		Vater temperature input: 1.0°C		
		OO % saturation input: 0.1%	J.D	
		Oxygen partial pressure input: 0.1 l	KPa	
	DO concentration input: 0.00 to Water temperature input: 0.0 to	4.00 mg/L I∩ 0°C		
	DO % saturation input: 0.0 to			
	Oxygen partial pressure input: 0.0			

^(*1) If $\Box\Box\Box\Box$ (No action), $\Box\Box\Box\Box$ (Sensor cap replacement timer), $\Box\Box\Box\Box$ (Self-check output) or $\Box\Box\Box\Box$ (Cleansing output) is selected in [EVT6 type], this setting item and all subsequent items will not be available.

^(*2) Not available if ロロド (DO concentration input High/Low limits independent action), 「うせん (Water temperature input High/Low limits independent action), ロロード (DO % saturation input High/Low limits independent action) or ロード (Oxygen partial pressure input High/Low limits independent action) is selected in [EVT6 type].

Character	Setting Item, Setting Range	Factory Default	Data
on/5	EVT6 ON delay time	0 seconds	
	Setting range: 0 to 9999 second	e: 0 to 9999 seconds	
oFF5	EVT6 OFF delay time	0 seconds	
	Setting range: 0 to 9999 second	ds	
oon5	Output ON Time when EVT6	0 seconds	
	Output ON		
	Setting range: 0 to 9999 second	ds	
ooF5	Output OFF Time when EVT6	0 seconds	
	Output ON		
	Setting range: 0 to 9999 second	ds	
E_L5	EVT6 High/Low limits	DO concentration input: 0.00 mg/L	
	independent lower side value	Water temperature input: 0.0℃	
	(*)	DO % saturation input: 0.0%	
		Oxygen partial pressure input: 0.0 kPa	
	•	to 20.00 mg/L	
	Water temperature input: 0.0 to		
	·	0 200.0%	
E_HS	Oxygen partial pressure input: (EVT6 High/Low limits	DO concentration input: 0.00 mg/L	
	independent upper side value	Water temperature input: 0.0°C	
	independent upper side value	DO % saturation input: 0.0%	
		Oxygen partial pressure input: 0.0 kPa	
	DO concentration input: 0.00	to 20.00 mg/L	
	Water temperature input: 0.0 to	•	
	· · · · · · · · · · · · · · · · · · ·	200.0%	
	Oxygen partial pressure input: ().0 to 150.0 kPa	
EHY5	EVT6 hysteresis	DO concentration input: 0.01 mg/L	
		Water temperature input: 1.0℃	
		DO % saturation input: 0.1%	
	Oxygen partial pressure input: 0.1 kPa		
	DO concentration input: 0.01 to 2.00 mg/L		
	Water temperature input: 1.0 to 5.0°C DO % saturation input: 0.1 to 20.0%		
	'		
	Oxygen partial pressure input: 0.1 to 15.0 kPa		

^(*) If ゴロガム (DO concentration input High/Low limits independent action), 「カガム (Water temperature input High/Low limits independent action), ゴウガム (DO % saturation input High/Low limits independent action) or エアガム (Oxygen partial pressure input High/Low limits independent action) is selected in [EVT6 type], this setting item and all subsequent items will be available.

Communication Group

Character	Setting Item, Setting Range	Factory Default	Data
557L	Communication protocol	Shinko protocol	
noñL	กอกี่∟: Shinko protocol		
	ក್¤ದೆ∺ : MODBUS ASCII mode		
	ಗೆದರ್ದ: MODBUS RTU mode		
cōna	Instrument number	0	
	0 to 95		
cāhP	Communication speed	9600 bps	
<u> </u>	<i>□□95</i> : 9600 bps		
	☐ /母♂:19200 bps		
	୍ର ∄ଞ୍ଜି : 38400 bps		
cāfī	Data bit/Parity	7 bits/Even	
7885	อีกอก : 8 bits/No parity		
	ไก¤ก:7 bits/No parity		
	<i>ឱEಟ⊓</i> : 8 bits/Even		
	ヿ゚゙゙゙゙゙゙゚゚ ∃゚゙゙゙゙゙ヮ: 7 bits/Even		
	<i>ಔ¤ದದ</i> : 8 bits/Odd		
	ೌರದ್ದ : 7 bits/Odd		
<u> </u>	Stop bit	1 bit	
	: 1 bit		

Cleansing Group

Character	Setting Item, Setting Range	Factory Default	Data
cLIA	Cleansing time	30 seconds	
30	Setting range: 10 to 120 seconds		
cLcY	Cleansing inactive interval	OFF (None)	
off.	ರ್೯೯∷ (None), 10 to 240 minutes		
cl! [Standby after Cleansing	0 seconds	
	Setting range: 0 to 60 seconds		

Basic Function Group

Character	Setting Item, Setting Range	Factory Default	Data
Lock	Set value lock	Unlock	
	(Unlock): All set values can be cha	anged.	
	上ロロ / (Lock 1): None of the set values c	an be changed.	
	とゅこざ (Lock 2): Only EVT1 to EVT6 valu	es can be changed.	
	上 ឆ ⊑ ∃ (Lock 3): All set values can be ten	nporarily changed. However,	
	they revert to their previous value after the power is		
	turned off because they are not saved in the		
	non-volatile IC memory.		
LIGI	Auto-light function	Disabled	
	=i=i=i : Disabled		
	出っE□ : Enabled		
r: AE	Indication time	00.00 (Remains lit)	
00.00	Setting range:		
	00.00 (Remains lit)		
	00.01 to 60.00 (Minutes.Seconds)		

Character	Setting Item, Setting Range	Factory Default	Data
1 Err	EVT output when input errors occur	Disabled	
oFF□	<i>□⊓</i> ∷: Enabled		
	<i>□FF</i> □ : Disabled		
<u>'></u> 8 /□	EVT1 value	365 days	
<u> </u>	Setting range: 0 to 1095 days		
	EVT1 ON delay time	0 seconds	
	Setting range: 0 to 9999 seconds		
off!	EVT1 OFF delay time	0 seconds	
	Setting range: 0 to 9999 seconds		
<i>582</i>	EVT2 value	365 days	
<u>⊞365</u>	Setting range: 0 to 1095 days		
on[2	EVT2 ON delay time	0 seconds	
	Setting range: 0 to 9999 seconds		
aFF2	EVT2 OFF delay time	0 seconds	
	Setting range: 0 to 9999 seconds		
<i>583</i> □	EVT3 value (*)	365 days	
□365	Setting range: 0 to 1095 days		
on[3	EVT3 ON delay time (*)	0 seconds	
	Setting range: 0 to 9999 seconds		
oFf∃	EVT3 OFF delay time (*)	0 seconds	
	Setting range: 0 to 9999 seconds		
584	EVT4 value (*)	365 days	
<u> </u>	Setting range: 0 to 1095 days		
on!"Y	EVT4 ON delay time (*)	0 seconds	
	Setting range: 0 to 9999 seconds		
of: "4	EVT4 OFF delay time (*)	0 seconds	
	Setting range: 0 to 9999 seconds		
585	EVT5 value (*)	365 days	
<u> </u>	Setting range: 0 to 1095 days		
an/5	EVT5 ON delay time (*)	0 seconds	
	Setting range: 0 to 9999 seconds		
aFF5	EVT5 OFF delay time (*)	0 seconds	
	Setting range: 0 to 9999 seconds		
585 <u></u>	EVT6 value (*)	365 days	
<i>⊞3</i> 85	Setting range: 0 to 1095 days		
an/5	EVT6 ON delay time (*)	0 seconds	
	Setting range: 0 to 9999 seconds		
oF15	EVT6 OFF delay time (*)	0 seconds	
	Setting range: 0 to 9999 seconds		
rElā	Sensor cap replacement timer	365 days	
<i>□3</i> 85	remainder		
	Setting range: 0 to 1095 days		

^(*) Available only when EVT output (EVT option) is ordered.

Self-Check Group

Character	Mode					
All lit	LED all lit mode					
Individually lit	LED individual lit mode					
EEY[]	Key input mode					
nonE	Temperature Display Key Input					
	nonE	When no key is pressed				
	∐P∭	When the 🛆 key is pressed				
	daūn	When the 🔽 key is pressed				
	db	When 2 or more keys are pressed simultaneously				
aUT 🗆	Output mode					
oFF□	Temperature Display	Output				
	oFF□	All EVT outputs: OFF, Transmission output 1 and 2: 4 mA DC				
	EAL!	EVT1 output ON				
	E81.5	EVT2 output ON				
	£873	EVT3 output ON				
	E814	EVT4 output ON				
	EBFS					
	£875	EVT6 output ON				
	[rol	Transmission output 1: 20 mA DC				
	[rod	Transmission output 2: 20 mA DC				
do	Input mode					
Measured	DO Display Temperature Display					
value	do	DO concentration measured value				
	<u>J</u> FAP	Water temperature measured value				
	dohi	DO % saturation measured value				
	Oxygen partial pressure measured value					
	nc8P	Sensor cap serial number				

Data Clear Group

Character	Setting Item, Setting Range	Factory Default	Data
ことうと	Data clear selection	Calibration value	
∈RL□	⊏≅ಓ⊞ : Calibration value		
	<i>'¬E「</i> □ : Set value		
cLr[]	Data clear Stop/Perform	Data clear Stop	
no	ם : Data clear Stop		
	ゴミっ : Data clear Perform		

Error Codes

The following error codes are indicated on the Temperature Display.

Error Code	Description	Occurrence
Err0	Non-volatile IC memory error	Constantly
Err I	DO Sensor communication errors have occurred, or DO Sensor is	When
	not connected.	measuring
	After a command is sent to the DO Sensor, if there is no response	and calibrating
	for 500 ms, the command will be sent again.	
	If no response occurs 4 times consecutively, this error code will be	
	displayed.	
	If communication status returns to normal, the unit will automatically	
	return to normal status.	
	When this error code is displayed, the previous measured value is	
	retained.	
ErrZ	DO Sensor cap is not attached, or it is incorrectly attached.	
Err3	Calibration error (when input errors have occurred, or when calibra-	When
	tion cannot be performed 30 minutes after starting calibration)	calibrating
Erry	DO Sensor internal memory deletion.	When
	Displayed when Quality ID3 is received from the DO Sensor.	measuring
		and calibrating

14. Key Operation Flowchart Abbreviations: Meas. value: Measured value, DO: Dissolved oxygen, Temp: Temperature, Calib: Calibration, Adjust: Adjustment, C. Desired vaue: Concentration desired value, Trans: Trans **POWER ON** Trans: Transmission **Display Mode or Cleansing Output Mode (*1)** Meas.value (*2) DO % Saturation/ DO Concentration / Meas.value (*2) Meas.value (*2) Oxygen Partial Pressure / Meas.value (*3) Temp. Display Mode Meas.value (*3) Temp. Display Mode Meas.value (*3) Temp. Display Mode **DO Concentration** SET_ RESET RESET Meas.value (*2) Meas.value (*4) 1-point calibration [-] [-] |-| *|*|-| (100% saturation calib.) 1-point Calib. Mode (P.41) **√** Meas.value (*2) **DO Concentration** Meas.value (*4) 1st-point calibration (*5) i-*2*-|-*|*2|-(100% saturation calib.) 2-point Calib. Mode (P.43) SET RESET 2nd-point calibration Meas.value (*4) 1-2-(0-point calibration) cAdi SET____ RESET **Concentration Option** Meas.value (*4) **Concentration Option** -|-|-|-C.Desired value **Calibration Mode Auto Calibration** (P.45) **SEE** (3 sec) Meas.value (*2) **Forced Cleansing** Automatically proceeds after cleansing action Meas.value (*3) Mode (P.54) + set (3 sec) SET___ RESET **Transmission output Transmission output** 000 1 Zero adjust. (P.47) 1 Span adjust. (P.47) RUNZ →+ ₩ (3 sec) RUEZ SET____ RESET Transmission output Transmission output]0,00 2 Zero adjust. (P.48) 2 Span adjust. (P.48) F.n.c.[**DO Concentration** Γ.σ. I **Transmission** ſ.r.a.2 **Transmission Input Group Output 1 Group Output 2 Group** SET___ RESET RESET <u>dF</u>e1 Trol Trod Signal output Transmission output Transmission output ___50 do III do III response time (P.23) 1 type (P.24) 2 type (P.25) Salinity correction $\Gamma - H I$ Transmission output [-HZ Transmission output 20.00 2000 (P.23) 1 high limit (P.24) 2 high limit (P.25) SET___ RESET SET___ RESET RESET , [O <u> SERL</u> 1-L 1 [r.[2 Transmission output Altitude correction Transmission output 0.00 0.00 1 low limit (P.24) 2 low limit (P.25)(P.23)

About Setting Item

RESET.

Signal output response time (P.23)

• **Upper left**: DO Display: Indicates the setting item characters. • **Lower left**: Temperature Display: Indicates the factory default. • **Right side**: Indicates the setting item and reference page.

RESET

SET___ RESET

Trans. output 2 status

when calibrating (P.25)

Trans. output 2 value

HOLD when calibrating

(P.25)

[--2

BEFH

0.00

E.H.T.3 EVT3 Action
Group

Setting item in shaded section will be displayed only when the corresponding option is ordered.

(P.24)

Trans. output 1 status

when calibrating (P.24)

Trans. output 1 value

HOLD when calibrating

SET_ RESET

[-<u>-</u> |

BEFH

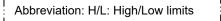
]0,00

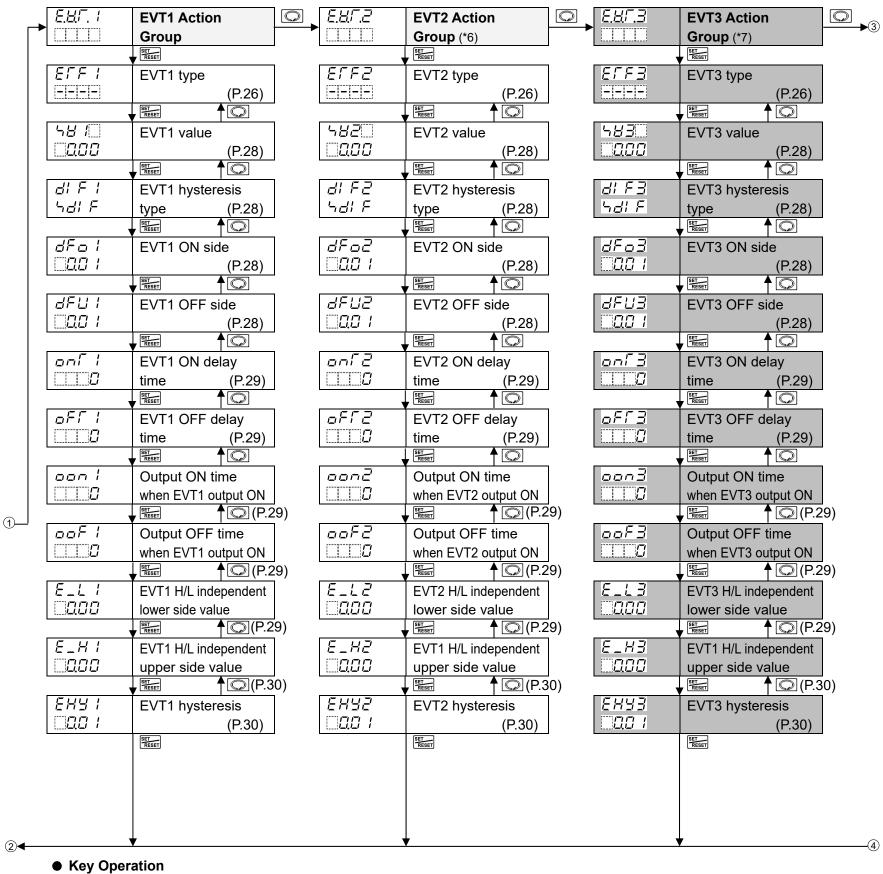
^(*1) In Cleansing Output Mode, the measured value (DO concentration, DO % saturation, Oxygen partial pressure, temperature) is held during cleansing action (using 'Cleansing time' and 'Standby after cleansing').

^(*2) Indicates the measured value of DO concentration, DO % saturation or Oxygen partial pressure.

^(*3) Indicates temperature measured value. (*4) During calibration, DO concentration measured value flashes.

^(*5) If errors occur during 1st-point calibration (100% saturation calibration) in 2-point Calibration Mode, the unit will revert to the Display Mode or Cleansing Output Mode by pressing the or key.



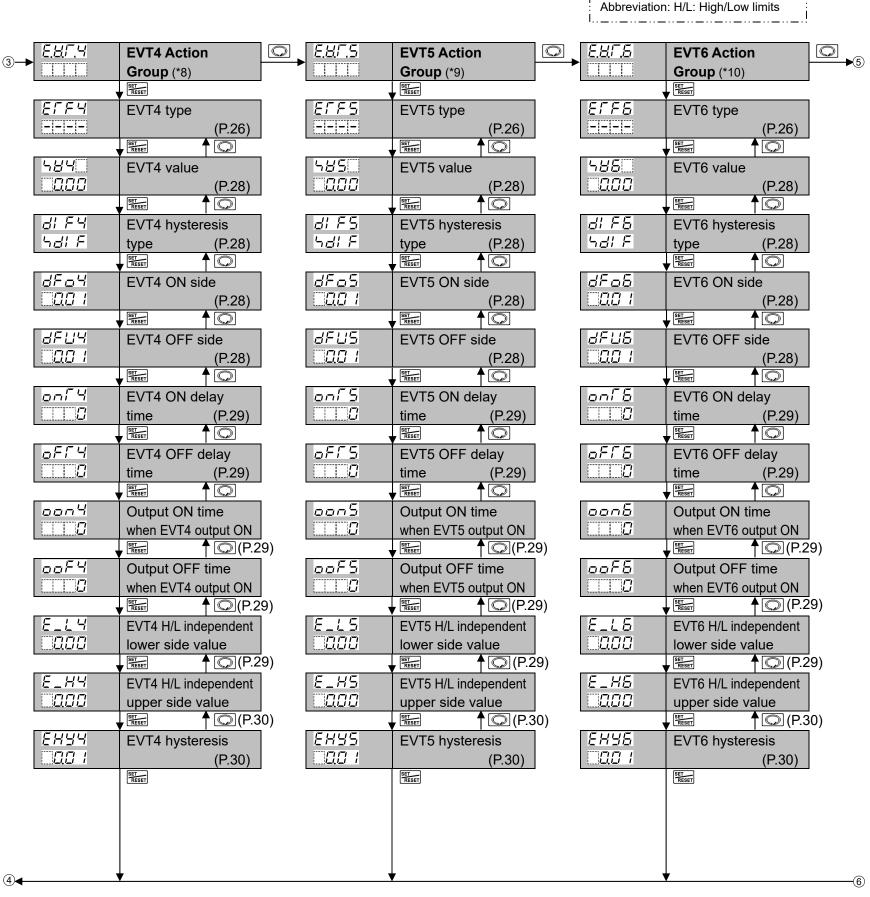


- 🛆, Ö, 🖼 Press the 🛆, O or 🖼 key. The unit will proceed to the next setting item, illustrated by an arrow.
- 🖂 + 🖾 (3 sec): Press and hold the 🖾 and 🖾 keys (in that order) together for 3 seconds. The unit will proceed to the next mode.
- 🚟 (3 sec), 🔘 (3 sec): Press the 🖼 or 🔘 key for 3 seconds. The unit will proceed to the next setting item, illustrated by an arrow.
- 🗀 + 🚟 (3 sec): Press and hold the 🖾 and 🖼 keys (in that order) together for 3 seconds. The unit will proceed to the next mode.
- 🖂 + 🚟 (3 sec): Press and hold the 🖾 and 🚟 keys (in that order) together for 3 seconds. The unit will proceed to the next mode.
- To set each item, use the \triangle or ∇ key, and register the set value with the key.
- If the 🔘 key is pressed for 3 seconds at any setting item, the unit will revert to Display Mode or Cleansing Output Mode.
- (*6) Action, indication condition and setting range of the EVT2 Action Group are the same EVT1 Action Group.

(*7) Action, indication condition and setting range of the EVT3 Action Group are the same EVT1 Action Group.

Substitute EVT1 character (l) with EVT2 character (L). Refer to EVT1 Action Group (pp. 26 to 30).

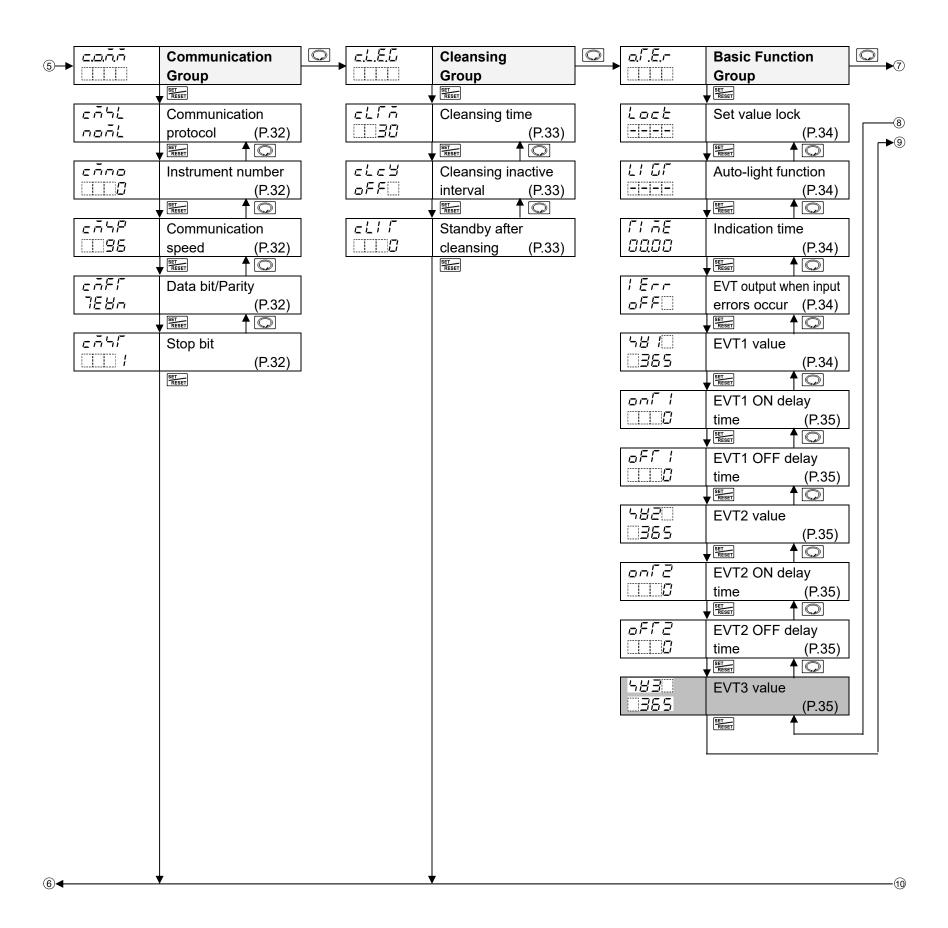
Substitute EVT1 character ($\frac{1}{2}$) with EVT3 character ($\frac{1}{2}$). Refer to EVT1 Action Group (pp. 26 to 30).

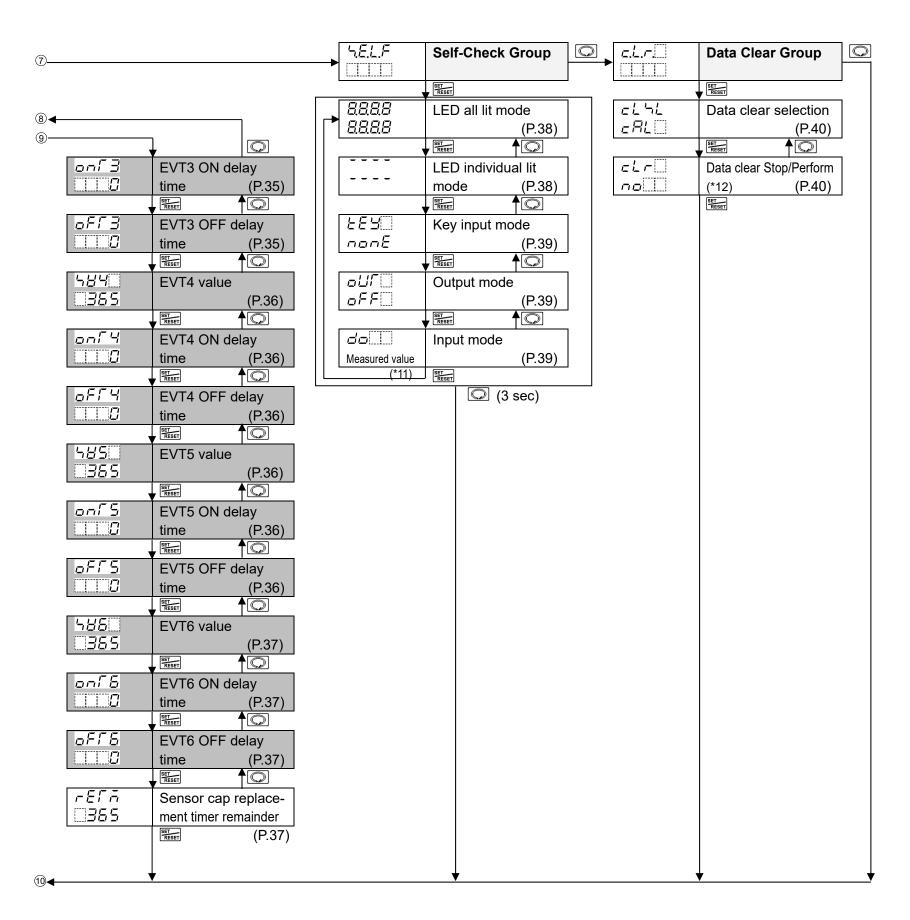


^(*8) Action, indication condition and setting range of the EVT4 Action Group are the same EVT1 Action Group. Substitute EVT1 character (') with EVT4 character ('). Refer to EVT1 Action Group (pp. 26 to 30).

^(*9) Action, indication condition and setting range of the EVT5 Action Group are the same EVT1 Action Group. Substitute EVT1 character ('1) with EVT5 character (5). Refer to EVT1 Action Group (pp. 26 to 30).

^(*10) Action, indication condition and setting range of the EVT6 Action Group are the same EVT1 Action Group. Substitute EVT1 character ($\frac{1}{2}$) with EVT6 character ($\frac{5}{2}$). Refer to EVT1 Action Group (pp. 26 to 30).





^(*11) Indicates DO concentration measured value.

^(*12) Depending on the selection in [Data clear Stop/Perform], the unit operates as follows.

If 'Data clear Stop' is selected, data will not be cleared. The unit will revert to the mode prior to Data clear Stop (either Display Mode or Cleansing Output Mode).

If 'Data clear Perform' is selected, data will be cleared. The unit will revert to the mode prior to Data clear Perform (either Display Mode or Cleansing Output Mode). (While data is being cleared, all indications are momentarily unlit.)

15. Maintenance

15.1 Maintenance

- Please perform the following maintenance procedure every month.
- Clean the measurement section with tap water.
- Check that the measurement section is not damaged or deteriorated.
- Check that DO Sensor cable is not damaged or deteriorated.
- · Check that installation devices are not corroded.

15.2 Periodic Inspection

- Please check the following items every 3 months.
- The DO meter (WIL-102-DO) is securely fixed in place.
- Check that the DO meter (WIL-102-DO) is not damaged.
- · Check that screws in the terminal block are not rusty.

15.3 Replacement of Consumables (Maintenance Parts)

■ Purchase new sensor cap (DOS-CP), and replace one (1) year after installation (Recommended).

15.4 Calibration

■ The DO meter (WIL-102-DO) is designed to be used for a long period of time, however, calibrate it at least once a year to maintain measurement reliability.

See Section "8. Calibration" (p.41).

15.5 Long-Term Storage

- When the DO meter (WIL-102-DO) and DO Sensor are not used for a long period of time, store them as follows.
- Disconnect the power from the mains electricity.
- Pull the DO Sensor out of the water, and clean it.
- Store the DO meter (WIL-102-DO) and DO Sensor away from direct sunlight.

16. Reference Chart

Amount of saturated DO in water at each temperature (At an atmospheric pressure 1, Salinity concentration 0 PSU)

Temper- ature (°C)	Amount of saturated DO (mg/L)	Temper- ature (°C)	Amount of saturated DO (mg/L)	Temper- ature (°C)	Amount of saturated DO (mg/L)	Temper- ature (℃)	Amount of saturated DO (mg/L)
1	14.22	11	11.03	21	8.92	31	7.43
2	13.83	12	10.78	22	8.74	32	7.31
3	13.46	13	10.54	23	8.58	33	7.18
4	13.11	14	10.31	24	8.42	34	7.07
5	12.77	15	10.08	25	8.26	35	6.95
6	12.45	16	9.87	26	8.11	36	6.84
7	12.14	17	9.67	27	7.97	37	6.73
8	11.84	18	9.47	28	7.83	38	6.62
9	11.56	19	9.28	29	7.69	39	6.52
10	11.29	20	9.09	30	7.56	40	6.41

JIS K 0102-2016

***** Inquiries *****

For any inquiries about this unit, please contact our agency or the vendor where you purchased the unit after checking the following.

	[Example]
• Model	 WIL-102-DO
 Serial number 	 No. 194F05000

In addition to the above, please let us know the details of the malfunction, or discrepancy, and the operating conditions.

SHINKO TECHNOS CO., LTD. OVERSEAS DIVISION

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