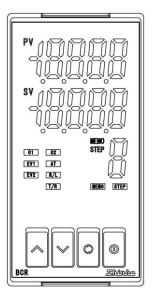
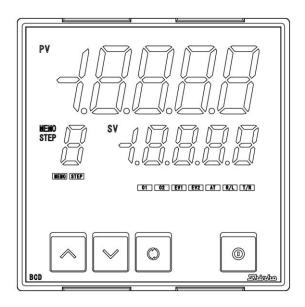
BCx2 INSTRUCTION MANUAL







Shinko

Preface

Thank you for purchasing our digital indicating controller BCx2 (BCS2, BCR2, BCD2). This manual contains instructions for the mounting, functions, operations and notes when operating the BCx2. To prevent accidents arising from the misuse of this controller, please ensure the operator receives this manual.

Abbreviations used in this manual

Abbreviation	Term
PV	Process variable
SV	Desired value
MV	Manipulated variable
DV	Deviation
OUT1	Control output OUT1
OUT2	Control output OUT2
AT	Auto-tuning

Characters used in this manual

Indication	-/-		1	Ē	3	4	5	5	7	8	3	Γ	F
Number, °C/°F	-1	0	1	2	3	4	5	6	7	8	9	$^{\circ}$	${}^{\circ}\!\mathrm{F}$
Indication	R	Ь	E	ď	Ε	F		Н	-	ij	E	L) į
Alphabet	Α	В	С	D	Е	F	G	Н	I	J	K	L	М
Indication	Π	۵	P	9	<i>_</i>	4	5	Ш	Ħ	ū	ü	占	111
Alphabet	Ν	0	Р	Q	R	S	Т	U	V	W	Χ	Υ	Z

Notes

- This instrument should be used in accordance with the specifications described in the manual. If it is not used according to the specifications, it may malfunction or cause a fire.
- Be sure to follow the warnings, cautions and notices. If they are not observed, serious injury or malfunction may occur.
- The contents of this instruction manual are subject to change without notice.
- Care has been taken to ensure that the contents of this instruction manual are correct, but if there are any doubts, mistakes or questions, please inform our sales department.
- This instrument is designed to be installed through a control panel indoors. If it is not, measures must be taken to ensure that the operator cannot touch power terminals or other high voltage sections.
- Any unauthorized transfer or copying of this document, in part or in whole, is prohibited.
- Shinko Technos Co., Ltd. is not liable for any damage or secondary damage(s) incurred as a result of using this product, including any indirect damage.

Safety Precautions (Be sure to read these precautions before using our products.)

The safety precautions are classified into categories: "Warning" and "Caution". Depending on circumstances, procedures indicated by riangle Caution may result in serious consequences, so be sure to follow the directions for usage.



Procedures which may lead to dangerous conditions and cause death or serious injury, if not carried out properly.



Procedures which may lead to dangerous conditions and cause superficial to medium injury or physical damage or may degrade or damage the product, if not carried out properly.



Warning

- To prevent an electrical shock or fire, only Shinko or qualified service personnel may handle the inner assembly.
- To prevent an electrical shock, fire, or damage to instrument, parts replacement may only be undertaken by Shinko or qualified service personnel.



Safety Precautions

- To ensure safe and correct use, thoroughly read and understand this manual before using this instrument.
- This instrument is intended to be used for industrial machinery, machine tools and measuring equipment. Verify correct usage after purpose-of-use consultation with our agency or main office. (Never use this instrument for medical purposes with which human lives are involved.)
- External protection devices such as protective equipment against excessive temperature rise, etc. must be installed, as malfunction of this product could result in serious damage to the system or injury to personnel. Proper periodic maintenance is also required.
- This instrument must be used under the conditions and environment described in this manual.
 Shinko Technos Co., Ltd. does not accept liability for any injury, loss of life or damage occurring due to the instrument being used under conditions not otherwise stated in this manual.

Warning on Model Label



Caution

Failure to handle this instrument properly may result in minor or moderate injury or property damage due to fire, malfunction, malfunction, or electric shock. Please read this manual before using the product to ensure that you fully understand the product.



Caution with Respect to Export Trade Control Ordinance

To avoid this instrument from being used as a component in, or as being utilized in the manufacture of weapons of mass destruction (i.e. military applications, military equipment, etc.), please investigate the end users and the final use of this instrument.

In the case of resale, ensure that this instrument is not illegally exported.

Precautions for Use

1. Installation Precautions



Caution

This instrument is intended to be used under the following environmental conditions (IEC61010-1): Overvoltage category $\, \mathbb{I} \,$, Pollution degree 2

Ensure the mounting location corresponds to the following conditions:

- A minimum of dust, and an absence of corrosive gases
- · No flammable, explosive gases
- · No mechanical vibrations or shocks
- No exposure to direct sunlight, an ambient temperature of -10 to 55° C (14 to 131°F) that does not change rapidly, and no icing
- An ambient non-condensing humidity of 35 to 85 %RH
- No large capacity electromagnetic switches or cables through which large current is flowing
- No water, oil or chemicals or where the vapors of these substances can come into direct contact with the unit
- Please note that the ambient temperature of this unit not the ambient temperature of the control panel must not exceed 55°C (131°F) if mounted through the face of a control panel, otherwise the life of electronic components (especially electrolytic capacitors) may be shortened.

Note • Avoid setting this instrument directly on or near flammable material even though the case of this instrument is made of flame-resistant resin.

2. Wiring Precautions



Caution

- Do not leave wire remnants in the instrument, as they could cause a fire or malfunction.
- Use the solderless terminal with an insulation sleeve in which the M3 screw fits when wiring the instrument.
- The terminal block of this instrument is designed to be wired from the left side. The lead wire must be inserted from the left side of the terminal, and fastened with the terminal screw.
- Tighten the terminal screw using the specified torque. If excessive force is applied to the screw when tightening, the terminal screw or case may be damaged.
- Do not pull or bend the lead wire on the terminal side when wiring or after wiring, as it could cause malfunction.
- When using a terminal cover for the BCS2, pass terminal wires numbered 7 to 12 into the holes of the terminal cover.
- This instrument does not have a built-in power switch, circuit breaker and fuse. It is necessary to install a power switch, circuit breaker and fuse near the controller. (Recommended fuse: Time-lag fuse, rated voltage 250 V AC, rated current 2 A)
- For a 24 V AC/DC power source, do not confuse polarity when using direct current (DC).
- Do not apply a commercial power source to the sensor which is connected to the input terminal nor allow the power source to come into contact with the sensor.
- Use a thermocouple and compensating lead wire according to the sensor input specifications of this controller.
- Use the 3-wire RTD according to the sensor input specifications of this controller.
- For DC voltage input, (+) side input terminal number of 0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC differs from that of 0 to 1 V DC.

Model	Terminal Number
BCS2	(9): (+) side of 0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC
	(0): (+) side of 0 to 1 V DC
BCR2, BCD2	②: (+) side of 0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC
	②: (+) side of 0 to 1 V DC

- When using a relay contact output type, externally use a relay according to the capacity of the load to protect the built-in relay contact.
- When wiring, keep input wires (thermocouple, RTD, etc.) away from controller AC power sources or load wires.

3. Operation and Maintenance Precautions



Caution

- It is recommended that AT be performed on the trial run.
- Do not touch live terminals. This may cause electrical shock or problems in operation.
- Turn the power supply to the instrument OFF when retightening the terminal or cleaning. Working on or touching the terminal with the power switched ON may result in severe injury or death due to electrical shock.
- Use a soft, dry cloth when cleaning the instrument. (Alcohol based substances may tarnish or deface the unit.)
- As the display section is vulnerable, be careful not to put pressure on, scratch or strike it with a hard object.

4. Compliance with Safety Standards



Caution

- Always install the recommended fuse described in this manual externally.
- If the instrument is used in a manner not specified by the manufacturer, the protection provided by the instrument may be impaired.
- Use a device with reinforced insulation or double insulation for the external circuit connected to this product.
- When using this product as a UL certified product, use a power supply conforming to Class 2 or LIM for the external circuit connected to the product.

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1. Model

1.1 Model

	B C□2									
	BCS2						48 x 48 x 68	mm (W x H x D) (Depth of control panel interior: 60)		
Size	BCR2						48 x 96 x 68	mm (W x H x D) (Depth of control panel interior: 60)		
	BCD2						96 x 96 x 68	mm (W x H x D) (Depth of control panel interior: 60)		
Caratral	44	R					Relay contac	et: 1a		
Control OUT1	output	S					Non-contact	voltage (for SSR drive) 12 V DC±15%		
0011		Α					Direct curren	t: 4 to 20 mA DC		
Power s	supply		0				100 to 240 V	100 to 240 V AC (Standard)		
voltage			1				24 V AC/DC	24 V AC/DC		
Input				0			Multi-range (*1)		
					0			No Option 1 needed.		
					1		EV2	Event output EV2 (*3)		
					2		DS	Heating/Cooling control output OUT2, Non-contact voltage		
					3		DA	Heating/Cooling control output OUT2, Direct current		
Ontion	1 (*0)				4		P24	Insulated power output		
Option (Change	e only one	a ant	ion \		5		EV2+DR(*4)	Event output EV2 (*3) + Heating/Cooling control		
(Choose	e Offig Office	e opi	1011.)					output OUT2, Relay contact		
					6		EV2+DS(*4)	Event output EV2 (*3) + Heating/Cooling control		
								output OUT2, Non-contact voltage		
					7		EV2+DA(*4)	Event output EV2 (*3) + Heating/Cooling control		
								output OUT2, Direct current		
'			0		No Option 2 needed.					
						1	C5W (20A)	Event input (2 points) (*5) + Serial communication +		
								Heater burnout alarm (20A) (*6)		
						2	C5W (100A)	Event input (2 points) (*5) + Serial communication +		
								Heater burnout alarm (100A) (*6)		
						3	EIW (20A)	Event input (2 points) +		
0	2 (#6)							Heater burnout alarm (20A) (*6)		
Option 2		1	· \			4	EIW (100A)	Event input (2 points) +		
(Choose	(Choose only one option.)					Heater burnout alarm (100A) (*6)				
5			5	EIT (*4)	Event input (2 points) (*7)+					
					External setting input + Transmission output					
			6	C5	Serial communication					
	7					7	W (20A)	Heater burnout alarm (20 A) (*6)		
8					8	W (100A) Heater burnout alarm (100 A) (*6)				
						9	El Event input (2 points)			

- (*1) Thermocouple, RTD, Direct current and DC voltage can be selected by keypad.
- (*2) Only one option can be selected from Option 1 and Option 2 respectively.
- (*3) Event output EV1 is standard.

The following outputs can be selected in [Event output EV1/EV2 allocation] by keypad:

Alarm output (12 alarm types and No alarm action), Heater burnout alarm output, Loop break alarm output, Time signal output, Output during AT, Pattern end output, Output by communication command, Heating/Cooling control output OUT2 (for EV2 option only).

For Event output EV1/EV2, Heater burnout alarm output and Output by communication command are available when C5W, EIW, C5 or W option is ordered.

- (*4) When EV2+D□ option and EIT option are added simultaneously, Transmission output terminals are used for EV2 output, so Transmission output is disabled. For the BCS2, EV2+D□ cannot be selected.
- (*5) For the BCS2, Event input (2 points) is not available.
- (*6) For direct current output type, Heater burnout alarm does not work. CT (Current Transformer) are sold separately.
- (*7) For the BCS2, 1 point of Event input is available.

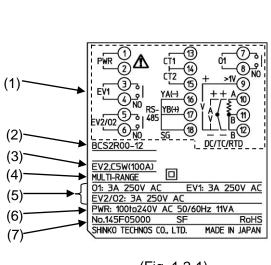
1.2 How to Read the Model Label

The model label is attached to the right side of the case.

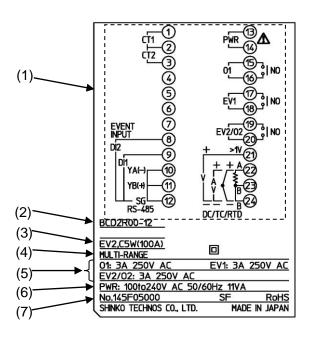
BCS2 (e.g.) BCS2R00-12

BCR2, BCD2

(e.g.) BCD2R00-12



(Fig. 1.2-1)



(Fig. 1.2-2)

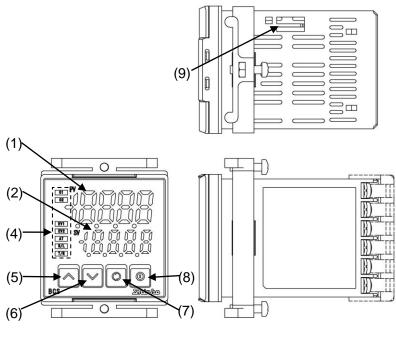
No.	Description	Example
(1)	Terminal arrangement	BCS2R00-12, BCD2R00-12 (*1)
(2)	Model	BCS2R00-12, BCD2R00-12
(3)	Option	EV2 (Event output EV2)
		C5W(100A) [Serial communication + Heater burnout
		alarm (100 A)] (*2)
(4)	Input	MULTI-RANGE (Multi-range input)
(5)	Control output, Event output	O1: 3 A 250 V AC (Control output OUT1)
		EV1: 3 A 250 V AC (Event output EV1)
		EV2: 3 A 250 V AC (Event output EV2)
(6)	Power supply voltage,	100 to 240 V AC 50/60 Hz,
	Power consumption	11 VA
(7)	Serial number	No. 145F05000

^(*1) Terminal arrangement diagram differs depending on the model.

^(*2) For Heater burnout alarm output (C5W, EIW, W options), CT rated current is entered in bracket ().

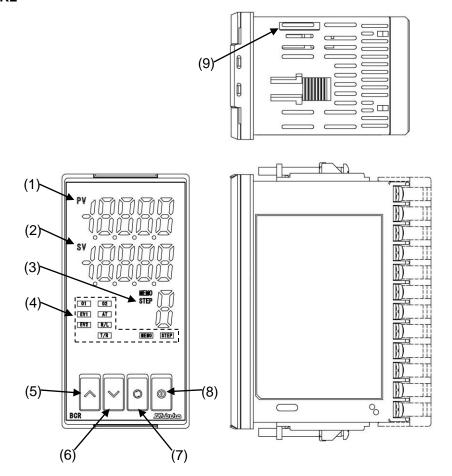
2. Names and Functions of Controller

BCS2

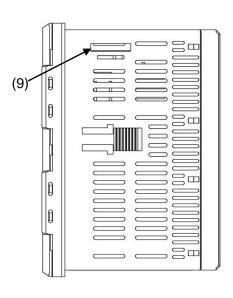


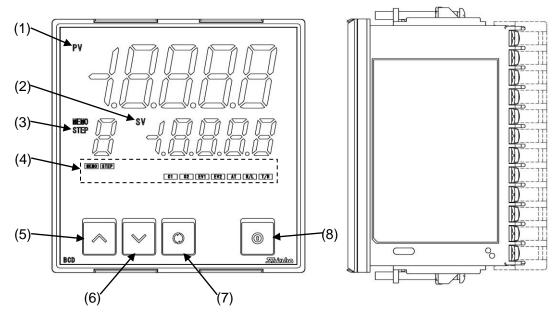
(Fig. 2-1)

BCR2



(Fig. 2-2)





(Fig. 2-3)

Display

No.	Name	Description					
(1)	PV Display	Indicates PV.	Indicates PV.				
		Indicates setting	g characters in each setting mode.				
(2)	SV Display	Indicates SV.					
		Indicates the se	t data in each setting mode.				
		In Monitor mode	e, indicated contents differ depending on the model as				
		follows.	follows.				
		Model	Indicated Contents				
		BCS2	, , , , , , , , , , , , , , , , , , , ,				
		number (Program control) or Set value memory number					
		(Fixed value control).					
		BCR2, BCD2	BCR2, BCD2 Indicates MV or Remaining time (Program control).				
(3)	MEMO/STEP	Indicates Set value memory number (Fixed value control) or Step number					
	Display	(Program contro	ol). (For BCR2, BCD2)				

Action Indicators

No.	Name	Description				
(4)	O1 (Green)	Lit when control output OUT1 is ON.				
		For direct current output type, flashes corresponding to the MV in 125 ms				
		cycles.				
	O2 (Yellow)	Lit when control output OUT2 (EV2, DS, DA, EV2+D□ options) is ON.				
		For direct current output type (DA option), flashes corresponding to the MV				
		in 125 ms cycles.				
	EV1 (Red)	Lit when Event output EV1 is ON.				
	EV2 (Red)	Lit when Event output EV2 (EV2, EV2+D□ options) is ON.				
		Unlit if \$\Bar{\Bar{\Bar{\Bar{\Bar{\Bar{\Bar{				
		[Event output EV2 allocation].				
	AT (Yellow)	Flashes while AT, 'AT on startup' or Auto-reset is performing.				
	R/L (Yellow)	Lit during Remote action, selected in [Remote/Local] (EIT option).				
	T/R (Yellow)	Lit during Serial communication (C5W, C5 options) TX (transmitting) output				
	MEMO	Lit when Set value memory number (Fixed value control) is indicated.				
	(Yellow)	(For BCR2, BCD2)				
	STEP (Green)	Lit when a step number (Program control) is indicated. (For BCR2, BCD2)				

Key

No.	Name		Description			
(5)	UP key	Increases the numeric value.				
		By pressing this key for 1 secon	d during Program control, the performing			
		step is interrupted, proceeding t	o the beginning of the next step. (Advance			
		function)				
(6)	DOWN key	Decreases the numeric value.				
(7)	MODE key	Switches a setting mode, and registers the set data.				
		By pressing this key for 3 seconds during RUN mode, the unit enters				
		Monitor mode.				
(8)	OUT/OFF key	By pressing the @ key for approx. 1 second, one of the following items				
		selected in [OUT/OFF key function] is activated.				
		OUT/OFF Key Function Description				
		Control output OFF function	Turns control output ON or OFF.			
		Auto/Manual control	Switches the Auto/Manual control.			
		Program control	Starts/Stops the Program control.			

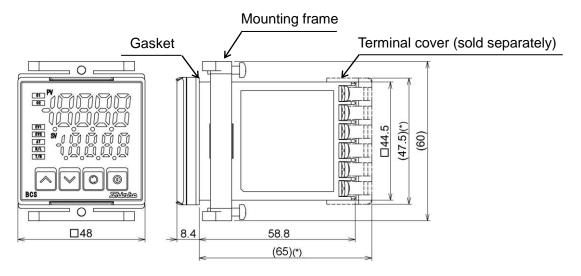
Console Connector

	• • • • • • • • • • • • • • • • • • • •	
No.	Name	Description
(9)	Console	By connecting the tool cable (CMD-001, sold separately), the following
	connector	operations can be conducted from an external computer using the Console software SWC-BCx01M.
		Reading and setting of SV, PID and various set values
		Reading of PV and action status
		Function change

3. Mounting to the Control Panel

3.1 External Dimensions (Scale: mm)

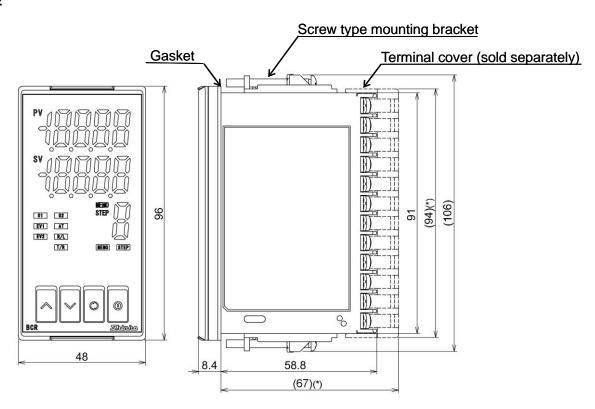
BCS2



(*) When the terminal cover is used.

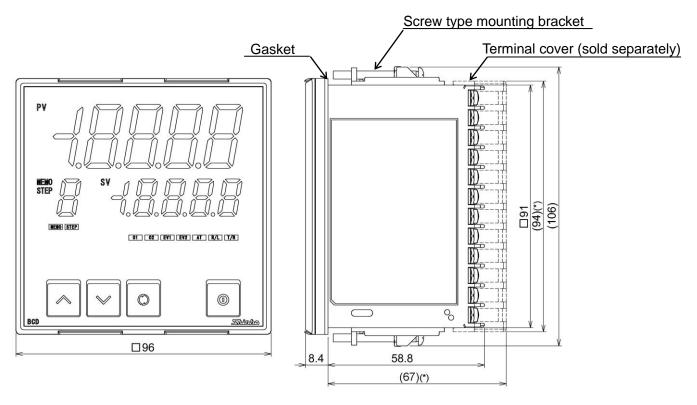
(Fig. 3.1-1)

BCR2



(*) When the terminal cover is used.

(Fig. 3.1-2)



(*) When terminal covers are used.

(Fig. 3.1-3)

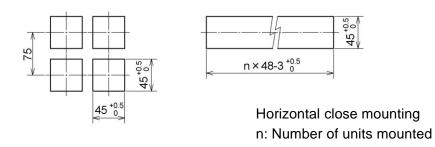
3.2 Panel Cutout (Scale: mm)



Caution

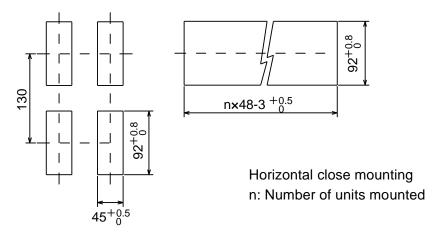
If horizontal close mounting is used for the controller, IP66 specification (Drip-proof/Dust-proof) may be compromised, and all warranties will be invalidated.

BCS2



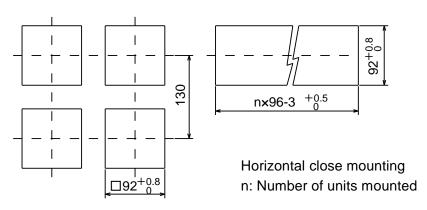
(Fig. 3.2-1)

BCR2



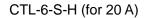
(Fig. 3.2-2)

BCD2

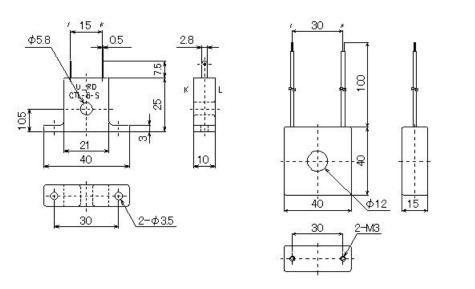


(Fig. 3.2-3)

3.3 CT External Dimensions (Scale: mm)







(Fig. 3.3-1)

3.4 Mounting to, and Removal from, the Control Panel



Caution

As the mounting frame of the BCS2 is made of resin, do not use excessive force while tightening screws, or the mounting frame could be damaged.

Tighten screws with one rotation upon the screw tips touching the panel.

The torque is 0.05 to 0.06 N·m.

For the BCR2, BCD2, the torque should be 0.1 N·m.

3.4.1 How to Mount the Unit

BCS2

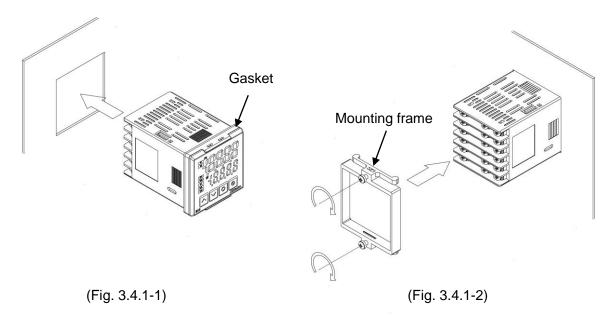
Mount the controller vertically to the flat, rigid panel to ensure it adheres to the Drip-proof/Dust-proof specification (IP66).

If the lateral close mounting is used for the controller, IP66 specification (Drip-proof/Dust-proof) may be compromised, and all warranties will be invalidated.

Mountable panel thickness: 1 to 5 mm

- (1) Insert the controller from the front side of the control panel. (Fig. 3.4.1-1)

 If the Drip-proof/Dust-proof specification (IP66) is not necessary, the gasket may be removed (Please keep in mind the warranty is void if gasket is removed).
- (2) Insert the mounting frame until it comes into contact with the panel, and fasten with screws. Tighten screws with one rotation upon the screw tips touching the panel. (Fig. 3.4.1-2) The torque is 0.05 to 0.06 N•m.



BCR2, BCD2

Mount the controller vertically to the flat, rigid panel to ensure it adheres to the Drip-proof/Dust-proof specification (IP66).

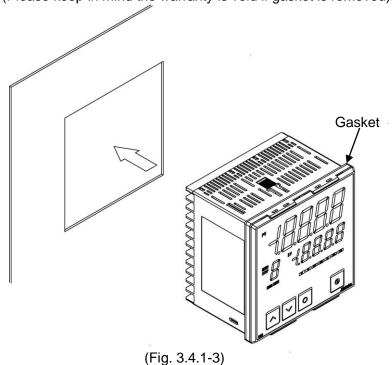
If the lateral close mounting is used for the controller, IP66 specification (Drip-proof/Dust-proof) may be compromised, and all warranties will be invalidated.

Mountable panel thickness: 1 to 7 mm

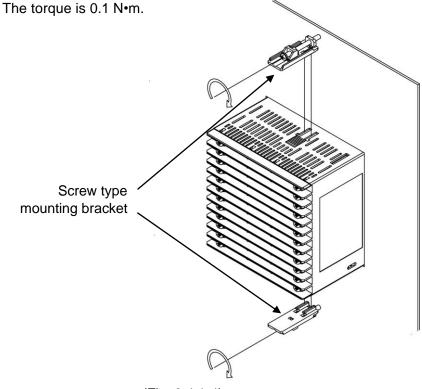
(1) Insert the controller from the front side of the control panel. (Fig. 3.4.1-3)

If the Drip-proof/Dust-proof specification (IP66) is not necessary, the gasket may be removed.

(Please keep in mind the warranty is void if gasket is removed).



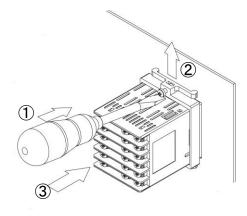
(2) Attach the mounting brackets by the slots at the top and bottom of the case, and secure the controller in place with the screws.



3.4.2 How to Remove the Mounting Frame and Unit

BCS2 (Fig. 3.4.2-1)

- (1) Turn the power to the unit OFF, and disconnect all wires before removing the mounting frame.
- (2) Insert a flat blade screwdriver between the mounting frame and unit (1).
- (3) Slowly push the frame upward using the screwdriver ($^{\textcircled{2}}$), while pushing the unit toward the panel ($^{\textcircled{3}}$).
- (4) Repeat step (2) and slowly push the frame downward using the screwdriver for the other side. The frame can be removed little by little by repeating these steps.



(Fig. 3.4.2-1)

BCR2, BCD2

- (1) Turn the power to the unit OFF, and disconnect all wires before removing the unit.
- (2) Loosen the screws of the mounting brackets, and remove the mounting brackets.
- (3) Pull the unit out from the front of the control panel.

4. Wiring



${ m !} ackslash$ Warning

Turn the power supply to the instrument off before wiring or checking.

Working on or touching the terminal with the power switched on may result in severe injury or death due to electrical shock.



🚹 Caution

- Do not leave wire remnants in the instrument, as they could cause a fire or malfunction.
- Use the solderless terminal with an insulation sleeve in which the M3 screw fits when wiring the instrument.
- The terminal block of this instrument is designed to be wired from the left side. The lead wire must be inserted from the left side of the terminal, and fastened with the terminal screw.
- Tighten the terminal screw using the specified torque. If excessive force is applied to the screw when tightening, the terminal screw or case may be damaged.
- Do not pull or bend the lead wire on the terminal side when wiring or after wiring, as it could cause malfunction.
- When using a terminal cover for the BCS2, pass terminal wires numbered 7 to 12 into the holes of the terminal cover.
- This instrument does not have a built-in power switch, circuit breaker and fuse. It is necessary to install a power switch, circuit breaker and fuse near the controller. (Recommended fuse: Time-lag fuse, rated voltage 250 V AC, rated current 2 A)
- For a 24 V AC/DC power source, do not confuse polarity when using direct current (DC).
- Do not apply a commercial power source to the sensor which is connected to the input terminal nor allow the power source to come into contact with the sensor.
- · Use a thermocouple and compensating lead wire according to the sensor input specifications of this controller.
- Use the 3-wire RTD according to the sensor input specifications of this controller.
- For DC voltage input, (+) side input terminal number of 0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC differs from that of 0 to 1 V DC.

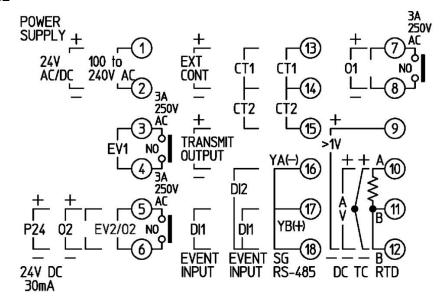
Model	Terminal Number
BCS2	9: (+) side of 0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC
	①: (+) side of 0 to 1 V DC
BCR2, BCD2	②: (+) side of 0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC
	②: (+) side of 0 to 1 V DC

- When using a relay contact output type, externally use a relay according to the capacity of the load to protect the built-in relay contact.
- When wiring, keep input wires (thermocouple, RTD, etc.) away from AC sources or load wires.

4.1 Terminal Arrangement

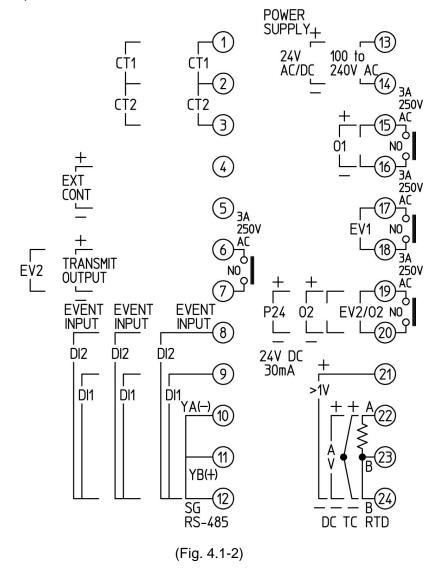
Terminal arrangement of the BCS2, BCR2, BCD2 differs depending on the options as follows.

BCS2



(Fig. 4.1-1)

BCR2, BCD2

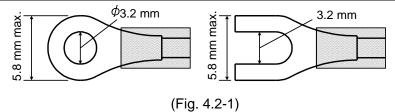


Terminal	Description		
POWER SUPPLY	100 to 240 V AC or 24 V AC/DC		
	For a 24 V AC/DC power source, do not confuse polarity when using		
	direct current (DC).		
EV1	Event output E\	/1	
EV2	Event output E\	$\sqrt{2}$ (EV2, EV2+D□ options)	
O2	Control output 0	DUT2 (EV2, DS, DA, EV2+D□ options)	
P24	24 V DC insulat	ed power output (P24 option)	
O1	Control output 0	DUT1	
RTD	RTD input		
TC	Thermocouple i	nput	
DC	Direct current, [DC voltage inputs	
	For DC voltag	e input, (+) side input terminal number of 0 to 5 V DC, 1 to	
	5 V DC, 0 to 1	0 V DC differs from that of 0 to 1 V DC.	
	Model	Terminal Number	
	BCS2	9: + side of 0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC	
		10: + side of 0 to 1 V DC	
	BCR2, BCD2	②: + side of 0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC	
		②: + side of 0 to 1 V DC	
CT1	CT input 1 (C5W, EIW, W options)		
CT2	CT input 2 (C5W, EIW, W options)		
RS-485	Serial communication RS-485 (C5W, C5 options)		
EVENT INPUT	Event input DI1 (BCS2: EIW, EIT, EI options,		
	BCR2/BCD2: C5W, EIW, EIT, EI options)		
	Event input DI2 (BCS2: EIW, EI options,		
	BCR2/BCD2: C5W, EIW, EIT, EI options)		
EXT CONT	External setting input (EIT option)		
TRANSMIT OUTPUT	Transmission output (EIT option) or Event output EV2 (EV2+D□ option)		
	BCR2, BCD2: If EV2+D□ option and EIT option are added simultaneously,		
	Transmission output terminals are used for EV2 output, so Transmission output		
	will be disabled.		

4.2 Lead Wire Solderless Terminal

Use a solderless terminal with an insulation sleeve in which an M3 screw fits as shown below. The torque should be $0.63~\text{N} \cdot \text{m}$.

Solderless Terminal	Manufacturer	Model	Tightening Torque
Vtuno	NICHIFU TERMINAL INDUSTRIES CO., LTD.	TMEX1.25Y-3	
Y-type	J.S.T.MFG.CO.,LTD.	VD1.25-B3A	0.00 Nissa
Ding topo	NICHIFU TERMINAL INDUSTRIES CO., LTD.	TMEX1.25-3	0.63 N•m
Ring-type	J.S.T.MFG.CO.,LTD.	V1.25-3	

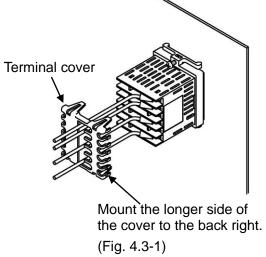


4.3 Terminal Cover

BCS2

When using a terminal cover (sold separately), make sure the longer side is on the back right side of the case.

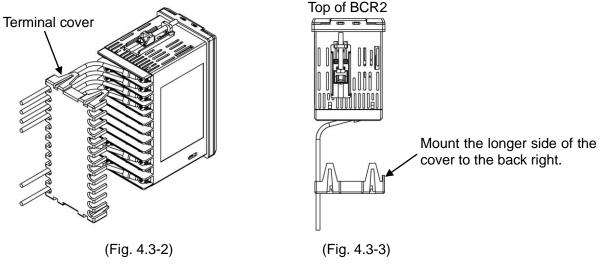
Pass the wires from terminals 7 to 12 into the holes of the terminal cover.



BCR2

When using a terminal cover (sold separately), make sure the longer side is on the back right side of the case.

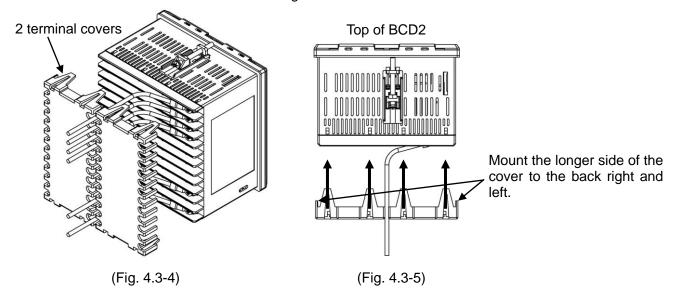
Pass the wires from terminals 13 to 24 through the left side of the terminal cover.



BCD2

When using terminal covers (sold separately), make sure the longer side is on the back right and left sides of the case.

Pass the wires from terminals 13 to 24 through between covers.



4.4 Wiring

For the terminal arrangement, refer to Section '4.1 Terminal Arrangement' (p.19).

4.4.1 Power Supply

Power supply voltage is 100 to 240 V AC or 24 V AC/DC.

For a 24 V AC/DC power source, ensure polarity is correct when using direct current (DC).

BCS2	BCR2, BCD2
PWR 2	PWR 13

4.4.2 Control Output OUT1, OUT2

When EV2, DS, DA or EV2+D□ option is ordered, control output OUT2 is available.

Specifications of Control output OUT1, OUT2 are shown below.

	output corr, core are enemi selem	
Relay contact	1a	
	Control capacity: 3 A 250 V AC (resistive load),	
	1 A 250 V AC (inductive load $\cos\phi$ =0.4)	
	Electrical life: 100,000 cycles	
	Minimum applicable load: 10 mA 5 V DC	
Non-contact voltage	12 V DC±15%	
(for SSR drive)	Max. 40 mA (short circuit protected)	
Direct current	4 to 20 mA DC	
	Load resistance: Max. 550 Ω	

BCS2		BCF	22, BCD2
Relay contact	Non-contact voltage, Direct current	Relay contact	Non-contact voltage, Direct current
EV2/02 5 0 NO	R +	01 NO	+ (5)
01 8 0 NO	+	EV2/02/20 NO	02

Number of Shinko SSR units when connected in parallel (for Non-contact voltage output):

SA-400 series: 5 unitsSA-500 series: 2 units

4.4.3 Input

Each input wiring is shown below.

For DC voltage input, (+) side input terminal number of 0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC differs from that of 0 to 1 V DC.

BCS2			
Thermocouple	RTD	Direct current, DC voltage (0 to 1 V)	DC voltage (0 to 5 V, 1 to 5 V, 0 to 10 V)
+ (1) (1) (1) (1) (1) (1) (1) (1) (1) (1)	A (1) (1) (2) RTD	+ LA > _ DC	+ 9 (0) v (1) - (12) DC

BCR2, BCD2			
Thermocouple	RTD	Direct current, DC voltage (0 to 1 V)	DC voltage (0 to 5 V, 1 to 5 V, 0 to 10 V)
†22 (23) 24 TC	A 22 W 23 B 23 RTD	#F4>JI B	무 + () () () ()

4.4.4 Event Output 1, Event Output 2

Event output EV1 is a standard feature.

If EV2 or EV2+D□ option is ordered, Event output EV2 is available.

Specifications of Event output 1 and Event output 2 are shown below.

Relay contact	1a
	Control capacity: 3 A 250 V AC (resistive load)
	1 A 250 V AC (inductive load $\cos\phi$ =0.4)
	Electrical life: 100,000 cycles
	Minimum applicable load: 10 mA 5 V DC

BCS2	В	CR2, BCD2
EV1 3 0	EV1 18 NO	
	For EV2 option	For EV2+D□ option
EV2/02 5 6 NO	EV2/02 19 NO	EV2 7 NO

4.4.5 Insulated Power Output

If P24 option is ordered, the Insulated power output is available.

Specifications of Insulated power output are shown below.

Output voltage	24±3 V DC (at load current 30 mA DC)	
Ripple voltage	Within 200 mV DC (at load current 30 mA DC)	
Max load current	30 mA DC	

BCS2	BCR2, BCD2
P24 5 - 6	P24 (9)

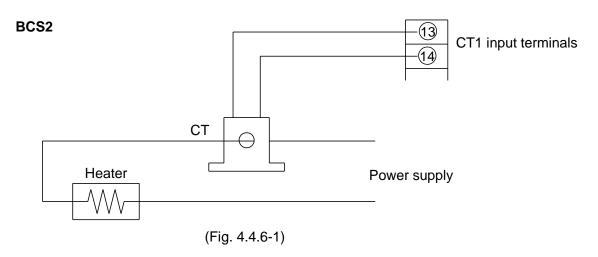
4.4.6 CT Input

CT input is available when Heater burnout alarm (C5W, EIW, W options) is ordered.

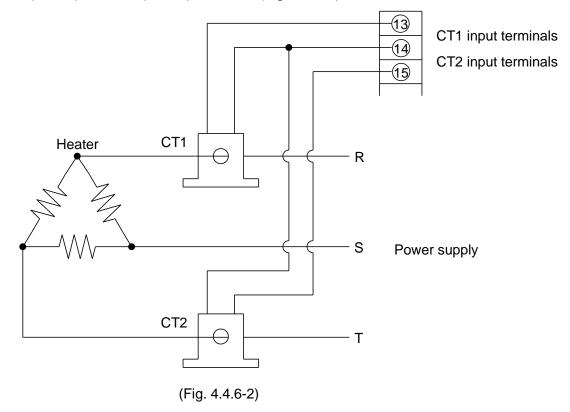
Cannot be used for detecting heater current under phase control.

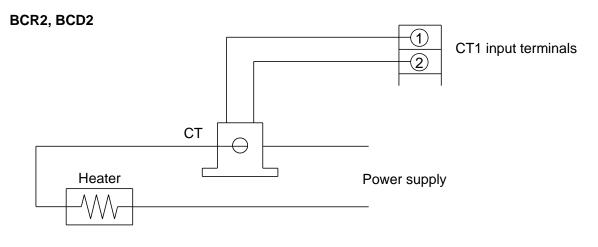
BCS2	BCR2, BCD2
CT1 (14) CT2 (15)	

Pass one lead wire of the heater circuit into the hole of the CT. (Fig. 4.4.6-1) When wiring, keep the CT wire away from AC sources or load wires to avoid the external interference.



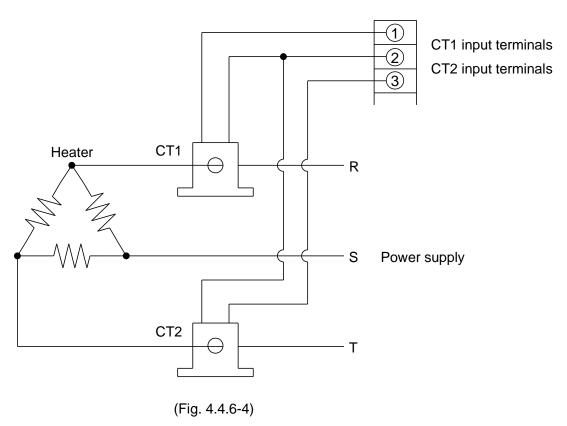
If using 3-phase, pass any 2 lead wires of R, S, T into the CT, and connect them to CT1 ($^{\textcircled{3}}$, $^{\textcircled{4}}$) and CT2 ($^{\textcircled{4}}$, $^{\textcircled{5}}$) terminals. (Fig. 4.4.6-2)





(Fig. 4.4.6-3)

When using 3-phase, pass any 2 lead wires of R, S, T into the CT, and connect them to CT1 $(^{\textcircled{1}}, ^{\textcircled{2}})$ and CT2 $(^{\textcircled{2}}, ^{\textcircled{3}})$ terminals. (Fig. 4.4.6-4)



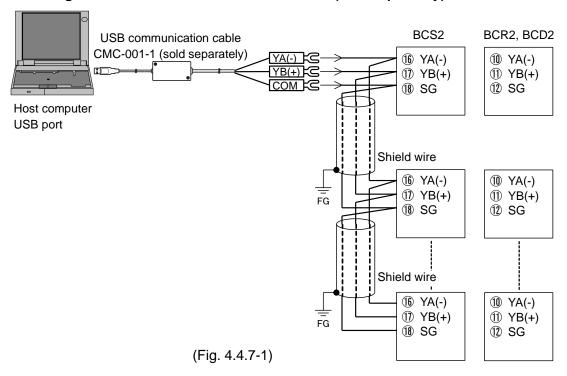
4.4.7 Serial Communication

If the C5W or C5 option is ordered, Serial communication is available.

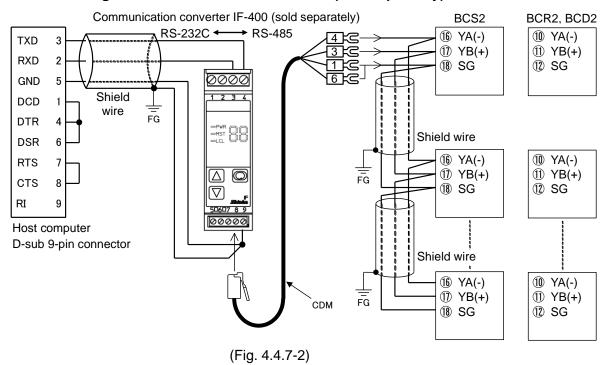
BCS2	BCR2, BCD2
YA(-) 16 RS- YB(+) 17 485 SG 18	YA(-) (10) YB(+) (11) SG (12) RS-485

(1) Serial Communication

• When using USB communication cable CMC-001-1 (sold separately)



When using communication converter IF-400 (sold separately)



(2) SV digital transmission

By connecting to Shinko programmable controllers PCA1 or PCB1 (select 'SV digital transmission' in [Communication protocol]), the Step SV can be received from programmable controllers.

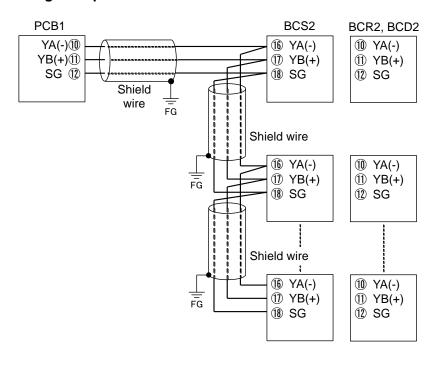
Wiring

For the SV digital transmission, connect YA (-) to YA (-), YB (+) to YB (+), SG to SG terminal respectively.

Up to 31 units of the BCS2 or BCR2 or BCD2 can be connected.

The following shows a connection example of PCB1 and BCS2, BCR2, BCD2. (Fig. 4.4.7-3)

Wiring example of PCB1 and BCx2



(Fig. 4.4.7-3)

Shield wire

Connect only one end of the shield to the FG to avoid a ground loop. If both ends of the shield wire are connected to the FG, the circuit will be closed, resulting in a ground loop. This may cause noise. Be sure to ground the FG.

Recommended cable: OTSC-VB 2PX0.5SQ (made by Onamba Co., Ltd.) or equivalent (Use a twisted pair cable.)

4.4.8 Event Input

Event Input DI1 is available for the BCS2 with Event input (EIW, EIT, EI options).

Event Input DI1 is available for the BCR2, BCD2 with Serial communication (C5W option) or Event input (EIW, EIT, EI options).

Event Input DI2 is available for the BCS2 with Event input (EIW, EI options).

Event Input DI2 is available for the BCR2, BCD2 with Serial communication (C5W option) or Event input (EIW, EIT, EI options).

Specifications of Event input are shown below.

Circuit current when closed	Approx. 16 mA
-----------------------------	---------------

BCS2		BCR2, BCD2
EIW (20A), EIW (100A), EI	EIT	EIW (20A), EIW (100A), EIT, EI
DI2 (17) DI1 (18) EVENT INPUT	DI1 (18) EVENT INPUT	D1 (1) (2) (8) (8) (9) (9) (1) (1) (1) (1) (1) (1) (1) (1) (1) (1

4.4.9 External Setting Input

If the EIT option is ordered, External setting input is available.

Specifications of External setting input are shown below.

Setting signal	Direct current 4 to 20 mA DC
Allowable input	50 mA DC max.
Input impedance	50 Ω max.
Input sampling period	125 ms

BCS2	BCR2, BCD2
EXT ± (3) CONT (4)	EXT CONT 5

4.4.10 Transmission Output

If the EIT option is ordered, Transmission output is available.

For the BCR2, BCD2, if EV2+D□ option and EIT option are added simultaneously,

Transmission output terminals become EV2 output terminals, so Transmission output will be disabled.

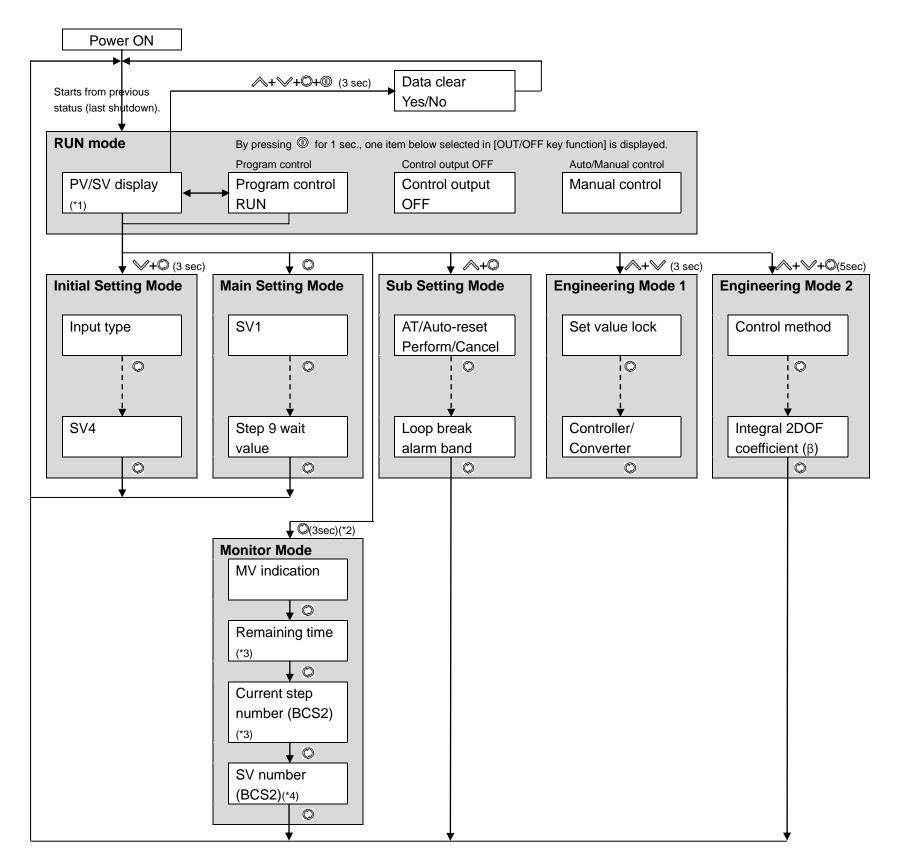
Specifications of Transmission output are shown below.

Resolution	12000	
Output	4 to 20 mA DC	
	Load resistance: Max 550 Ω	
Output accuracy	Within ±0.3% of Transmission output span	

BCS2	BCR2, BCD2
TRANSMIT + (15) OUTPUT - (16)	TRANSMIT +6 OUTPUT 7

5. Outline of Key Operation and Each Mode

5.1 key Operation



[Each Mode and Setting Item]

- (*1) If 'Program control' is selected in [OUT/OFF key function], the unit will enter Standby mode (program control waiting).
- (*2) The unit cannot proceed to Monitor mode if it is in Standby of program control.
- (*3) Available only when 'Program control' is selected in [OUT/OFF key function].
- (*4) Not available if 'Program control' is selected in [OUT/OFF key function].

[Key Operation]

- V+O (3 sec): Press and hold the V and O keys (in that order) together for approx. 3 sec.
- \wedge + \mathbb{O} : Press and hold the \wedge and \mathbb{O} keys (in that order) together.

- ♥ ②: If the ② key is pressed, the unit will proceed to the next setting item, illustrated by an arrow.

 By pressing the ⑤ key, the mode goes back to the previous mode.
- ↓ ©: Press the © key until the desired setting mode appears.

- If the $\ \ \, \bigcirc$ key is pressed for approx. 3 seconds at each item, the unit will revert to the RUN mode.
- If the ® key is pressed for approx. 3 seconds at each item, the following will be performed depending on the selection in [OUT/OFF key function]. If 'Control output OFF function' is selected in [OUT/OFF key function], the unit will enter Control output OFF status.
 - If 'Auto/Manual control' is selected in [OUT/OFF key function], the unit will enter Manual control status.
 - If 'Program control' is selected in [OUT/OFF key function], the unit will enter 'Program control RUN' or Standby mode.

5.2 Modes

.2 Modes			
Mode	Description		
RUN mode	When power is turned ON, the unit enters RUN mode.		
	The PV Display indicates PV, and the SV Display indicates SV.		
	Control starts from previous status (last shutdown).		
	By pressing the ® key for approx. 1 sec, one of the following functions is		
	activated depending on the selection in [OUT/OFF key function].		n in [OUT/OFF key function].
	OUT/OFF Key	y Function	Description
	Control output OFF	= function	Turns the control output ON or OFF.
	Auto/Manual contr	ol	Switches the Auto/Manual control.
	Program control		Starts/Stops the Program control.
Monitor mode	By pressing the ©	key for approx. 3	sec in RUN mode, the unit enters Monitor
			, and the SV Display indicates MV.
	·	-	e following is indicated.
	Indicated contents	•	-
	Model		Indicated Contents
	BCS2	Indicates MV. R	Remaining time (Program control), Step
			am control) or Set value memory number
		(Fixed value co	,
	BCR2, BCD2	`	Remaining time (Program control).
Initial setting mode			that order) together for approx. 3 sec in RUN
I mud setting mode	mode, the unit ente	• ,	, -
	The following items	•	000.
			nit, Event output EV1/EV2 (EV2, EV2+D□
		• •	/DI2 allocation (*), SV1, etc.
Main setting mode			de, the unit enters Main setting mode.
Wall Setting mode	SV can be set.	Key III Kert IIIoc	te, the unit enters main setting mode.
		' is selected in [C	OUT/OFF key function], SV, Time and Wait
	value for Steps 1 to	-	7017 Reg function], GV, Time and Walt
	•		ected in [Event input DI1/DI2 allocation] (*),
		=	
Sub setting mode	SV1 to SV4 can be set. By pressing the and keys (in that order) together in RUN mode, the unit		
Cub setting mode	enters Sub setting r	• '	rulat order) together in record mode, the drift
	The following items		
			se action, Event output EV1/EV2 (EV2,
			30 dollon, Event odipat E v 1/E v 2 (E v 2,
Engineering mode 1	EV2+D□ option), etc. By pressing the ∧ and ∨ keys (in that order) together for approx. 3 sec in		
Lingineering mode i	RUN mode, the uni	• `	, -
	The following items	· ·	ing mode 1.
			2 allocation (*), Event output EV1/EV2
		•	n, Sensor correction, PV filter time constant,
	•	• •	unction, Controller/Converter, etc.
Engineering mode 2			n that order) together for approx. 5 sec in
Linginiceting mode 2	RUN mode, the uni	•	, -
	The following items	_	ing mode 2.
			n 2DOF coefficient (α), Integral 2DOF
		Froportional gair	1 2001 Goeilicient (a), integral 200F
	coefficient (β)		

^(*) Event input DI1 allocation: BCS2 with EIW, EIT, EI options, Event input DI2 allocation: BCS2 with EIW, EI options, BCR2/BCD2 with C5W, EIW, EIT, EI options

5.3 Basic Operation after Power-ON

After the unit is mounted to the control panel and wiring is completed, operate the unit following the procedure below.

(1) Turn the power supply to the unit ON

After the power is turned ON, the PV Display indicates the input type, and the SV Display indicates the Input range high limit value (for thermocouple, RTD inputs) or Scaling high limit value (for DC voltage, current inputs) for approximately 3 seconds. (Table 5.3-1)

During this time, all outputs and the indicators are in OFF status. [0 mA DC for the direct current output type, and 0 mA DC for Transmission output (EIT option)]

Control will then start, indicating the PV on the PV Display and SV on the SV Display. While the control output OFF function is working, the PV Display indicates [aff]. Indication differs depending on the selection in [Indication when control output OFF].

(Table 5.3-1)

(Table 5.5 T)	°C		°F	
Sensor Input	PV Display	SV Display	PV Display	SV Display
K	ELLE	1370	EIF	2498
	E□ .C	4000	E□ F	7520
J	JUL	1888	JUF	1832
R	- <u>Ε</u>	1750	r EF	3200
S	'- <u> </u>	1750	'¬[F	3200
В	ЬШЕ	1820	b∐F	3308
E	$\mathcal{E} \square \mathcal{L}$	800	ELLF	1472
Т	$\mathcal{I} \square \mathcal{I}$	4000	$\Gamma \square \mathcal{F}$	7520
N	$\sigma \square \mathcal{L}$	1300	n F	2372
PL-II	PL ZE	1390	PL2F	2534
C(W/Re5-26)	ΕΠΕ	23 15	E □F	4 199
Pt100	PF .E	8500	PT F	1562.0
JPt100	JPT.E	5000	JPT.F	932.0
Pt100	PTUE	850	PT F	1552
JPt100	JPFE	<u> </u>	JPFF	
4 to 20 mA DC	420R			
0 to 20 mA DC	020R			
0 to 1 V DC	O IB	Cooling bigh	limit value	
0 to 5 V DC	0 5 <i>8</i>	Scaling high	iiiiiit value	
1 to 5 V DC	/ <u></u> 58			
0 to 10 V DC	0 108			

When power is turned ON, and any errors are found, the following error codes are indicated on the PV Display.

To cancel the error code, press the \bigcirc key.

Error Code	Error Contents
E-01	Non-volatile IC memory is defective.
E-02	Data writing (in non-volatile IC memory) error when power failure occurs.

(2) Enter each value.

Refer to Sections '6. Initial Setting' (p.37) to '8. Operation and Settings of Standard Functions' (p.80):

Enter each value: Input type, Control method, Direct/Reverse action, SV, PID constants, Event output EV1 allocation, etc.

(3) Turn the load circuit power ON

Control starts, so as to reach, and then maintain the control target at the SV.

· Error codes during operation

If errors occur during operation, error codes below are indicated on the PV Display.

Error Code	Error Contents
E-05 (*)	PV has exceeded Input range high limit value (scaling high limit value for DC
L U (*)	voltage, current inputs).
E-05 (*)	PV has dropped below Input range low limit value (scaling low limit value for DC
	voltage, current inputs).
E-07 (*)	Input burnout, or PV has exceeded the Indication range and Control range.
Er 10	Hardware malfunction

^(*) Indicated when Enabled is selected in [Error indication Enabled/Disabled].

Indication Range and Control Range

Input Type	Indication Range and Control Range
Thermocouple	[Input range low limit – 50°C (100°F)] to [Input range high limit + 50°C (100°F)]
RTD	[Input range low limit – Input span x 1%] to [Input range high limit + 50°C (100°F)]
DC voltage,	[Scaling low limit – Scaling span x 1%] to
Direct current	[Scaling high limit + Scaling span x 10%]

Input error (Overscale, Underscale)

If input errors (overscale, underscale) occur, the following will be performed depending on the selection in [Error indication Enabled/Disabled].

If Disabled is selected in [Error indication Enabled/Disabled]:

Overscale occurs if PV has exceeded Input range high limit value (Scaling high limit value for DC voltage, current inputs). The PV Display indicates PV.

Underscale occurs if PV has dropped below Input range low limit value (Scaling low limit value for DC voltage, current inputs). The PV Display indicates PV.

For manual control, the preset MV is output.

If Enabled is selected in [Error indication Enabled/Disabled]:

Overscale occurs if PV has exceeded Input range high limit value (Scaling high limit value for DC voltage, current inputs). The PV Display indicates PV and error code $\mathcal{E} \cap \mathcal{I} \mathcal{I}$ alternately.

Underscale occurs if PV has dropped below Input range low limit value (Scaling low limit value for DC voltage, current inputs). The PV Display indicates PV and error code $\mathcal{E} r \mathcal{Q} \mathcal{B}$ alternately.

For manual control, the preset MV is output.

Burnout

If burnout occurs, the following will be performed depending on the selection in [Error indication Enabled/Disabled].

If Disabled is selected in [Error indication Enabled/Disabled]:

If PV has exceeded Indication range and Control range, the PV Display flashes [_ _ _].

If PV has dropped below Indication range and Control range, the PV Display flashes [_ _ _ _].

If thermocouple or RTD input is burnt out, or if DC voltage (0 to 1 V DC) input is disconnected, the PV Display flashes [_____].

If DC voltage or current input is disconnected:

For 4 to 20 mA DC, 1 to 5 V DC inputs, the PV Display flashes [____].

For 0 to 20 mA DC, 0 to 5 V DC and 0 to 10 V DC inputs, the PV Display indicates the value corresponding with 0 mA DC or 0 V DC input.

OUT1 and OUT2 are turned OFF (OUT1 low limit value for direct current output, and OUT2 low limit value for DA, EV2+DA).

For manual control, the preset MV is output.

If Alarm, Heater burnout alarm or Loop break alarm is selected in [Event output EV1/EV2 allocation], Event output will be turned ON under the alarm active conditions.

Burnout is enabled even in standby (program control waiting) mode in Program control.

[Output status when input errors occur] can be used only for controllers using direct current and voltage inputs, and direct current output.

Output status differs depending on selection in [Output status when input errors occur].

Output status when input errors occur	Contents, Indication	Output Status			
		OUT1		OUT2	
		Direct	Reverse	Direct	Reverse
		(Cooling) action	(Heating) action	(Cooling) action	(Heating) action
۵۸	[] is flashing.	ON (20mA) or OUT1 high limit value (*) OFF (4mA) or OUT1 low limit value	OFF (4mA) or OUT1 low limit value	OFF or OUT2 low limit value	ON or OUT2 high limit value (*)
oFF.					OFF or OUT2 low limit value
ال ام	[] is flashing.	OFF (4mA) or OUT1 low limit value	ON (20mA) or OUT1 high limit value (*)	ON or OUT2 high limit value (*)	OFF or OUT2 low limit value
oFF.			OFF (4mA) or OUT1 low limit value	OFF or OUT2 low limit value	

^(*) Outputs a value between OFF (4mA) and ON (20mA) or between OUT1 (or OUT2) low limit value and OUT1 (or OUT2) high limit value, depending on deviation.

If Enabled is selected in [Error indication Enabled/Disabled]:

If PV has exceeded Indication range and Control range, the PV Display indicates [$[E \cap G]]$] alternately.

If PV has dropped below Indication range and Control range, the PV Display indicates [---] and $[E \cap G]$ alternately.

If thermocouple or RTD input is burnt out, or if DC voltage (0 to 1 V DC) input is disconnected, the PV Display indicates [-] and [$E \cap G$] alternately.

If DC voltage or current input is disconnected:

For 4 to 20 mA DC, 1 to 5 V DC inputs, the PV Display indicates [---] and $[E \cap G]$ alternately.

For 0 to 20 mA DC, 0 to 5 V DC and 0 to 10 V DC inputs, the PV Display indicates the value corresponding with 0 mA DC or 0 V DC input.

OUT1 and OUT2 are turned OFF (OUT1 low limit value for direct current output, and OUT2 low limit value for DA, EV2+DA).

For manual control, the preset MV is output.

If Alarm, Heater burnout alarm or Loop break alarm is selected in [Event output EV1/EV2 allocation], Event output will be turned ON under the alarm active conditions.

Burnout is enabled even in standby (program control waiting) mode in Program control

[Output status when input errors occur] can be used only for controllers using direct current and voltage inputs, and direct current output.

Output status differs depending on selection in [Output status when input errors occur].

Output status when input errors occur	Contents, Indication	Output Status			
		OUT1		OUT2	
		Direct	Reverse	Direct	Reverse
		(Cooling) action	(Heating) action	(Cooling) action	(Heating) action
on	[] and [E - []] are indicated alternatedly.	ON (20mA) or OUT1 high limit value (*)	OFF (4mA) or OUT1 low limit value	OFF or OUT2 low limit value	ON or OUT2 high limit value (*)
oFF		OFF (4mA) or OUT1 low limit value			OFF or OUT2 low limit value
on	[] and [E] are indicated alternatedly.	OFF (4mA) or OUT1 low limit value	ON (20mA) or OUT1 high limit value (*)	ON or OUT2 high limit value (*)	OFF or OUT2 low limit value
oFF.			OFF (4mA) or OUT1 low limit value	OFF or OUT2 low limit value	

^(*) Outputs a value between OFF (4mA) and ON (20mA) or between OUT1 (or OUT2) low limit value and OUT1 (or OUT2) high limit value, depending on deviation.

6. Initial Setting

Setup (setting the Input type, Event output allocation, SV, etc.) should be done before using this controller, according to the user's conditions.

Perform setup in Initial setting mode.

Setting items in Initial setting mode are shown in (Table 6.1).

If the user's specification is the same as the factory default value of this instrument, or if user's instrument has already been installed in a system, initial settings are not necessary. Proceed to Section '7. Settings' (p.53).

(Table 6.1)

Setting Items in Initial Setting Mode	Factory Default
Input type	K -200 to 1370°C
Scaling high limit	1370℃
Scaling low limit	-200℃
Decimal point place	No decimal point
Event output EV1 allocation	No event
EV1 alarm value 0 Enabled/Disabled	Disabled
EV1 alarm value	0℃
EV1 high limit alarm value	0℃
EV1 alarm hysteresis	1.0℃
EV1 alarm delay time	0 sec
EV1 alarm Energized/De-energized	Energized
Event output EV2 allocation (EV2, EV2+D□ options)	No event
EV2 alarm value 0 Enabled/Disabled (EV2, EV2+D□ options)	Disabled
EV2 alarm value (EV2, EV2+D□ options)	0℃
EV2 high limit alarm value (EV2, EV2+D□ options)	0℃
EV2 alarm hysteresis (EV2, EV2+D□ options)	1.0℃
EV2 alarm delay time (EV2, EV2+D□ options)	0 sec
EV2 alarm Energized/De-energized (EV2, EV2+D□ options)	Energized
Heater burnout alarm 1 value (C5W, EIW, W options)	0.0 A
Heater burnout alarm 2 value (C5W, EIW, W options)	0.0 A
Loop break alarm time	0 minutes
Loop break alarm band	0℃
Event input DI1 allocation	No event
(BCS2: EIW, EIT, EI options, BCR2/BCD2: C5W, EIW, EIT, EI options)	
Event input DI2 allocation	No event
(BCS2: EIW, EI options, BCR2/BCD2: C5W, EIW, EIT, EI options)	
External setting input high limit (EIT option)	1370℃
External setting input low limit (EIT option)	-200°ℂ
Transmission output type (EIT option)	PV transmission
Transmission output high limit (EIT option)	1370℃
Transmission output low limit (EIT option)	-200°ℂ
SV1	0℃
SV2 (BCS2: EIW, EIT, EI options, BCR2/BCD2: C5W, EIW, EIT, EI options)	0℃
SV3 (BCS2: EIW, EI option, BCR2/BCD2: C5W, EIW, EIT, EI options)	0℃
SV4 (BCS2: EIW, EI option, BCR2/BCD2: C5W, EIW, EIT, EI options)	0℃

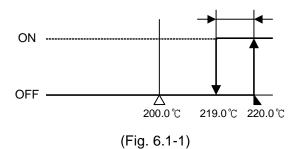
6.1 Example of Initial Setting

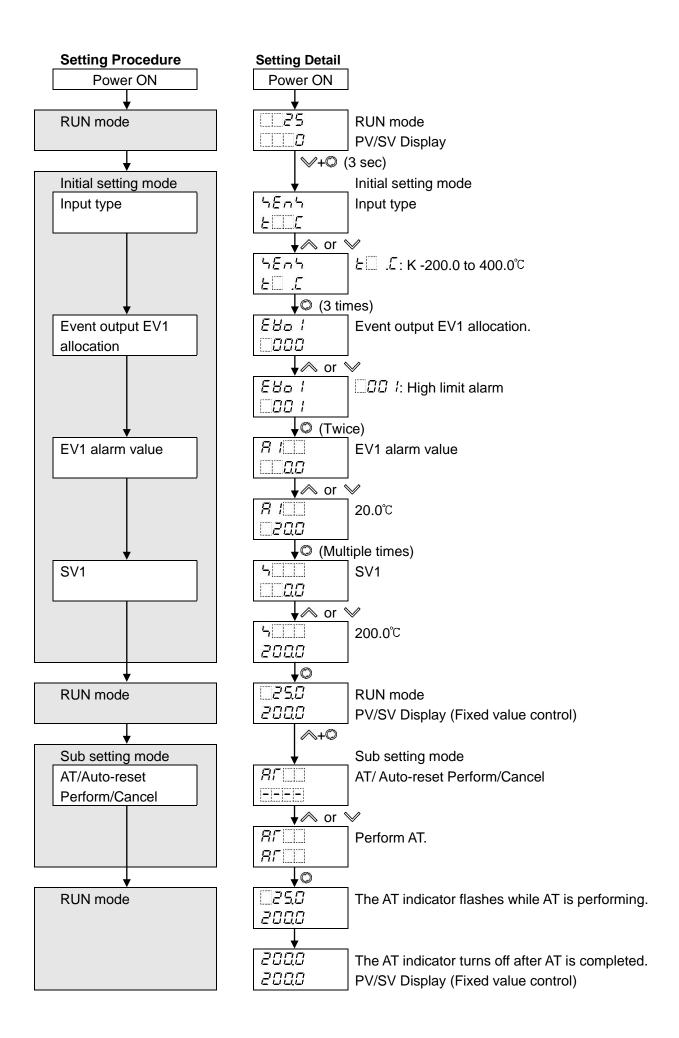
(e.g.) BCS2R00-00

Initial Setting Items	Example
Input type	K -200.0 to 400.0℃
Event output EV1 allocation	High limit alarm
EV1 alarm value	20.0 [°] C (Deviation setting from SV)
SV	200.0°C (Fixed value control)

PID control is performed. PID constants are calculated by performing AT.

Alarm action





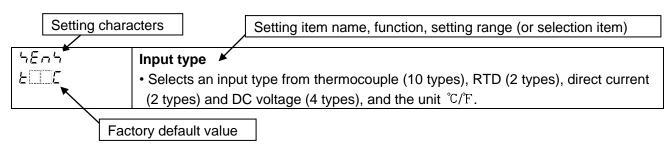
6.2 Initial Setting Mode

To enter Initial setting mode, press and hold the \vee and $\mathbb O$ keys (in that order) for 3 seconds in RUN mode. To set (or select) each setting item, use the \wedge or \vee key.

To register each setting item, press the © key.

Explanation of setting item:

- Upper left: PV Display: Indicates setting characters.
- Lower left: SV Display: Indicates factory default value.
- Right side: Indicates the setting item, explanation of its function, and setting range (or selection item).



Characters, Factory Default	Setting Item, Function, Setting Range			
5675 E 6	 (2 types) and DC voltage (4 type), and t When changing the input from DC volta connected to this controller first, then ch with the sensor connected, the input circu 	Selects an input type from thermocouple (10 types), RTD (2 types), direct current (2 types) and DC voltage (4 type), and the unit °C/°F. When changing the input from DC voltage to other inputs, remove the sensor connected to this controller first, then change the input. If the input is changed with the sensor connected, the input circuit may break. When changing an input type, refer to Section "8.10 Items to be Initialized by		
	• Selection item: E	### F K -328 to 2498 F ### F K -328.0 to 752.0 F ### F J -328 to 1832 F ### F R 32 to 3200 F ### F S 32 to 3200 F ### F B 32 to 3308 F ### F E -328 to 1472 F ### F T -328.0 to 752.0 F ### F N -328 to 2372 F ### PL ### PL-II 32 to 2534 F ### E F C(W/Re5-26) 32 to 4199 F ### F F Pt100 -328.0 to 1562.0 F #### ### ### F F ### F F Pt100 -328.0 to 932.0 F #### F F Pt100 -328 to 1562 F #### #### JPt100 -328 to 932 F		
ԿՐL H 1370	□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□			

^(*1) The placement of the decimal point follows the selection.

Scaling low limit -200 Setting range: Input range low limit value to Scaling high limit value DC voltage, current inputs: -2000 to 10000 (*) Decimal point place Selects decimal point place. Selects decimal point place. Selection item: DC 1 digit after decimal point DC 20 2 digits after decimal point DC 20 3 digits after decimal point DC 20 3 digits after decimal point DC 20 3 digits after decimal point DC 20 4 digits after decimal point DC 20 4 digits after decimal point DC 20 5 Selects Event output EV1 from the Event Output Allocation Table below. When changing Event output EV1, refer to Section "8.10 Items to be Initialized by Changing Settings" (p.98). Selects Output Allocation Table DC 3 Alarm output, High limit alarm DC 3 Alarm output, High/Low limits alarm DC 3 Alarm output, High/Low limits alarm DC 3 Alarm output, High/Low limits independent alarm DC 3 Alarm output, High/Low limits range independent alarm DC 3 Alarm output, High/Low limit range independent alarm DC 3 Alarm output, High/Low limit range independent alarm DC 3 Alarm output, High/Low limit standby alarm DC 3 Alarm output, High/Low limit with standby alarm DC 3 Alarm output, High/Low limits with standby alarm DC 3 Alarm output, High/Low limits with standby alarm DC 3 Alarm output, High/Low limits with standby alarm DC 3 Alarm output, High/Low limits with standby alarm DC 3 Alarm output, High/Low limits with standby alarm DC 3 Alarm output, High/Low limits with standby alarm DC 3 Alarm output, High/Low limits with standby alarm DC 3 Alarm output, High/Low limits with standby alarm DC 3 Alarm output, High/Low limits with standby alarm DC 3 Alarm output, High/Low limits with standby alarm DC 3 Alarm output, High/Low limits with standby alarm DC 3 Alarm output, High/Low limits with standby alarm DC 3 Alarm output, High/Low limits with standby alarm DC 3 Alarm output, High/Low limits with standby alarm DC 3 Alarm output, High/Low limits with standby alarm DC 3 Alarm output, High/Low limits with standby alarm DC 3 Alarm output, High/Low limits wi	Characters, Factory Default	Setting Item, Function, Setting Range		
- Sets scaling low limit value Setting range: Input range low limit value to Scaling high limit value - DC voltage, current inputs: -2000 to 10000 (*) Decimal point place		Scaling low limit		
* Setting range: Input range low limit value to Scaling high limit value DC voltage, current inputs: -2000 to 10000 (*1) Decimal point place * Selection item: Tid No decimal point GC	-200			
Decimal point place Selects decimal point place Selection item:		Setting range: Input range low limit value to Scaling high limit value		
Selection item: O		DC voltage, current inputs: -2000 to 10000 (*1)		
Selection item: 1			·	
Company Comp				
COD 1 digit after decimal point COD 2 digits after decimal point COD 3 digits after decimal point COD 3 digits after decimal point Available only for DC voltage and current inputs				
2 digits after decimal point 2000 3 digits after decimal point Available only for DC voltage and current inputs Event output EV1 allocation Selects Event output EV1 from the Event Output Allocation Table below. When changing Event output EV1, refer to Section "8.10 Items to be Initialized by Changing Settings" (p.98). Selection item: Event Output Allocation Table GGC No event GGC Alarm output, High limit alarm GGC Alarm output, Low limit alarm GGC Alarm output, High/Low limits alarm GGC Alarm output, High/Low limit range alarm GGC Alarm output, High/Low limit range independent alarm GGC Alarm output, High/Low limit range independent alarm GGC Alarm output, Process high alarm GGC Alarm output, Process low alarm GGC Alarm output, High limit with standby alarm GGC Alarm output, Low limit with standby alarm GCC Alarm output, High/Low limits With standby independent alarm GCC Alarm output, High/Low limits With standby independent alarm GCC Alarm output, High/Low limits With standby independent alarm GCC Alarm output, High/Low limits With standby independent alarm GCC Alarm output, High/Low limits With standby independent alarm GCC Alarm output, High/Low limits With standby independent alarm GCC Alarm output, High/Low limits With standby independent alarm GCC Alarm output, High/Low limits With standby independent alarm GCC Alarm output, High/Low limits With standby independent alarm GCC Alarm output, High/Low limits With standby independent alarm GCC Alarm output Alarm output GCC Alarm out				
### Support of the company of the co			· · · · · · · · · · · · · · · · · · ·	
Available only for DC voltage and current inputs EVent output EV1 allocation Selects Event output EV1, refer to Section "8.10 Items to be Initialized by Changing Settings" (p.98). Selection item: Event Output Allocation Table DDD I Alarm output, High limit alarm DDD Alarm output, High/Low limits alarm DDD Alarm output, High/Low limit range alarm DDD Alarm output, High/Low limit range independent alarm DDD Alarm output, Process high alarm DDD Alarm output, High limit with standby alarm DDD Alarm output, High/Low limits			'	
Event output EV1 allocation Selects Event output EV1 from the Event Output Allocation Table below. When changing Event output EV1, refer to Section "8.10 Items to be Initialized by Changing Settings" (p.98). Selection item: Event Output Allocation Table DDD I Alarm output, High limit alarm DDD Alarm output, Low limit alarm DDD Alarm output, High/Low limits alarm DDD Alarm output, High/Low limit range alarm DDD Alarm output, High/Low limit range independent alarm DDD Alarm output, Process high alarm DDD Alarm output, Process low alarm DDD Alarm output, High/Low limit with standby alarm DDD Alarm output, High/Low limits wit				
Selects Event output EV1 from the Event Output Allocation Table below. When changing Event output EV1, refer to Section "8.10 Items to be Initialized by Changing Settings" (p.98). Selection item: Event Output Allocation Table DD Alarm output, High limit alarm DD Alarm output, High/Low limits alarm DD Alarm output, High/Low limits alarm DD Alarm output, High/Low limits independent alarm DD Alarm output, High/Low limit range alarm DD Alarm output, High/Low limit range independent alarm DD Alarm output, Process high alarm DD Alarm output, High limit with standby alarm DD Alarm output, High limit with standby alarm DD Alarm output, High limit with standby alarm DD Alarm output, High/Low limits with standby alarm DD Alarm output, High/Low limits with standby alarm DD Alarm output, High/Low limits with standby independent alarm DD Alarm output, High/Low limits with standby independent alarm DD Alarm output, High/Low limits with standby independent alarm DD Alarm output, High/Low limits with standby independent alarm DD Alarm output, High/Low limits with standby independent alarm DD Alarm output, High/Low limits with standby independent alarm DD Alarm output, High/Low limits with standby independent alarm DD Alarm output, High/Low limits with standby independent alarm DD Alarm output, High/Low limits with standby independent alarm DD Alarm output, High/Low limits with standby independent alarm DD Alarm output, High/Low limits with standby independent alarm DD Alarm output, High/Low limits with standby independent alarm DD Alarm output, High/Low limits with standby independent alarm DD Alarm output, High/Low limits with standby independent alarm DD Alarm output, High/Low limits with standby independent alarm DD Alarm output, High/Low limits with standby alarm DD Alarm output, High/Low limits with standby alarm DD Alarm output, High/Low limit	200000	Available or	nly for DC voltage and current inputs	
When changing Event output EV1, refer to Section "8.10 Items to be Initialized by Changing Settings" (p.98). Selection item: Event Output Allocation Table GGG No event GGG Alarm output, High limit alarm GGG Alarm output, Low limit alarm GGG Alarm output, High/Low limits alarm GGG Alarm output, High/Low limits independent alarm GGG Alarm output, High/Low limit range independent alarm GGG Alarm output, Process high alarm GGG Alarm output, Process low alarm GGG Alarm output, High limit with standby alarm GGG Alarm output, Low limit with standby alarm GGG Alarm output, Low limit with standby alarm GGG Alarm output, High/Low limits with standby alarm GGG Alarm output, High/Low			-	
Changing Settings" (p.98). Selection item: Event Output Allocation Table BBB No event BBB I Alarm output, High limit alarm BBB Alarm output, Low limit alarm BBB Alarm output, High/Low limits alarm BBB Alarm output, High/Low limits independent alarm BBB Alarm output, High/Low limit range alarm BBB Alarm output, High/Low limit range independent alarm BBB Alarm output, Process high alarm BBB Alarm output, Process low alarm BBB Alarm output, High limit with standby alarm BBB Alarm output, High limit with standby alarm BBB Alarm output, Low limit with standby alarm BBB Alarm output, High/Low limits With standby independent alarm BBB Alarm output, High/Low limits With standby independent alarm BBB Alarm output BBB Alarm output			·	
Selection item: Event Output Allocation Table BBB No event BBB I Alarm output, High limit alarm BBB Alarm output, Low limit alarm BBB Alarm output, High/Low limits alarm BBB Alarm output, High/Low limit range alarm BBB Alarm output, High/Low limit range independent alarm BBB Alarm output, Process high alarm BBB Alarm output, Process low alarm BBB Alarm output, High limit with standby alarm BBB Alarm output, Low limit with standby alarm BBB Alarm output, High/Low limits with standby alarm BBB Alarm output, High/Low				ction "8.10 Items to be Initialized by
Event Output Allocation Table GGG No event GGG Alarm output, High limit alarm GGG Alarm output, Low limit alarm GGG Alarm output, High/Low limits alarm GGG Alarm output, High/Low limits alarm GGG Alarm output, High/Low limits independent alarm GGG Alarm output, High/Low limit range alarm GGG Alarm output, High/Low limit range independent alarm GGG Alarm output, Process high alarm GGG Alarm output, Process low alarm GGG Alarm output, High limit with standby alarm GGG Alarm output, Low limit with standby alarm GGG Alarm output, High/Low limits with standby alarm GGG Alarm output, High/Low limits with standby alarm GGG Alarm output, High/Low limits with standby alarm GGG Alarm output, High/Low limits with standby alarm GGG Alarm output, High/Low limits TGGG		_	- , ,	
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Alarm output, Low limit alarm GGG Alarm output, High/Low limits alarm Alarm output, High/Low limits independent alarm GGG Alarm output, High/Low limit range alarm Alarm output, High/Low limit range independent alarm GGG Alarm output, Process high alarm GGG Alarm output, Process low alarm GGG Alarm output, Process low alarm Alarm output, High limit with standby alarm GGG Alarm output, Low limit with standby alarm GGG Alarm output, High/Low limits with standby alarm GGG Alarm output, High/Low limits with standby alarm GGG Alarm output, High/Low limits With standby alarm GGG Alarm output, High/Low limits With standby independent alarm GGG Alarm output, High/Low limits With standby independent alarm GGG Alarm output, High/Low limits With standby independent alarm GGG Alarm output, High/Low limits With standby independent alarm GGG Alarm output, High/Low limits With standby independent alarm GGG Alarm output Turns OFF or ON during Program control, by setting OFF and ON				
Alarm output, High/Low limits alarm GG9 Alarm output, High/Low limits independent alarm GG5 Alarm output, High/Low limit range alarm Alarm output, High/Low limit range independent alarm GG8 Alarm output, Process high alarm GG9 Alarm output, Process low alarm Alarm output, High limit with standby alarm Alarm output, Low limit with standby alarm GG1 Alarm output, High/Low limits With standby independent alarm GG1 Heater burnout alarm output GG1 Turns OFF or ON during Program control, by setting OFF and ON				
Alarm output, High/Low limits independent alarm Alarm output, High/Low limit range alarm Alarm output, High/Low limit range independent alarm Alarm output, Process high alarm Alarm output, Process low alarm Alarm output, High limit with standby alarm Alarm output, Low limit with standby alarm Alarm output, Low limit with standby alarm Alarm output, High/Low limits With standby independent alarm Heater burnout alarm output Black Loop break alarm output Turns OFF or ON during Program control, by setting OFF and ON			Alarm output, Low limit alarm	
independent alarm GGS Alarm output, High/Low limit range alarm Alarm output, High/Low limit range independent alarm Alarm output, Process high alarm Alarm output, Process low alarm Alarm output, High limit with standby alarm Alarm output, Low limit with standby alarm Alarm output, High/Low limits with standby independent alarm Alarm output, High/Low limits with standby independent alarm DIS Heater burnout alarm output Turns OFF or ON during Program control, by setting OFF and ON				
Alarm output, High/Low limit range alarm Alarm output, High/Low limit range independent alarm Alarm output, Process high alarm Alarm output, Process low alarm Alarm output, High limit with standby alarm Alarm output, Low limit with standby alarm Alarm output, High/Low limits With standby independent alarm BIS IS Heater burnout alarm output CIN IN I		<u> </u>		
alarm Alarm output, High/Low limit range independent alarm Alarm output, Process high alarm Alarm output, Process low alarm Alarm output, High limit with standby alarm Alarm output, Low limit with standby alarm Alarm output, High/Low limits With standby independent alarm Black Alarm output Clack Alarm output Turns OFF or ON during Program control, by setting OFF and ON				
Alarm output, High/Low limit range independent alarm Alarm output, Process high alarm Alarm output, Process low alarm Alarm output, High limit with standby alarm Alarm output, Low limit with standby alarm Alarm output, High/Low limits with standby independent alarm Alarm output, High/Low limits with standby independent alarm Alarm output, Tims OFF or ON during Program control, by setting OFF and ON				
Alarm output, Process high alarm BBB Alarm output, Process low alarm BBB Alarm output, High limit with standby alarm BBB Alarm output, Low limit with standby alarm BBB Alarm output, High/Low limits with standby alarm BBB Alarm output, High/Low limits with standby alarm BBB Alarm output, High/Low limits with standby independent alarm BBB Heater burnout alarm output BBB IBB Heater burnout alarm output BBB IBB Turns OFF or ON during Program control, by setting OFF and ON		005	Alarm output, High/Low limit range	
Alarm output, Process low alarm Alarm output, High limit with standby alarm Alarm output, Low limit with standby alarm Alarm output, High/Low limits with standby alarm Alarm output, High/Low limits with standby alarm Alarm output, High/Low limits with standby independent alarm II I Heater burnout alarm output II Loop break alarm output II I Loop break alarm output Turns OFF or ON during Program control, by setting OFF and ON		רחח	•	
Alarm output, High limit with standby alarm Alarm output, Low limit with standby alarm Alarm output, High/Low limits with standby alarm Alarm output, High/Low limits with standby alarm Alarm output, High/Low limits with standby independent alarm II I Heater burnout alarm output II Loop break alarm output II I Turns OFF or ON during Program control, by setting OFF and ON				
Alarm output, Low limit with standby alarm Alarm output, High/Low limits with standby alarm Alarm output, High/Low limits with standby independent alarm Alarm output, High/Low limits with standby independent alarm Black IB Alarm output, High/Low limits with standby independent alarm Black IB Alarm output, High/Low limits with standby independent alarm Black IB Alarm output, High/Low limits with standby alarm Turns OFF or ON during Program control, by setting OFF and ON			Alarm output, High limit with standby	
Alarm output, High/Low limits with standby alarm Alarm output, High/Low limits with standby independent alarm B 13 Heater burnout alarm output B 14 Loop break alarm output B 15 Time signal output Turns OFF or ON during Program control, by setting OFF and ON		_0 IO	Alarm output, Low limit with standby	
Alarm output, High/Low limits with standby independent alarm I I Heater burnout alarm output I Loop break alarm output I I Turns OFF or ON during Program control, by setting OFF and ON			Alarm output, High/Low limits	
with standby independent alarm G 13 Heater burnout alarm output G 14 Loop break alarm output Time signal output Turns OFF or ON during Program control, by setting OFF and ON		n :2		
Loop break alarm output Turns OFF or ON during Program control, by setting OFF and ON				
Time signal output Turns OFF or ON during Program control, by setting OFF and ON		<u> </u>	Heater burnout alarm output	
control, by setting OFF and ON		_0 /Y	Loop break alarm output	
		_ <i>0</i> /5	Time signal output	Turns OFF or ON during Program
time within the step set in [Step number].				time within the step set in [Step
UI IS Output during AT Turns ON during AT.		DO IS	Output during AT	•
			·	Turns ON when Program control
		.	T ditem one output	ends, and remains ON until turned
☐☐ IB Output by communication Turns OFF or ON by communication		C 18	Output by communication	Turns OFF or ON by communication
command 00E4H during Serial			, ,	
communication. B0 EV1 output 0: OFF				
1: ON				
B1 EV2 output 0: OFF				B1 EV2 output 0: OFF
(*1) The placement of the decimal point follows the selection.	(*4) The place of (*1)	oo doelas -1 1	nt fallows the colors:	1: ON

^(*1) The placement of the decimal point follows the selection.

Characters,	Setting Item, Function, Setting Range		
Factory Default	EV4 clarm value 0 Enchled/Dischled		
	 EV1 alarm value 0 Enabled/Disabled When EV1 alarm value is 0 (zero), alarm action can be Enabled or Disabled. 		
/ //_/\k:	Selection item:	zero), alaim action can be Enabled of Disabled.	
	Disabled		
	Enabled		
		High limit clarm) to 1705 (Alarm output High/Low limit range	
	Available when \$\Bar{\text{\ti}\}\ext{\te}\text{		
	independent alarm), $\square \square \square \square$ (Alarm output, High limit with standby alarm) to $\square \square \square \square \square$ (Alarm output, High/Low limits with standby independent alarm) are selected in [Event output EV1 allocation].		
R (EV1 alarm value	ent diann) are selected in [Event output Evil anocation].	
	Sets EV1 alarm value.		
		1 low limit alarm value in the following cases:	
	0.07 (0.07)	/Low limits independent alarm), \(\sum_{\pi} \varphi \) (Alarm	
	_	independent alarm), or $\square \square \square \square \square \square$ (Alarm output,	
		independent alarm) is selected in [Event output EV1	
	allocation].	,	
	Setting range:		
	High limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)	
	Low limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)	
	High/Low limits alarm	0 to Input span °C (°F) (*1) (*2)	
	High/Low limits independent	0 to Input span °C (°F) (*1) (*2)	
	alarm		
	High/Low limit range alarm 0 to Input span °C (°F) (*1) (*2)		
	High/Low limit range	0 to Input span °C (°F) (*1) (*2)	
	independent alarm		
	Process high alarm Input range low limit to Input range high limit (*1) (*3)		
	Process low alarm	Input range low limit to Input range high limit (*1) (*3)	
	High limit with standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)	
	Low limit with standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)	
	High/Low limits with standby	0 to Input span °C (°F) (*1) (*2)	
	alarm		
	High/Low limits with standby	0 to Input span °C (°F) (*1) (*2)	
	independent alarm		
	Available when any alarm from $\square GG \ !$ (Alarm output, High limit alarm) to $\square G \ ! \not \in$ (Alarm output, High/Low		
	limits with standby independent alarm) is selected in [Event output EV1 allocation].		
A IH	EV1 high limit alarm value		
	Sets EV1 high limit alarm value.		
	This value is available only for the following.		
	_	/Low limits independent alarm), 🗆🗆 🙃 (Alarm	
		independent alarm), or $\square \square \square \square \square \square \square$ (Alarm output,	
	,	independent alarm) is selected in [Event output EV1	
	allocation].		
	Setting range: Same as those decimal point follows the selection.	e of EV1 alarm value	

 $^{(^{\}star}1)$ The placement of the decimal point follows the selection.

 $^(^*2)$ For DC voltage, current inputs, the input span is the same as the scaling span.

 $^{(^\}star 3) \ \text{For DC voltage, current inputs, input range low (or high) limit value is the same as scaling low (or high) limit value.}$

Characters, Factory Default	Setting Item, Function, Setting Range		
A IHY	EV1 alarm hysteresis		
	Sets EV1 alarm hysteresis.		
	• Setting range: 0.1 to 1000.0°C (°F),		
	DC voltage, current inputs: 1 to 10000 (*1)		
	Available when any alarm from $\square \square \square$ (Alarm output, High limit alarm) to $\square \square$ \square (Alarm output, High/Low		
	limits with standby independent alarm) is selected in [Event output EV1 allocation].		
R IdY	EV1 alarm delay time		
	Sets EV1 alarm action delay time.		
	When setting time has elapsed after the input enters the alarm output range, the		
	alarm is activated.		
	Setting range: 0 to 10000 seconds		
	Available when any alarm from $\square \square \square$ (Alarm output, High limit alarm) to $\square \square$ /2 (Alarm output, High/Low		
	limits with standby independent alarm) is selected in [Event output EV1 allocation].		
A ILĀ	EV1 alarm Energized/De-energized		
noñL	Selects Energized/De-energized status for EV1 alarm.		
	(Refer to 'EV1/EV2 Energized/De-energized' on p.50.)		
	Selection item:		
	nañL Energized		
	ァミガ De-energized		
	Available when any alarm from 🗆 larm (Alarm output, High limit alarm) to 🗀 12 (Alarm output, High/Low		
	limits with standby independent alarm) is selected in [Event output EV1 allocation].		
[5]5	TS1 output step number		
	Sets the step number at which Time signal output TS1 will be turned OFF or ON		
	during Program control.		
	(Refer to 'Time Signal Output' on p.52.)		
	Setting range: 1 to 9		
	Available only when $\Box 3$ /5 (Time signal output) is selected in [Event output EV1 allocation].		
rh IF	TS1 OFF time		
0000	Sets Time signal output TS1 OFF time.		
	(Refer to 'Time Signal Output' on p.52.)		
	• Setting range: 00:00 to 99:59 (*2)		
	Available only when $\square 3$ /5 (Time signal output) is selected in [Event output EV1 allocation].		
15 lo	TS1 ON time		
00,00	Sets Time signal output TS1 ON time.		
	(Refer to 'Time Signal Output' on p.52.)		
	• Setting range: 00:00 to 99:59 (*2)		
	Available only when $\square III$ (Time signal output) is selected in [Event output EV1 allocation].		
(*1) The placement of t	he decimal point follows the selection		

^(*1) The placement of the decimal point follows the selection.

^(*2) Time unit follows the selection in [Step time unit].

Characters, Factory Default	Setting Item, Function, Setting Range			
E805	Event output EV2 allocation			
<u> </u>	 Selects Event output EV2 from the Event Output Allocation Table below. When changing Event output EV2, refer to Section "8.10 Items to be Initialized by Changing Settings" (p.98). Selection item: 			
		Event Output Allocation Table		
		No event		
	00 1	Alarm output, High limit alarm		
	002	Alarm output, Low limit alarm		
	003	Alarm output, High/Low limits alarm		
	007	Alarm output, High/Low limits		
		independent alarm		
	005	Alarm output, High/Low limit range alarm		
	005	Alarm output, High/Low limit range independent alarm		
	007	Alarm output, Process high alarm		
	008	Alarm output, Process low alarm		
	009	Alarm output, High limit with standby alarm		
	_0 IO	Alarm output, Low limit with standby alarm		
		Alarm output, High/Low limits with standby alarm		
	<u>□</u> 0 12	Alarm output, High/Low limits with standby independent alarm		
	□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□			
	<u> </u>	Loop break alarm output		
	<u></u> 0 15	Time signal output	Turns OFF or ON during Program control, by setting OFF and ON times within the step set in [Step number].	
	D 16	Output during AT	Turns ON during AT.	
	<u> </u>	Pattern end output	Turns ON when Program control ends, and remains ON until turned	
	□0 I8	Output by communication command	OFF by pressing the ® key. Turns OFF or ON by communication command 00E4H during Serial communication. B0 EV1 output 0: OFF 1: ON B1 EV2 output 0: OFF 1: ON	
	IS	Heating/Cooling control	B1 EV2 output 0: OFF 1: ON Works as Control output OUT2	
	<u> </u>	relay contact output	(Heating/Cooling control).	
	Available or	lly when Event output EV2 (EV2, EV2+D□ options		
R2ER	EV2 alarm value 0 Enabled/Disabled			
no		V2 alarm value is 0 (zero), alarm action	n can be Enabled or Disabled.	
	Disabled Disabled Disabled Disabled Disabled Disabled Disabled Disabled Disabled Disabled Disabled Disable Disabled Disable Disabled Disable Disabled Di			
(*1) Not available if Heati		nits with standby independent alarm) are selected ntrol (EV2+D option) is ordered.	III į⊏vent output ⊏v∠ allocationį.	

Characters, Factory Default	Setting Item, Function, Setting Range		
R2	EV2 alarm value		
	Sets EV2 alarm value.		
	EV2 alarm value matches EV	2 low limit alarm value in the following cases:	
	□□□□ (Alarm output, High/l	Low limits independent alarm), $\square GGS$ (Alarm output,	
	High/Low limit range indepen	dent alarm), or $\square \mathcal{Z} \not \in$ (Alarm output, High/Low limits	
	with standby independent ala	arm) is selected in [Event output EV2 allocation].	
	Setting range:		
	High limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)	
	Low limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)	
	High/Low limits alarm	0 to Input span °C (°F) (*1) (*2)	
	High/Low limits independent	0 to Input span °C (°F) (*1) (*2)	
	alarm		
	High/Low limit range alarm	0 to Input span °C (°F) (*1) (*2)	
	High/Low limit range	0 to Input span °C (°F) (*1) (*2)	
	independent alarm		
	Process high alarm	Input range low limit to Input range high limit (*1) (*3)	
	Process low alarm	Input range low limit to Input range high limit (*1) (*3)	
	High limit with standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)	
	Low limit with standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)	
	High/Low limits with standby	0 to Input span °C (°F) (*1) (*2)	
	High/Low limits with standby	0 to Input span °C (°F) (*1) (*2)	
	independent alarm		
	Available only when Event output EV2	(EV2, EV2+DL options) is ordered. ' (Alarm output, High limit alarm) to にない (Alarm output, High/Low	
		is selected in [Event output EV2 allocation].	
R2H	EV2 high limit alarm value		
	Sets EV2 high limit alarm val	ue.	
	This value is available only fo	or the following:	
		Low limits independent alarm), $\square \square \square S$ (Alarm output,	
	High/Low limit range indeper	ndent alarm), or $\square \mathcal{Q} \not \in \mathcal{C}$ (Alarm output, High/Low limits	
	with standby independent ala	arm) is selected in [Event output EV2 allocation].	
	Setting range: Same as those	e of EV2 alarm value	
	Available only when Event output EV2	(EV2, EV2+D□ options) is ordered.	
R2HY	EV2 alarm hysteresis		
	Sets EV2 alarm hysteresis.		
	• Setting range: 0.1 to 1000.0°		
	DC voltage, current inputs: 1		
	Available only when Event output EV2 Available when any alarm from	(Ev2, Ev2+レニ) options) is ordered. ' (Alarm output, High limit alarm) to ニロ だ (Alarm output, High/Low	
	-	is selected in [Event output EV2 allocation].	
8248	EV2 alarm delay time		
	Sets EV2 alarm action delay		
		ed after the input enters the alarm output range, the	
	alarm is activated.		
	Setting range: 0 to 10000 sec Available and when Event output EV/3		
	Available only when Event output EV2 Available when any alarm from	(EV2, EV2+DL) options) is ordered. (Alarm output, High limit alarm) to $\square \mathcal{G} \wr \mathcal{Z}$ (Alarm output, High/Low	
	I -	is selected in [Event output EV2 allocation].	

- (*1) The placement of the decimal point follows the selection.
- $(^*2)$ For DC voltage, current inputs, the input span is the same as the scaling span.
- (*3) For DC voltage, current inputs, input range low (or high) limit value is the same as scaling low (or high) limit value.

Characters,		Cotting Itom Function Cotting Dongs		
Factory Default	Setting Item, Function, Setting Range			
R2LA	EV2 alarm Energized/De-energized			
noñL	Selects E	nergized/De-energized status for EV2 alarm.		
	(Refer to '	EV1/EV2 Energized/De-energized' on p.50.)		
	Selection	item:		
	noñL	Energized		
	rE85	De-energized		
	Available only	when Event output EV2 (EV2, EV2+D options) is ordered.		
	Available whe	on any alarm from $\square GG$ l (Alarm output, High limit alarm) to $\square G$ l l (Alarm output, High/Low		
	limits with sta	ndby independent alarm) is selected in [Event output EV2 allocation].		
5-2-	TS2 outpu	t step number		
	Sets the s	tep number at which Time signal output TS2 will be turned OFF or ON		
	during Pro	gram control.		
	(Refer to "	Time Signal Output' on p.52.)		
	 Setting ra 	nge: 1 to 9		
	Available only	when $\square \mathcal{I}$ (Time signal output) is selected in [Event output EV2 allocation].		
F52F	TS2 OFF ti	me		
0000	Sets Time	Sets Time signal output TS2 OFF time.		
	(Refer to "	Time Signal Output' on p.52.)		
	• Setting range: 00:00 to 99:59 (*1)			
	Available only	Available only when 🗔 /5 (Time signal output) is selected in [Event output EV2 allocation].		
['52o	TS2 ON tin	ne		
0000	Sets Time signal output TS2 ON time.			
	(Refer to 'Time Signal Output' on p.52.)			
	• Setting range: 00:00 to 99:59 (*1)			
	Available only	when \$\instyle I^5\$ (Time signal output) is selected in [Event output EV2 allocation].		
H I	Heater bur	nout alarm 1 value		
<u> </u>		leater current value for Heater burnout alarm 1.		
H I and CT1 current	Characters H I and CT1 current value are alternately indicated on the PV			
value are alternately	Display.			
indicated on the PV	When OUT1 is ON, the CT1 current value is updated.			
Display.	When OUT1 is OFF, the unit memorizes the previous value when OUT1 was ON. Upon returning to set limits, the alarm will stop.			
	 Setting ra 	_		
	20 A: 0.0 to 20.0 A			
	100 A: 0.0	to 100.0 A		
	Setting to	0.0 disables the alarm.		
	Not available	for the direct current output type.		
	Available who	en Heater burnout alarm (C5W, EIW, W options) is ordered.		

^(*1) Time unit follows the selection in [Step time unit].

Characters, Factory Default	Setting Item, Function, Setting Range				
H2	Heater burnout alarm 2 value				
	Sets the heater current value for Heater burnout alarm 2.				
		only when using 3-p		out diam. Li	
H∄ and CT2		ers <i>H⊒</i> and CT2 cur		alternately indic	ated on the PV
current value are		713 712 and 012 cui	ioni value are e	inciriately indic	ated on the r
alternately	Display. When OUT1 is ON, the CT2 current value is updated.				
indicated on the				•	when OUT1 was ON.
PV Display.		•		•	when our was on.
	Upon returning to set limits, the alarm will stop. • Setting range:				
		to 20.0 A			
		0 to 100.0 A			
		0.0 disables the ala	rm		
		e for the direct current outp			
		ly when Heater burnout ala	• •	otions) is ordered.	
LP_F	_	ak alarm time			
		time to assess the Lo	•	า.	
		Loop Break Alarm' o	•		
		ange: 0 to 200 minute			
		0 (zero) disables the	e alarm.		
LP_H	-	ak alarm band			
		temperature to asses	•	ak alarm.	
		Loop Break Alarm' of	•	ν°α (°D)	
		ange: 0 to 150°C (˚F),)C (F)	
	DC voltage, current inputs: 0 to 1500 (*1)				
E81 1	Setting to 0 (zero) disables the alarm.				
	Event input DI1 allocation				
	Selects Event input DI1 from Event Input Allocation Table. (Refer to 'Event Input' on p. 51.)				
	(Refer to 'Event Input' on p.51.)				
	• Selection item: Event Input Allocation Table				
		Fyent input Input ON Input OFF			
		function	(Closed)	(Open)	Remarks
		No event			
		Set value memory			
	002	Control ON/OFF	Control OFF	Control ON	Control output OFF
		(*2)			function
	003	Direct/Reverse	Direct	Reverse	Always effective
		action	action	action	
	004	Preset output 1	Preset	Usual	If sensor is burnt out,
		ON/OFF	output	control	the unit maintains
					control with the
					preset MV.
	005	Preset output 2	Preset	Usual	The unit maintains
		ON/OFF	output	control	control with the
					preset MV.
	005	Auto/Manual	Manual	Automatic	Effective when
		control	control	control	Auto/Manual control
					is selected in [OUT/
		oint follows the selection.			OFF key function].

^{(*1):} The placement of the decimal point follows the selection.
(*2): "Control ON/OFF" is not displayed when "Auto/Manual control" or "Program control" is selected for "OUT/OFF key function".

Characters, Factory Default	Setting Item, Function, Setting Range				
000 E81 1	Event input Input ON Input OFF function (Closed) (Open) Remarks				Remarks
	<u> </u>	Remote/Local	Remote	Local	Effective when External setting input (EIT option) is ordered.
	008	Program control RUN/STOP	RUN	STOP	Level action when power is turned on
	009	Program control Holding/Not holding	Holding	Not holding	Level action when power is turned on
	0 10	Program control	Advance	Usual	
		Advance function	function	control	
		Integral action	Integral	Usual	Control continues
		Holding	action	integral	with the integral
			Holding	action	value being held.
		available only when Event ir CD2, available when Serial			input (EIW, EIT, EI options) is
EBI 2	Event inp	ut DI2 allocation			
_000	Selects I	Event input DI2 from	Event Input Allo	cation Table.	
	(Refer to	'Event Input' on p.51)		
	 Selection 	n item:			
	Same as those of Event input DI1 allocation For BCS2, available only when Event input (EIW, EI option) is ordered. For BCR2/BCD2, available when Serial communication (C5W option) or Event input (EIW, EIT, EI options) is ordered.				
-TLH	External setting input high limit				
מרפו	Sets External setting input high limit value.				
	This value corresponds to 20 mA in direct current input. • Setting range: External setting input low limit to Input range high limit (*1)				
				high limit (*1)	
	_	nly when External setting ir	•		
rrll	External	setting input low lin	nit		
-200		ternal setting input lo			
	This valu	e corresponds to 4 n	nA in direct curr	ent input.	
	Setting range	ange: Input range lov	v limit to Extern	al setting input	high limit (*1)
	Available o	nly when External setting ir	nput (EIT option) is o	ordered.	
1-04	Transmission output type				
PB	Selects t	ransmission output t	уре.		
	• When ch	anging transmission	output type, ref	fer to Section "8	3.10 Items to be
	Initialized	d by Changing Settin	ıgs" (p.98).		
	 Selection 	n item:			
	PH	PV transmission			
	5 <i>8</i>	SV transmission			
	⊼8□□	MV transmission			
	<i>d</i> 8□□	DV transmission			
	Available on	ly when Transmission outp	ut (EIT option) is ord	lered.	
(*1) The placement of the	ha daaimal nair	at follows the coloation			

 $^{(^{\}star}1)$ The placement of the decimal point follows the selection.

Characters, Factory Default		Setting Item, Function, Setting Range	
T-LH T	Transmission output high limit		
1370	Sets the Transmission output high limit value.		
		s to 20 mA in direct current output.	
	Setting range:	·	
	PV, SV transmission	Transmission output low limit to Input range high limit value	
		DC voltage, current inputs: -2000 to 10000	
	MV transmission	Transmission output low limit to 105.0%	
	DV transmission	Transmission output low limit to Scaling span (*1)	
	Available only when Transm	ission output (EIT option) is ordered.	
T-LL	Transmission output	low limit	
-200	Sets the Transmission	n output low limit value.	
	This value correpond	s to 4 mA in direct current output.	
	Selection item:		
	PV, SV transmission	Input range low limit to Transmission output high limit value	
		DC voltage, current inputs: -2000 to 10000	
	MV transmission	-5.0% to Transmission output high limit value	
	DV transmission	-Scaling span to Transmission output high limit value (*1)	
	Available only when Transm	ission output (EIT option) is ordered.	
<u></u>	SV1		
	Sets SV1.		
		g low limit to Scaling high limit (*1)	
	Available when Control output OFF function or Auto/Manual control is selected in [OUT/OFF key function].		
\ <u>\</u> \{\bar{2}\b	SV2		
	• Sets SV2.		
	Setting range: Scaling low limit to Scaling high limit (*1)		
	Available for the following: **When Control output OFF function or Auto/Manual control is selected in IQUIT/OFF key function.		
	 When Control output OFF function or Auto/Manual control is selected in [OUT/OFF key function]. For BCS2, Event input (EIW, EIT, El options) is ordered. 		
	• For BCR2/BCD2, Serial c	ommunication (C5W option) or Event input (EIW, EIT, EI options) is ordered.	
, - ,(,)	·	memory) is selected in [Event input DI1/DI2 allocation].	
5 <u>3</u>	SV3		
	• Sets SV3.	or Lawre Books 4 at Carallina and high Books or o	
		g low limit to Scaling high limit (*1)	
	Available for the following:	function or Auto/Manual control is selected in [OUT/OFF key function].	
	For BCS2, Event input (E)		
	• For BCR2/BCD2, Serial communication (C5W option) or Event input (EIW, EIT, EI options) is ordered.		
1 1 11	• When \$\Bar{\Pi} \Bar{\Pi}\$ (Set value memory) is selected in [Event input DI1/DI2 allocation].		
54 <u> </u>	SV4		
1l	• Sets SV4.	a low limit to Scaling high limit (*4)	
		g low limit to Scaling high limit (*1)	
	Available for the following:When Control output OFF	function or Auto/Manual control is selected in [OUT/OFF key function].	
	For BCS2, Event input (E)		
		ommunication (C5W option) or Event input (EIW, EIT, EI options) is ordered.	
	• When □□□□	memory) is selected in [Event input DI1/DI2 allocation].	

^(*1) The placement of the decimal point follows the selection.

[EV1/EV2 Energized/De-energized]

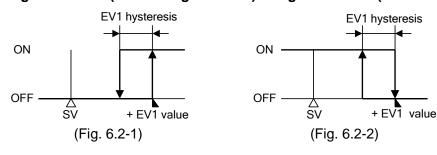
When non- (Energized) is selected, Event output 1 or 2 is conductive (ON) while the EV1/EV2 indicator is lit.

Event output 1 or 2 is not conductive (OFF) while the EV1/EV2 indicator is not lit.

When $r \not\in \Xi'$ (De-energized) is selected, Event output 1 or 2 is not conductive (OFF) while the EV1/EV2 indicator is lit.

Event output 1 or 2 is conductive (ON) while the EV1/EV2 indicator is not lit.

High limit alarm (when Energized is set) High limit alarm (when De-energized is set)



EV1 value and EV1 hysteresis represent EV1 alarm value and EV1 alarm hysteresis respectively. For EV2, read "EV2" for "EV1".

[Loop Break Alarm]

When the control action is Reverse (Heating) control:

- If the PV does not **reach** the Loop break alarm band setting within the time allotted to assess the Loop break alarm (after the MV has reached 100% or the OUT high limit value), the alarm will be activated.
- Likewise, if the PV does not **drop to** the Loop break alarm band setting within the time allotted to assess the Loop break alarm (after the MV has reached 0% or the OUT low limit value), the alarm will be activated.

When the control action is Direct (Cooling) control:

- If the PV does not **drop to** the Loop break alarm band setting within the time allotted to assess the Loop break alarm (after the MV has reached 100% or the OUT high limit value), the alarm will be activated
- Likewise, if the PV does not **reach** the Loop break alarm band setting within the time allotted to assess the Loop break alarm (after the MV has reached 0% or the OUT low limit value), the alarm will be activated.
- If Serial communication (C5W, C5 options) is added, status can be read by reading Status flag 1.

[Event Input]

• If $\square\square\square$ (Set value memory) is selected, the set value memory number by connecting between 16, 17 and 18 (BCS2) or between 8, 9 and 12 (BCR2, BCD2) as shown in the table below.

When only Event input DI1 is selected.[O: ON (Closed), X: OFF (Open)]

Set value memory number Connecting terminals	SV1	SV2
DI1 [17-18(BCS2), 9-12(BCR2, BCD2)]	X	0

When only Event input DI2 is selected.[O: ON (Closed), X: OFF (Open)]

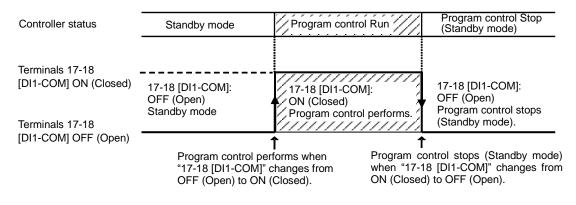
Set value memory number Connecting terminals	SV1	SV2
DI2 [16-18(BCS2), 8-12(BCR2, BCD2)]	X	0

When both Event input DI1, DI2 are selected. [O: ON (Closed), X: OFF (Open)]

Set value memory number Connecting terminals	SV1	SV2	SV3	SV4
DI1 [17-18(BCS2), 9-12(BCR2, BCD2)]	×	0	X	0
DI2 [16-18(BCS2), 8-12(BCR2, BCD2)]	×	×	0	0

- Preset value of \$\overline{\pi} \overline{\pi} \overline{\pi}\$ (Preset output 1 ON/OFF) and \$\overline{\pi} \overline{\pi} \overline{\pi}\$ (Preset output 2 ON/OFF) can be set in [OUT1/OUT2 MV preset value (p.77)] in Engineering mode 1.
- If \$\Bar{\text{\text{\$\pi}}} \Bar{\text{\$\pi}}\$ (Preset output 2 ON/OFF) is selected in [Event input DI1 allocation], and \$\Bar{\text{\$\pi}} \Bar{\text{\$\pi}}\$ (Auto/Manual control) is selected in Event input DI2 allocation, and if DI1-COM and DI2-COM terminals are turned ON (Closed) simultaneously, then Preset output 2 will be given priority, and control starts with the MV set in [OUT1/OUT2 MV preset value (p.77)] in Engineering mode 1. In this case, control will be switched to manual control, and MV cannot be changed via keypad.
- Signal edge action from OFF to ON / ON to OFF is engaged.
- If $\square \square \square \square \square$ (Program control RUN/STOP) is selected in [Event input DI1 allocation], the following action will be performed.

However, only when power is turned ON, Level action is engaged - which follows the input status [ON (Closed) or OFF (Open)] of Event input DI1.



(Fig. 6.2-3)

- OR calculation [if any one is ON (closed), the function activates] begins if the same functions except [III] / (Set value memory) have been selected in [Event input DI1/DI2 allocation].

 If any terminals DI1-COM or DI2-COM is ON (closed), the function activates.
- If any function except \(\bigcap \) I\(\bigcap \) (Program control Advance function) is selected in [Event input DI1/DI2 allocation], Level action is engaged when power is turned ON which follows the input status [ON (Closed) or OFF (Open)] of Event input DI1/DI2.

[Time Signal Output]

Time signal output activates during Time signal output ON time within each step (number). Time signal output ON time follows Time signal output OFF time after the program control starts.

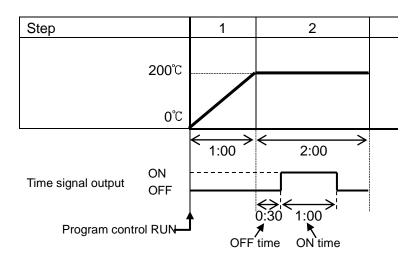
The following program pattern shows that the temperature rises to 200°C for 1 hour, and stays at 200°C for 2 hours after Program control starts.

Step	1	2
Step SV	200℃	200℃
Step time	1:00	2:00

Time signal output (Fig. 6.2-4) is shown when set as follows.

• TS1/TS2 output step number: 2

• TS1/TS2 OFF time: 0:30 • TS1/TS2 ON time: 1:00



(Fig. 6.2-4)

Time signal output is effective within the step set in [TS1/TS2 output step number]. For example, if TS1/TS2 ON time is set to "2:00" at the above, Time signal output is turned OFF at the moment when Step 2 is completed.

7. Settings

In this section, Main setting mode, Sub setting mode, Engineering mode 1 and Engineering mode 2 will be explained.

7.1 Main Setting Mode

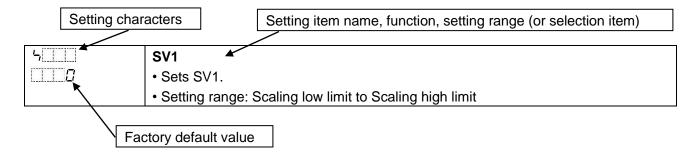
To enter Main setting mode, press the © key in RUN mode.

Use the \wedge or \vee key for settings (or selections).

To register the set data, use the Q key.

Explanation of setting items:

- Upper left: PV Display: Indicates setting characters.
- Lower left: SV Display: Indicates factory default value.
- Right side: Indicates the setting item, explanation of its function and setting range (or selection item).



Depending on the selection in [OUT/OFF key function], corresponding item is indicated.

When 'Control output OFF function' or 'Auto/Manual control' is selected in [OUT/OFF key function]:

Characters, Factory Default	Setting Item, Function, Setting Range
4	SV1
	• Sets SV1.
	Corresponds to [SV1] in Initial setting mode.
	Setting range:
	Scaling low limit to Scaling high limit (*1)
<u> </u>	SV2 (*2)
	• Sets SV2.
	Corresponds to [SV2] in Initial setting mode.
	Setting range:
	Scaling low limit to Scaling high limit (*1)
<u>53</u>	SV3 (*2)
	• Sets SV3.
	Corresponds to [SV3] in Initial setting mode.
	Setting range:
	Scaling low limit to Scaling high limit (*1)
54	SV4 (*2)
	• Sets SV4.
	Corresponds to [SV4] in Initial setting mode.
	Setting range:
	Scaling low limit to Scaling high limit (*1)

^(*1) The placement of the decimal point follows the selection.

Available for the following:

- For BCS2, when Event input (EIW, EI option) is ordered
- For BCR2/BCD2, when Serial communication (C5W option) or Event input (EIW, EIT, EI options) is ordered.
- When □□□□ ! (Set value memory) is selected in [Event input DI1/DI2 allocation]

When 'Program control' is selected in [OUT/OFF key function]:

Characters, Factory Default	Setting Item, Function, Setting Range
4	Step 1 SV
	Sets Step 1 SV.
	Setting range:
	Scaling low limit to Scaling high limit (*1)
$\Gamma \square_{-} I$	Step 1 time
00.00	Sets Step 1 time.
	Setting range:
	, or 00:00 to 99:59
	If is set, Step 1 time will be held, and Fixed value control will be performed
	using Step 1 SV.
	Step 1 wait value
	Sets Step 1 wait value.
	Setting range:
	0 to 20% of input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1)
	Setting the value to 0 disables this Wait function.

 $^{(\}ensuremath{^{*}}\xspace1)$ The placement of the decimal point follows the selection.

^(*2) When $\square \square \square \square \square$ (Set value memory) is selected in [Event input DI1 allocation] or [Event input DI2 allocation], SV1 and SV2 can be set. When $\square \square \square \square$ (Set value memory) is selected in both [Event input DI1 allocation] and [Event input DI2 allocation], SV1, SV2, SV3 and SV4 can be set.

Characters, Factory Default	Setting Item, Function, Setting Range
52	Step 2 SV
	Sets Step 2 SV.
	Setting range:
<u></u>	Scaling low limit to Scaling high limit (*1)
	Step 2 time
00.00	• Sets Step 2 time.
	• Setting range:
	If EEEE is set, Step 2 time will be held, and Fixed value control will be performed
	using Step 2 SV.
	Step 2 wait value
	• Sets Step 2 wait value.
	• Setting range:
	0 to 20% of input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1)
	Setting the value to 0 disables this Wait function.
43	Step 3 SV
	• Sets Step 3 SV.
	Setting range:
	Scaling low limit to Scaling high limit (*1)
	Step 3 time
0000	• Sets Step 3 time.
	• Setting range:
	====, or 00:00 to 99:59
	If is set, Step 3 time will be held, and Fixed value control will be performed
- m -	using Step 3 SV.
	Step 3 wait value
	• Sets Step 3 wait value.
	Setting range: 0 to 20% of input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1)
	Setting the value to 0 disables this Wait function.
44	Step 4 SV
	• Sets Step 4 SV.
	• Setting range:
	Scaling low limit to Scaling high limit (*1)
<u> </u>	Step 4 time
0000	Sets Step 4 time.
	Setting range:
	= = = , or 00:00 to 99:59
	If is set, Step 4 time will be held, and Fixed value control will be performed
	using Step 4 SV.

^(*1) The placement of the decimal point follows the selection.

Characters, Factory Default	Setting Item, Function, Setting Range
JI_ Y	Step 4 wait value
	Sets Step 4 wait value.
	Setting range:
	0 to 20% of input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1)
	Setting the value to 0 disables this Wait function.
45	Step 5 SV
	Sets Step 5 SV.
	Setting range:
	Scaling low limit to Scaling high limit (*1)
Γ <u></u> 5	Step 5 time
0000	Sets Step 5 time.
	Setting range:
	=====, or 00:00 to 99:59
	If Fig. 1 is set, Step 5 time will be held, and Fixed value control will be performed
	using Step 5 SV.
5_5	Step 5 wait value
	Sets Step 5 wait value.
	Setting range:
	0 to 20% of input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1)
	Setting the value to 0 disables this Wait function.
45	Step 6 SV
	Sets Step 6 SV.
	Setting range:
	Scaling low limit to Scaling high limit (*1)
Γ	Step 6 time
0000	Sets Step 6 time.
	Setting range:
	=====, or 00:00 to 99:59
	If is set, Step 6 time will be held, and Fixed value control will be performed
(- r	using Step 6 SV.
<u>5</u>	Step 6 wait value
	Sets Step 6 wait value.
	Setting range:
	0 to 20% of input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1)
, - ,	Setting the value to 0 disables this Wait function.
'- 7	Step 7 SV
	• Sets Step 7 SV.
	• Setting range:
	Scaling low limit to Scaling high limit (*1)

 $^{(\}ensuremath{^{\star}}\xspace1)$ The placement of the decimal point follows the selection.

Characters, Factory Default	Setting Item, Function, Setting Range
7_7	Step 7 time
0000	Sets Step 7 time.
	Setting range:
	=====, or 00:00 to 99:59
	If in it is set, Step 7 time will be held, and Fixed value control will be performed
	using Step 7 SV.
	Step 7 wait value
	• Sets Step 7 wait value.
	• Setting range:
	0 to 20% of input span DC voltage, current inputs: 0 to 20% of scaling span (*1)
	Setting the value to 0 disables this Wait function.
<i>48</i>	Step 8 SV
	• Sets Step 8 SV.
11	• Setting range:
	Scaling low limit to Scaling high limit (*1)
T 8	Step 8 time
0000	Sets Step 8 time.
	Setting range:
	====, or 00:00 to 99:59
	If FFF is set, Step 8 time will be held, and Fixed value control will be performed
	using Step 8 SV.
J_B	Step 8 wait value
	Sets Step 8 wait value.
	Setting range:
	0 to 20% of input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1)
\ <u>\</u>	Setting the value to 0 disables this Wait function.
	Step 9 SV
	• Sets Step 9 SV.
	Setting range: Scaling low limit to Scaling high limit (*1)
rs	Step 9 time
0000	• Sets Step 9 time.
	Setting range:
	====, or 00:00 to 99:59
	If EEEE is set, Step 9 time will be held, and Fixed value control will be performed
	using Step 9 SV.
ŭg	Step 9 wait value
	Sets Step 9 wait value.
	Setting range:
	0 to 20% of input span
	DC voltage, current inputs: 0 to 20% of scaling span (*1)
	Setting the value to 0 disables this Wait function.

^(*1) The placement of the decimal point follows the selection.

7.2 Sub Setting Mode

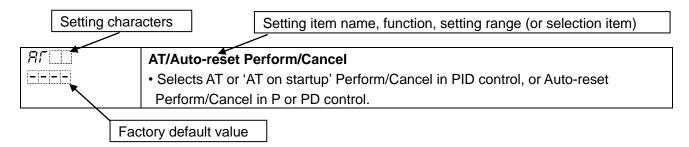
To enter Sub setting mode, press the \wedge and \otimes keys (in that order) together in RUN mode.

Use the \wedge or \vee key for settings (or selections).

To register the set data, use the Q key.

Explanation of setting items:

- Upper left: PV Display: Indicates setting characters.
- Lower left: SV Display: Indicates factory default value.
- Right side: Indicates the setting item, explanation of its function and setting range (or selection item).



Characters,				
Factory Default	Setting Item, Function, Setting Range			
Ar	AT/Auto-reset Perform/Cancel			
	• Selects A7	Selects AT or 'AT on startup' Perform/Cancel in PID control action, or Auto-reset		
	Perform/C	ancel in P or PD control action.		
	Refer to S	ections '8.5 Setting PID Constants (by Performing AT)' (p. 84), and		
	'8.6 Perfor	ming Auto-reset' (p. 87).		
	Selection	item:		
		AT/AT on startup/Auto-reset Cancel		
	R/	AT Perform		
	85_5	'AT on startup' Perform		
	r hEr	Auto-reset Perform		
	Not available	for ON/OFF control or PI control.		
P	OUT1 prop	ortional band		
	Sets OUT	1 proportional band.		
	 Setting ran 	ge:		
		ıple, RTD input without decimal point: 0 to input span℃ (℉)		
		ple, RTD input with decimal point: 0.0 to input ${ t span}^{ t c}$ (${ t F}$)		
	DC voltage, current inputs: 0.0 to 1000.0%			
* ***	1	omes ON/OFF control when set to 0 or 0.0.		
	Integral tin			
	• Sets the in			
		can be performed when PD is control action (I = 0).		
		nge: 0 to 3600 seconds		
		e value to 0 disables integral action. if OUT1 is in ON/OFF control.		
	Derivative			
50		erivative time.		
		nge: 0 to 1800 seconds		
		value to 0 disables derivative action.		
		if OUT1 is in ON/OFF control.		
L				

Characters, Factory Default	Setting Item, Function, Setting Range
Arū[ARW
<u> </u>	Sets ARW (anti-reset windup).
	Setting range: 0 to 100%
	Available only when OUT1 is in PID control.
rhEF	Manual reset
	Sets the reset value manually.
	If auto-reset is executed, the reset value will be automatically set.
	Setting range: ±Proportional band value
	If a value larger than 100.0% is set in [OUT1 proportional band], the setting range
	will be ±100.0.
	Available when OUT1 is in P or PD control.
	OUT1 proportional cycle
□□□30	Sets proportional cycle for OUT1.
Factory default: • Relay contact	For relay contact output, if the proportional cycle time is decreased, the frequency
output: 30 sec.	of the relay action increases, and the life of the relay contact is shortened.
Non-contact voltage	Setting range: 0.5, or 1 to 120 seconds
output: 3 sec.	Not available for direct current output type, or if OUT1 is in ON/OFF control.
<u> </u>	OUT1 ON/OFF hysteresis
l ιΩ	Sets ON/OFF hysteresis for OUT1.
	• Setting range: 0.1 to 1000.0℃ (℉),
	DC voltage, current inputs: 1 to 10000 (*1)
* * *(******)	Available only when OUT1 is in ON/OFF control.
	OUT1 high limit
	• Sets OUT1 high limit value.
	• Setting range: OUT1 low limit value to 100%
	(Direct current output type: OUT1 low limit value to 105%)
	Not available if OUT1 is relay contact output type or non-contact voltage output type, and if OUT1 is in
	ON/OFF control.
oLL	OUT1 low limit
	• Sets OUT1 low limit value.
	• Setting range: 0% to OUT1 high limit value
	(Direct current output type: -5% to OUT1 high limit value)
	Not available if OUT1 is relay contact output type or non-contact voltage output type, and if OUT1 is in
or Al	ON/OFF control.
	• Sets changing value of OUT1 MV for 1 second.
tankankani 🚅	See 'OUT1 rate-of-change' on p. 63.
	• Setting range: 0 to 100 %/second
	Setting tange. 0 to 100 % second Setting the value to 0 disables this function.
	Not available if OUT1 is in ON/OFF control.
	Not available if OUT1 is in ON/OFF control.

^(*1) The placement of the decimal point follows the selection.

Characters, Factory Default	Setting Item, Function, Setting Range		
sAsi	OUT2 cooling method		
RI -	Selects OUT2 cooling method from air, oil or water cooling.		
	OUT2 proportional band		
	Air cooling		
	Oil cooling		
	Water cooling		
	SV		
	(Fig. 7.2-1)		
	Selection item:		
	Air cooling (linear characteristics)		
	Oil cooling (1.5th power of the linear characteristics)		
	Water cooling (2nd power of the linear characteristics)		
	Available when Heating/Cooling control [DS, DA, EV2(*1), EV2+D□ options] is ordered.		
- 1 m	Not available if OUT1 is in ON/OFF control or if OUT2 is in ON/OFF control.		
P_6	OUT2 proportional band		
	• Sets the proportional band for OUT2.		
	• Setting range:		
	Thermocouple, RTD input without decimal point: 0 to Input span °C (°F)		
	Thermocouple, RTD input with decimal point: 0.0 to Input span °C (°F)		
	DC voltage, current inputs: 0.0 to 1000.0%		
	When set to 0 or 0.0, OUT2 becomes ON/OFF control, and the item selected in		
	[OUT2 cooling method] will be disabled. Available when Heating/Cooling control [DS, DA, EV2(*1), EV2+D□ options] is ordered.		
	Not available if OUT1 is in ON/OFF control.		
c_b[]	OUT2 proportional cycle		
	Sets proportional cycle for OUT2.		
Factory default:	For relay contact output, if the proportional cycle time is decreased, the frequency		
EV2(*2), EV2+DR:	of the relay action increases, and the life of the relay contact is shortened.		
30 sec. DS: 3 sec.	Setting range: 0.5, or 1 to 120 seconds		
DO. 3 Sec.	Available when Heating/Cooling control [DS, DA, EV2(*1), EV2+D□ options] is ordered.		
	Not available if OUT1 is in ON/OFF control, OUT2 is in ON/OFF control or OUT2 is direct current output type.		
HY55	OUT2 ON/OFF hysteresis		
□□ <i>t</i> Ø	Sets ON/OFF hysteresis for OUT2.		
	• Setting range: 0.1 to 1000.0℃ (℉),		
	DC voltage, current inputs: 1 to 10000 (*2)		
	Available when Heating/Cooling control [DS, DA, EV2(*1), EV2+D□ options] is ordered.		
* * *	Available when OUT2 is in ON/OFF control.		
aLHb	OUT2 high limit		
□ <i>100</i>	• Sets OUT2 high limit value.		
	• Setting range: OUT2 low limit value to 100%		
	(Direct current output type: OUT2 low limit value to 105%)		
	Available when Heating/Cooling control [DS, DA, EV2(*1), EV2+D□ options] is ordered.		
	Not available if OUT2 is relay contact output type or non-contact voltage output type and OUT1 is in ON/OFF control.		
	Not available if OUT2 is relay contact output type or non-contact voltage output type and OUT2 is in ON/OFF		
	control.		

^(*1) When 🗆 19 (Heating/Cooling control relay contact output) is selected in [Event output EV2 allocation]}.

^(*2) The placement of the decimal point follows the selection.

Characters,	Setting Item, Function, Setting Range			
Factory Default				
oLLb	OUT2 low I			
		2 low limit value.		
	Setting range: 0% to OUT2 high limit value			
	(Direct current output type: -5% to OUT2 high limit value) Available when Heating/Cooling control [DS, DA, EV2(*1), EV2+D□ options] is ordered. Not available if OUT2 is relay contact output type or non-contact voltage output type and OUT1 is in ON/OF control. Not available if OUT2 is relay contact output type or non-contact voltage output type and OUT2 is in ON/OF			
 db	control.			
	Overlap/Dead band Sets the overlap band or dead band for OUT1 and OUT2.			
		•	ad band for OUTT and OUTZ.	
		e: Dead band		
		e: Overlap band	%c	
		nge: -200.0 to 200.0		
		e, current inputs: -2		
<i>r</i>			ol [DS, DA, EV2(*1), EV2+D□ options] is ordered.	
conf HERT	Direct/Reve		tion of the state	
lucui	Selects either Reverse (Heating) or Direct (Cooling) control action.			
	HERF.	Reverse (Heatin	·	
	Direct (Cooling) action			
8 1	EV1 alarm			
	• Sets EV1 alarm value.			
	Corresponds to [EV1 alarm value] in Initial setting mode.			
	EV1 alarm value matches EV1 low limit alarm value in the following cases:			
	☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐			
	allocation].			
	Setting ran	<u> </u>	(1 , ,), , , , , , , , , , , , , , , ,	
	High limit al		-(Input span) to Input span °C (°F) (*2) (*3)	
	Low limit ala		-(Input span) to Input span °C (°F) (*2) (*3)	
	High/Low lir		0 to Input span °C (°F) (*2) (*3)	
	High/Low lir alarm	nits independent	0 to Input span °C (°F) (*2) (*3)	
	High/Low lir	nit range alarm	0 to Input span °C (°F) (*2) (*3)	
	High/Low lir	nit range	0 to Input span °C (°F) (*2) (*3)	
	independen	t alarm		
	Process hig		Input range low limit to Input range high limit (*2) (*4)	
	Process low		Input range low limit to Input range high limit (*2) (*4)	
		th standby alarm	-(Input span) to Input span °C (°F) (*2) (*3))	
		th standby alarm	-(Input span) to Input span °C (°F) (*2) (*3)	
		nits with standby	0 to Input span °C (°F) (*2) (*3)	
	alarm	· ,		
		nits with standby	0 to Input span °C (°F) (*2) (*3)	
	independen	· ·		
	<u>.</u>		l (Alarm output, High limit alarm) to □□ l (Alarm output, High/Low	
	limits with star	dby independent alarm)	is selected in [Event output EV1 allocation].	

^(*1) When 🗍 '9 (Heating/Cooling control relay contact output) is selected in [Event output EV2 allocation] (*2) The placement of the decimal point follows the selection.
(*3) For DC voltage, current inputs, the input span is the same as the scaling span.

^(*4) For DC voltage, current inputs, input range low (or high) limit value is the same as scaling low (or high) limit value.

Characters,	Setting Item, Function, Setting Range
Factory Default	Jetting Item, I unction, Setting Nange
A IH	EV1 high limit alarm value
	Sets EV1 high limit alarm value.
	This value is available only for the following:
	□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□
	output, High/Low limit range independent alarm), or 🖂 🔁 (Alarm output,
	High/Low limits with standby independent alarm) is selected in [Event output EV1
	allocation].
	Corresponds to [EV1 high limit alarm value] in Initial setting mode.
	Setting range: Same as those of EV1 alarm value
<i>R2</i>	EV2 alarm value
	Sets EV2 alarm value.
	Corresponds to [EV2 alarm value] in Initial setting mode.
	EV2 alarm value matches EV2 low limit alarm value in the following cases:
	□□□□□ (Alarm output, High/Low limits independent alarm), □□□□ (Alarm
	output, High/Low limit range independent alarm), or 🖂 🛱 (Alarm output
	High/Low limits with standby independent alarm) is selected in [Event output
	EV2 allocation].
	Setting range: Same as those of EV1 alarm value
	Available when Event output EV2 (EV2, EV2+D options) is ordered.
	Available only when \$\sum \mathbb{G} \mathbb{G}\$! (Alarm output, High limit alarm) to \$\sum \mathbb{G}\$!2 (Alarm output, High/Low limits with
 R2H	standby independent alarm) is selected in [Event output EV2 allocation].
	EV2 high limit alarm value
	Sets EV2 high limit alarm value. This value is excluded a poly for the following:
	This value is available only for the following: \$\Bigcius Big G \text{\tilitet{\text{\ti}\text{\text{\text{\tex{
	output, High/Low limit range independent alarm), or $\Box \Box \Box \Box \Box \Box \Box$ (Alarm output,
	High/Low limits with standby independent alarm) is selected in [Event output EV2]
	allocation].
	Corresponds to [EV2 high limit alarm value] in Initial setting mode.
	Setting range: Same as those of EV1 alarm value
	Available when Event output EV2 (EV2, EV2+D□ options) is ordered.
H I	Heater burnout alarm 1 value
0.0	Sets the heater current value for Heater burnout alarm 1.
H I and CT1	Corresponds to [Heater burnout alarm 1 value] in Initial setting mode.
	Characters H i and CT1 current value are indicated alternately on the PV Display.
current value are alternately indicated	When OUT1 is ON, the CT1 current value is updated.
on the PV Display.	When OUT1 is OFF, the unit memorizes the previous value when OUT1 was ON.
on the r v Display.	Upon returning to set limits, the alarm will stop.
	Setting range:
	20 A: 0.0 to 20.0 A
	100 A: 0.0 to 100.0 A
	Setting to 0.0 disables the alarm.
	Not available for direct current output type.
	Available only when Heater burnout alarm (C5W, EIW, W options) is ordered.

Characters, Factory Default	Setting Item, Function, Setting Range
H2	Heater burnout alarm 2 value
	Sets the heater current value for Heater burnout alarm 2.
H∄ and CT2	Available only when using 3-phase.
current value are	Corresponds to [Heater burnout alarm 2 value] in Initial setting mode.
alternately	Characters HZ and CT2 current value are indicated alternately on the PV
indicated on the	Display.
PV Display.	When OUT1 is ON, the CT2 current value is updated.
	When OUT1 is OFF, the unit memorizes the previous value when OUT1 was ON.
	Upon returning to set limits, the alarm will stop.
	Setting range:
	20 A: 0.0 to 20.0 A
	100 A: 0.0 to 100.0 A
	Setting to 0.0 disables the alarm.
	Not available for direct current output type.
80 0 <u>-</u>	Available only when Heater burnout alarm (C5W, EIW, W options) is ordered.
LP_[Loop break alarm time
	Sets the time to assess the Loop break alarm.
	Corresponds to [Loop break alarm time] in Initial setting mode.
	Refer to 'Loop Break Alarm' on p.50.
	Setting range: 0 to 200 minutes
	Setting to 0 (zero) disables the alarm.
LP_H	Loop break alarm band
	Sets the temperature to assess the Loop break alarm.
	Corresponds to [Loop break alarm band] in Initial setting mode.
	Refer to 'Loop Break Alarm' on p.50.
	• Setting range: Thermosouple, PTD input without decimal point: 0 to 150°C (°E)
	Thermocouple, RTD input without decimal point: 0 to 150°C (˚F) Thermocouple, RTD input with decimal point: 0.0 to 150.0°C (˚F)
	DC voltage, current inputs: 0 to 1500 (*1)
	Setting to 0 (zero) disables the alarm.

^(*1) The placement of the decimal point follows the selection.

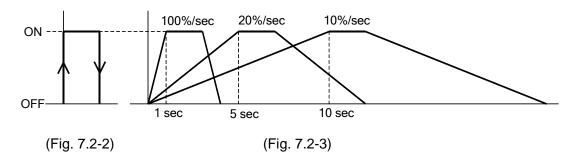
[OUT1 rate-of-change]

For Heating control, if PV is lower than SV, the output is generally turned from OFF to ON as shown in (Fig. 7.2-2).

If OUT1 rate-of-change is set, the output can be changed by the rate-of-change (Fig. 7.2-3).

This control is suitable for high temperature heaters (which are made from molybdenum, tungsten or platinum, etc., and used at approx. 1500 to 1800°C) which are easily burnt out from turning on electricity rapidly.

Usual output Output when Output rate-of-change is set



7.3 Engineering Mode 1

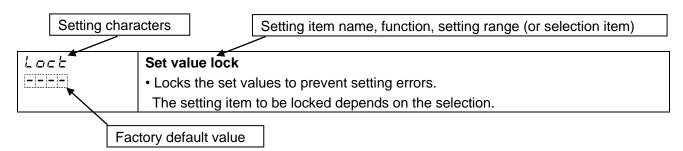
To enter Engineering mode 1, press and hold the \wedge and \vee keys (in that order) together for 3 seconds in RUN mode.

Use the \wedge or \vee key for settings (or selections).

To register the set data, use the Q key.

Explanation of setting items:

- Upper left: PV Display: Indicates setting characters.
- Lower left: SV Display: Indicates factory default value.
- Right side: Indicates the setting item, explanation of its function and setting range (or selection item).



Characters, Factory Default	Setting Item, Function, Setting Range			
Lock	Set value lock			
	Locks the set values to prevent setting errors.			
	The se	tting item	to be locked depends on the select	tion.
	Selection item:			
	Change via Ke		Change via Keypad	Change via Software Communication
		Unlock	All set values can be changed.	All set values can be
	Loci	Lock 1	None of the set values can be	changed.
			changed.	
	Loc2	Lock 2	In Fixed value control, only SV	
			and Alarm value can be changed.	
			In Program control, Step SV,	
			Step time and Alarm value can	
			be changed.	
	Loc3	Lock 3	All set values can be changed.	Setting items – except Input
	Loc4	Lock 4	None of the set values can be	type, Controller/Converter –
			changed.	can be changed temporarily
	Loc5	Lock 5	In Fixed value control, only SV	via software communication.
			and Alarm value can be changed.	However, if power is turned
			In Program control, Step SV,	ON again, the setting values
			Step time and Alarm value can	revert to the values before
			be changed.	Lock 3, 4 or 5 was selected.

Factory Default EB! Selects Event input DI1 allocation Selects Event input DI1 from the Event Input Allocation Table. Corresponds to [Event input DI1 allocation] in Initial setting mode. Selection item: Event Input Allocation Table Event Input Allocation Table Event input Input ON Input OFF (Open) DDD No event DDD Set value memory Control ON/OFF Control OFF Control ON Control output function DDD Direct/Reverse Direct Reverse Always effection action DDD Preset output 1 Preset output Usual control If sensor is but out, the unit	t OFF
Selects Event input DI1 from the Event Input Allocation Table. Corresponds to [Event input DI1 allocation] in Initial setting mode. Selection item: Event Input Allocation Table Event input Input ON (Open) No event ODD No event ODD Set value memory Control ON/OFF Control OFF Control ON Control output function ODD Direct/Reverse Direct Reverse Always effection ON/OFF Preset output 1 Preset output Usual control If sensor is but out, the unit	t OFF
Corresponds to [Event input DI1 allocation] in Initial setting mode. • Selection item: Event Input Allocation Table Event input Input ON (Open) GDD No event DDD Set value memory (*) Direct/Reverse Direct Reverse Always effection action DI Preset output 1 Preset output Usual control If sensor is but out, the unit	t OFF
Selection item: Event Input Allocation Table Event input Input ON (Open) DOD No event DOD Set value memory Control ON/OFF Control OFF Control ON Control output function Direct/Reverse Direct Reverse Always effection CODY Preset output 1 Preset output Usual control If sensor is buout, the unit	t OFF
Event Input Allocation Table Event Input Input ON Input OFF Remark	t OFF
Event input function (Closed) (Open) ODD No event ODD Set value memory Control ON/OFF Control OFF Control ON Control output function ODD Direct/Reverse action ON/OFF Preset output 1 ON/OFF ON/O	t OFF
function (Closed) (Open) Remark □□□□ No event □□□□ Set value memory □□□□ Control ON/OFF Control OFF Control ON Control output (*)	t OFF
No event GGG I Set value memory Control ON/OFF Control OFF Control ON Control output function (*) function GGG Direct/Reverse Direct Reverse Always effection action action GGG I Set value memory (*) Freset output Direct Direct Always effection GGG Preset output 1 Preset output Usual control If sensor is but out, the unit out, the unit	
Set value memory Control ON/OFF Control OFF Control ON (*) Direct/Reverse action Direct action Preset output 1 ON/OFF Set value memory Control OFF Control ON Footrol ON Control ON Always effection Control ON Footrol ON Footrol ON Footrol ON Control ON Footrol ON Fo	
Control ON/OFF Control OFF Control ON Control output function Direct/Reverse action action DIGGY Preset output 1 ON/OFF ON/OFF Control ON Control output function Control OFF Control ON Control output function Reverse action Control OFF Control ON Control output function Freset output Direct action ON/OFF ON/OFF Output ON/OFF Output out, the unit	
(*) function Direct/Reverse Direct Reverse Always effection action action DIGGY Preset output 1 ON/OFF Preset output Usual control If sensor is but out, the unit	
Direct/Reverse Direct Reverse Always effection action DDD Preset output 1 Preset output Usual control If sensor is but out, the unit	ve
Preset output 1 Preset output Usual control If sensor is but out, the unit	
ON/OFF out, the unit	
	rnt
maintains con	trol
with the prese	t MV.
☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐☐	tains
ON/OFF control with the	e
preset MV.	
□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□	
control control Auto/Manual control	
is selected in	-
OFF key func	
Remote Local Effective when External settir	
input (EIT opt	•
ordered.	011) 13
□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□	hen
RUN/STOP power is turned	
Program control Holding Not holding Level action w	
Holding/ power is turned	
Not holding	
□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□	
Advance function function	
□□□ / / Integral action Integral action Usual Control continu	
holding holding integral action with the integral	
value being he	eld.
For BCS2, available only when Event input (EIW, EIT, EI options) is ordered. For BCR2/BCD2, available when Serial communication (C5W option) or Event input (EIW, EIT, EI options) ordered.	
(*): "Control ON/OFF" is not displayed when "Auto/Manual control" or "Program control" is selected f "OUT/OFF key function".	or
E⊞ ₽ Event input DI2 allocation	
• Selects Event input DI2 from the Event Input Allocation Table.	l
Corresponds to [Event input DI2 allocation] in Initial setting mode.	
Selection item: Same as Event input DI1 allocation	
For BCS2, available only when Event input (EIW, EI options) is ordered. For BCR2/BCD2, available when Serial communication (C5W option) or Event input (EIW, EIT, EI option) ordered.	

Characters,	Setting Item, Function, Setting Range				
Factory Default					
E80	Event output EV1 allocation				
		Event output EV1 from the Event Outp			
		onds to [Event output EV1 allocation] in	S		
	When changing Event output EV1 allocation, refer to Section "8.10 Items to be				
	Initialized by Changing Settings" (p.98).				
	Selection item:				
	Event Ou	tput Allocation Table			
	000	No event			
	00 /	Alarm output, High limit alarm			
	002	Alarm output, Low limit alarm			
	003	Alarm output, High/Low limits alarm			
	004	Alarm output, High/Low limits			
		independent alarm			
	005	Alarm output, High/Low limit range			
		alarm			
	005	Alarm output, High/Low limit range			
		independent alarm			
	007	·			
	008	Alarm output, Process high alarm			
	000	Alarm output, Process low alarm			
	003	Alarm output, High limit with standby			
	111111111111111111111111111111111111111	Alarm output, Low limit with			
		standby			
		Alarm output, High/Low limits with standby alarm			
	_0 i2	Alarm output, High/Low limits			
		with standby independent alarm			
	13	Heater burnout alarm output			
		Loop break alarm output			
	ID 15	Time signal output	Turns OFF or ON during Program		
			control, by setting OFF time and		
			ON time within the step set in		
			[Step number].		
	LO 15	Output during AT	Turns ON during AT.		
	[] []	Pattern end output	Turns ON when Program control		
			ends, and remains ON until turned		
			OFF by pressing the ® key.		
	_0 <i>18</i>	Output by communication	Turns OFF or ON by communication		
		command	command 00E4H during Serial		
			communication.		
			B0 EV1 output 0: OFF		
			1: ON		
			B1 EV2 output 0: OFF		
	<u> </u>		1: ON		
RIER	EV1 alarr	n value 0 Enabled/Disabled			
no	• When E	V1 alarm value is 0 (zero), alarm action	n can be Enabled or Disabled.		
		onds to [EV1 alarm value 0 Enabled/Di			
	Selection	-	-		
	מח	Disabled			
	4E5	Enabled			
		hen $\Box \Box \Box \Box$ (Alarm output, High limit alarm) to $\Box \Box$			
		t alarm), □□□□ (Alarm output, High limit with sta			
	High/Low limits with standby independent alarm) are selected in [Event output EV1 allocation].				

Characters,	Setting Item, Function, Setting Range				
Factory Default		,			
8 1	EV1 alarm value				
	• Sets EV1 alarm value.				
	Corresponds to [EV1 alarm v				
	EV1 alarm value matches EV1 low limit alarm value in the following cases:				
	□□□□□ (Alarm output, High/Low limits independent alarm), □□□□ (Alarm				
	output, High/Low limit range independent alarm), or 🖫 💤 (Alarm output,				
	<u> </u>	by independent alarm) is selected in [Event output			
	EV1 allocation].				
	• Setting range: High limit alarm -(Input span) to Input span °C (°F) (*1) (*2) Low limit alarm -(Input span) to Input span °C (°F) (*1) (*2) High/Low limits alarm 0 to Input span °C (°F) (*1) (*2) High/Low limits independent 0 to Input span °C (°F) (*1) (*2)				
	alarm	0 to local to a con %0 (%T) (1) (1)			
	High/Low limit range alarm	0 to Input span °C (°F) (*1) (*2)			
	High/Low limit range independent alarm Process high alarm Process low alarm High limit with standby alarm Low limit with standby alarm O to Input span °C (°F) (*1) (*2) Input range low limit to Input range high limit (*1) (*3) -(Input span) to Input span °C (°F) (*1) (*2) -(Input span) to Input span °C (°F) (*1) (*2)				
	High/Low limits with standby	0 to Input span $^{\circ}$ ($^{\circ}$ F) (*1) (*2)			
	alarm	0 to input opair = (1)(1)(2)			
	High/Low limits with standby	0 to Input span °C (°F) (*1) (*2)			
	independent alarm				
	Available when any alarm from $\square \square \square$	/ (Alarm output, High limit alarm) to ロロルス (Alarm output, High/Low			
	limits with standby independent alarm)	is selected in [Event output EV1 allocation].			
R H□	EV1 high limit alarm value				
	 Sets EV1 high limit alarm val 	ue.			
	This value is available only fo	@#************************************			
	`	h/Low limits independent alarm), 🗆 🗆 🗸 (Alarm			
	output, High/Low limit range independent alarm), $\Box\Box$ \Box \Box (Alarm output,				
	High/Low limits with standby independent alarm) is selected in [Event output				
	EV1 allocation].				
	•	nit alarm value] in Initial setting mode.			
<u> </u>	Setting range: Same as thos	e of EV1 alarm value			
R IHY □□ (O	EV1 alarm hysteresis				
	 Sets EV1 alarm hysteresis. 	nysteresis] in Initial setting mode.			
	• Setting range: 0.1 to 1000.0°				
	DC voltage, current inputs: 1	` '			
	•	/ (Alarm output, High limit alarm) to □□ /ਟ (Alarm output, High/Low			
		is selected in [Event output EV1 allocation].			
L	startaby indoportable diamin				

^(*1) The placement of the decimal point follows the selection.

^(*2) For DC voltage, current inputs, the input span is the same as the scaling span.

^(*3) For DC voltage, current inputs, input range low (or high) limit value is the same as scaling low (or high) limit value.

Characters, Factory Default	Setting Item, Function, Setting Range		
8 189	EV1 alarm delay time		
	Sets EV1 alarm action delay time.		
	Corresponds to [EV1 alarm delay time] in Initial setting mode.		
	When setting time has elapsed after the input enters the alarm output range, the		
	alarm is activated.		
	Setting range: 0 to 10000 seconds		
	Available when any alarm from $\square \square \square$ $!$ (Alarm output, High limit alarm) to $\square \square$ $! ewline : \exists (Alarm output, High/Low)$		
	limits with standby independent alarm) is selected in [Event output EV1 allocation].		
A ILA	EV1 alarm Energized/De-energized		
noñL	Selects Energized/De-energized status for EV1 alarm.		
	Corresponds to [EV1 alarm Energized/De-energized] in Initial setting mode.		
	(Refer to 'EV1/EV2 Energized/De-energized' on p.50.)		
	Selection item:		
	nont Energized		
	ァミガト De-energized		
	Available when any alarm from $\square \square \square$! (Alarm output, High limit alarm) to $\square \square$! \supseteq (Alarm output, High/Low		
7= 5. 55	limits with standby independent alarm) is selected in [Event output EV1 allocation].		
[5]	TS1 output step number		
	Sets the step number for which Time signal output TS1 is turned OFF or ON		
	during Program control.		
	Corresponds to [TS1 output step number] in Initial setting mode.		
	Setting range: 1 to 9		
A-	Available only when 🗆 15 (Time signal output) is selected in [Event output EV1 allocation].		
[TS1 OFF time		
0000	Sets Time signal output TS1 OFF time.		
	Corresponds to [TS1 OFF time] in Initial setting mode.		
	• Setting range: 00:00 to 99:59 (*1)		
·- , ,	Available only when \$\sum 0 15\$ (Time signal output) is selected in [Event output EV1 allocation].		
[TS1 ON time		
0000	Sets Time signal output TS1 ON time.		
	Corresponds to [TS1 ON time] in Initial setting mode.		
	• Setting range: 00:00 to 99:59 (*1)		
	Available only when $\Box \mathcal{D}$ /5 (Time signal output) is selected in [Event output EV1 allocation].		

^(*1) Time unit follows the selection in [Step time unit].

Characters, Factory Default	Setting Item, Function, Setting Range			
E805	Event output EV2 allocation			
		Event output EV2 from the Event Outp	out Allocation Table below	
	Corresponds to [Event output EV2 allocation] in Initial setting mode.			
	• When changing Event output EV2, refer to Section "8.10 Items to be Initialized			
	by Changing Settings" (p.98). • Selection item:			
	Event Output Allocation Table			
		1		
		No event		
		Alarm output, High limit alarm		
		Alarm output, Low limit alarm		
		Alarm output, High/Low limits alarm		
	004	Alarm output, High/Low limits		
		independent alarm		
	005	Alarm output, High/Low limit range		
		alarm		
	005	Alarm output, High/Low limit range		
	,	independent alarm		
		Alarm output, Process high alarm		
	008	Alarm output, Process low alarm		
	009	Alarm output, High limit with		
		standby alarm		
		Alarm output, Low limit with		
		standby alarm		
		Alarm output, High/Low limits		
	0.00	with standby alarm		
	_0 <i>12</i>	Alarm output, High/Low limits		
		with standby independent alarm		
	0 13	Heater burnout alarm output		
	0 14	Loop break alarm output		
	II 15	Time signal output	Turns OFF or ON during Program	
			control, by setting OFF time and	
			ON time within the step set in	
	0443479700		[Step number].	
	_0 <i>1</i> 5	Output during AT	Turns ON during AT.	
	0 17	Pattern end output	Turns ON when Program control	
			ends, and remains ON until turned	
			OFF by pressing the ® key.	
	CC 18	Output by communication	Turns OFF or ON by communication	
		command	command 00E4H during Serial	
			communication.	
			B0 EV1 output 0: OFF	
			1: ON	
			B1 EV2 output 0: OFF	
			1: ON	
	O 19	Heating/Cooling control	Works as Control output OUT2	
		relay contact output (*1)	(Heating/Cooling control).	
	Available o	nly when Event output EV2 (EV2, EV2+D□ option	<u> </u>	
(*1) Not available if He	1) Not available if Heating/Cooling control (EV2+D option) is ordered.			

^(*1) Not available if Heating/Cooling control (EV2+D \square option) is ordered.

Characters, Factory Default	Setting Item, Function, Setting Range			
REER	EV2 alarm value 0 Enabled/Disabled			
00		zero), alarm action can be Enabled or Disabled.		
	Corresponds to [EV2 alarm value 0 Enabled/Disabled] in Initial setting mode.			
	Selection item:			
	no Disabled			
	보론与 Enabled			
	Available only when Event output EV2	(EV2, EV2+D□ options) is ordered.		
	Available when any alarm from \$\Bar{\text{\text{\$\pi}} \Bar{\text{\$\pi}}\$ (Alarm output, High limit alarm) to \$\Bar{\text{\$\pi}} \Bar{\text{\$\pi}}\$ (Alarm output, High limit range independent alarm), and from \$\Bar{\text{\$\pi}} \Bar{\text{\$\pi}}\$ (Alarm output, High limit with standby alarm) to \$\Bar{\text{\$\pi}} \Bar{\text{\$\pi}}\$ (Alarm output, High/Low limits with standby independent alarm) is selected in [Event output EV2 allocation].			
<i>R2</i>	EV2 alarm value			
	 Sets EV2 alarm value. 			
	Corresponds to [EV2 alarm v			
	Gel-Shanna anna	/2 low limit alarm value in the following cases:		
		/Low limits independent alarm), $\square G \square S$ (Alarm output,		
		ndent alarm), or 🗆 🗗 (Alarm output, High/Low		
	•	lent alarm) is selected in [Event output EV2 allocation].		
	Setting range:	2000		
	High limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)		
	Low limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)		
	High/Low limits alarm	0 to Input span °C (°F) (*1) (*2)		
	High/Low limits independent	0 to Input span °C (°F) (*1) (*2)		
	alarm			
	High/Low limit range alarm	0 to Input span °C (°F) (*1) (*2)		
	High/Low limit range	0 to Input span °C (°F) (*1) (*2)		
	independent alarm			
	Process high alarm	Input range low limit to Input range high limit (*1) (*3)		
	Process low alarm	Input range low limit to Input range high limit (*1) (*3)		
	High limit with standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)		
	Low limit with standby alarm	-(Input span) to Input span $^{\circ}\mathbb{C}$ ($^{\circ}\mathbb{F}$) (*1) (*2)		
	High/Low limits with standby	0 to Input span °C (°F) (*1) (*2)		
	alarm			
	High/Low limits with standby	0 to Input span °C (°F) (*1) (*2)		
	independent alarm			
	Available only when Event output EV2 (EV2, EV2+D options) is ordered.			
	Available when any alarm from $\square \square \square$			
A2H	EV2 high limit alarm value	,		
	 Sets EV2 high limit alarm va 	lue.		
	This value is available only for the following:			
	$\Box \Box \Box \Box \Box \Box$ (Alarm output, High/Low limits independent alarm), $\Box \Box \Box \Box \Box$ (Alarm			
	output, High/Low limit range independent alarm), or \$\subseteq \beta \text{!} \ightarrow \text{(Alarm output,}\$			
	High/Low limits with standby independent alarm) is selected in [Event output			
	EV2 allocation].			
	-	nit alarm value] in Initial setting mode.		
	Setting range: Same as those of EV2 alarm value			
	Available only when Event output EV2 (EV2, EV2+D options) is ordered.			
<u> </u>	<u> </u>			

- $(^{\star}1)$ The placement of the decimal point follows the selection.
- (*2) For DC voltage, current inputs, the input span is the same as the scaling span.
- (*3) For DC voltage, current inputs, input range low (or high) limit value is the same as scaling low (or high) limit value.

Characters, Factory Default		Setting Item, Function, Setting Range		
R2HY	EV2 alarm hysteresis			
	Sets EV2 alarm hysteresis.			
	Correspond	s to [EV2 alarm hysteresis] in Initial setting mode.		
		ge: 0.1 to 1000.0°C (°F),		
	DC voltage,	current inputs: 1 to 10000 (*1)		
	Available only w	when Event output EV2 (EV2, EV2+D□ options) is ordered.		
	Available when any alarm from $\square \square \square$ (Alarm output, High limit alarm) to $\square \square$ (Alarm output, High/Low			
	limits with stand	by independent alarm) is selected in [Event output EV2 allocation].		
R2dY	EV2 alarm d	elay time		
	Sets EV2 a	larm action delay time.		
	Correspond	s to [EV2 alarm delay time] in Initial setting mode.		
		g time has elapsed after the input enters the alarm output range, the		
	alarm is act			
		ge: 0 to 10000 seconds		
	Ī	when Event output EV2 (EV2, EV2+D options) is ordered.		
		any alarm from $\square \square \square$ $!$ (Alarm output, High limit alarm) to $\square \square$ $!$? (Alarm output, High/Low		
		lby independent alarm) is selected in [Event output EV2 allocation].		
R2L	EV2 alarm Energized/De-energized			
noñL	Selects Energized/De-energized status for EV2 alarm.			
	•	Corresponds to [EV2 alarm Energized/De-energized] in Initial setting mode.		
	Refer to 'EV1/EV2 Energized/De-energized' (p.50).			
	• Selection item:			
	Energized			
	r E 8 5	De-energized		
	Available only when Event output EV2 (EV2, EV2+D options) is ordered.			
	Available when any alarm from \$\sum_{\text{GG}} !\$ (Alarm output, High limit alarm) to \$\sum_{\text{G}} ! \mathcal{E}\$ (Alarm output, High/Low			
F1 71	limits with standby independent alarm) is selected in [Event output EV2 allocation].			
[525	TS2 output step number			
		ep number for which Time signal output TS2 is turned OFF or ON		
	during Prog			
	-	s to [TS2 output step number] in Initial setting mode.		
	Setting range			
152F	-	then ☐0 15 (Time signal output) is selected in [Event output EV2 allocation].		
0000	TS2 OFF time			
		signal output TS2 OFF time. s to [TS2 OFF time] in Initial setting mode.		
		ge: 00:00 to 99:59 (*2)		
		ge. 00.00 to 99.59 (°2) when $\square G$ /5 (Time signal output) is selected in [Event output EV2 allocation].		
[50]	TS2 ON time			
0000		signal output TS2 ON time.		
		s to [TS2 ON time] in Initial setting mode.		
	•	ge: 00:00 to 99:59 (*2)		
		ge. 00.00 to 99.59 ($^{\circ}$ 2) /hen $\square G$ /5 (Time signal output) is selected in [Event output EV2 allocation].		
	Available only w	men		

^(*1) The placement of the decimal point follows the selection.

^(*2) Time unit follows the selection in [Step time unit].

Characters, Factory Default		Setting Item, Function, Setting Range		
hot[]	Sensor correction coefficient			
(000		or correction coefficient.		
		of input value from a sensor.		
	l -	ensor correction= Current PV x (Sensor correction coefficient) +		
	. v ano. oc	(Sensor correction value)		
	Refer to So	ection '9.1 Input Value Correction' (p. 99).		
		nge: -10.000 to 10.000		
' -	Sensor correction			
	This correct	cts the input value from the sensor.		
		ensor cannot be set at the exact location where control is desired, the		
	sensor-mea	asured temperature may deviate from the temperature in the controlled		
	location. W	hen using multiple controllers, sometimes the measured temperatures do		
	not concur	due to differences in sensor accuracy or dispersion of load capacities. In		
		e, the control can be set at the desired temperature by adjusting the input		
		nsors. However, it is effective within the input rated range regardless of		
		the sensor correction value.		
	PV after sensor correction= Current PV x (Sensor correction coefficient) +			
	(Sensor correction value)			
	Refer to Section '9.1 Input Value Correction' (p.99).			
	l —	nge: -1000.0 to 1000.0℃ (℉)		
		e, current inputs: -10000 to 10000 (*1)		
FILF		ne constant		
		ter time constant.		
		e is set too high, it affects control results due to the delay of response.		
· · · · · · · · · · · · · · · · · · ·	• Setting range: 0.0 to 10.0 seconds			
دِمَ'ہے <u>ا</u>	Communication protocol			
noñL	Selects communication protocol.			
	• Selection			
	noñL	Shinko protocol		
	ñod8	MODBUS ASCII		
	nodr • •	MODBUS RTU		
	JoōL	Shinko protocol (JC command allocated)		
	JādA	MODBUS ASCII (JC command allocated)		
	ปกัปก	MODBUS RTU (JC command allocated)		
	Available only when Serial communication (C5W, C5 options) is ordered.			
<u>cāno</u>	Instrument			
		estrument number.		
		ment numbers should be set one by one when multiple instruments are		
		in Serial communication, otherwise communication is impossible.		
	Setting rar			
	Available only when Serial communication (C5W, C5 options) is ordered. he decimal point follows the selection.			

^(*1) The placement of the decimal point follows the selection.

Characters, Factory Default	Setting Item, Function, Setting Range		
cāhP	Communication speed		
98	Selects a communication speed equal to that of the host computer.		
	• Selection item:		
	98	9600 bps	
	<u> 192</u>	19200 bps	
	384	38400 bps	
	Available only	when Serial communication (C5W, C5 options) is ordered.	
cāFſ	Data bit/Pa		
7685		ata bit and parity.	
	• Selection	• •	
	8non	8 bits/No parity	
	Topo	7 bits/No parity	
	8580	8 bits/Even	
	7885	7 bits/Even	
	Bodd	8 bits/Odd	
	Todd	7 bits/Odd	
	Available only	when Serial communication (C5W, C5 options) is ordered.	
555F	Stop bit	· · · · · · · · · · · · · · · · · · ·	
	Selects the stop bit.		
	• Selection	item:	
		1 bit	
		2 bits	
	Available only	when Serial communication (C5W, C5 options) is ordered.	
cādy	Response	delay time	
□□ <i>ID</i>	 Response 	from the controller can be delayed after receiving command from the	
	host comp	uter.	
	If Respons	se delay time is changed via software communication, the changed delay	
	time will be	e reflected from that response data.	
	 Setting rai 	nge: 0 to 1000 ms	
* * *		when Serial communication (C5W, C5 options) is ordered.	
58_5	SVTC bias		
		sired value (SV) adds SVTC bias value to the value received by the	
	SVTC com		
	•	nge: ±20% of input span	
	_	e, current inputs: ±20% of scaling span (*1)	
		en Shinko protocol is selected in [Communication protocol].	
rear		en Serial communication (C5W, C5 options) is ordered.	
Lock	• Selects R	emote (Remote operation) or Local (keypad operation) setting of the SV.	
	 Selects IX Selection 	, , , , , , , , , , , , , , , , , , , ,	
	Lack	Local	
	-EAC	Remote	
		when External setting input (EIT option) is ordered.	
(*1) The placement of t	<u> </u>		

^(*1) The placement of the decimal point follows the selection.

Characters, Factory Default		Setting Item, Function, Setting Range		
- TLH	External setting input high limit			
1370	Sets External setting input high limit value.			
	(This value corresponds to 20 mA in direct current input.)			
	Setting range: External setting input low limit to Input range high limit			
		al setting input (EIT option) is ordered.		
- TLL	External setting inpu	ut low limit		
-200	Sets External setting	j input low limit value.		
	(This value correspo	nds to 4 mA in direct current input.)		
	Setting range: Input	range low limit to External setting input high limit		
	Available only when Extern	al setting input (EIT option) is ordered.		
-r_b	Remote bias			
	 During remote action 	n, SV includes the remote bias value.		
	Setting range: ±20%	% of input span		
	DC voltage, current i	nputs: ±20% of scaling span (*1)		
	Available only when Externation	al setting input (EIT option) is ordered.		
[roh	Transmission output	••		
PB	Selects the transmis			
		smission output type, refer to Section "8.10 Items to be		
	Initialized by Changi	ng Settings" (p.98).		
	• Selection item:			
	PH PV trans			
	う台 SV transi			
	MV transmission DV transmission			
r-LH	·	nission output (EIT option) is ordered.		
1370	Transmission output	_		
12 10	 Sets the Transmission output high limit value. (This value correponds to 20 mA in direct current output.) 			
	• Setting range:			
	PV, SV transmission			
	MV transmission	Transmission output low limit to 105.0%		
	DV transmission	Transmission output low limit to Scaling span (*1)		
	Available only when Transmission output (EIT option) is ordered.			
r-LL	Transmission output	t low limit		
-200	Sets the Transmission	on output low limit value.		
	(This value correpor	nds to 4 mA in direct current output.)		
	Setting range:			
	PV, SV transmission	Input range low limit to Transmission output high limit value		
	MV transmission	-5.0% to Transmission output high limit value		
	DV transmission	-Scaling span to Transmission output high limit value (*1)		
· , ;;;;;		nission output (EIT option) is ordered.		
<u>5</u> 5	Step time unit			
āl n□	<u> </u>	e unit for the Program control.		
	• Selection item:			
		Minutes		
		es:Seconds		
	Available only when Progra	m control is selected in [OUT/OFF key function].		

 $^{(^{\}star}1)$ The placement of the decimal point follows the selection.

Characters,		Setting Item, Function, Setting Range	
Factory Default	Power restore action		
'\ <u>'</u>	Selects the program status if a power failure occurs mid-program and it is restored.		
	Selection item:		
	s on f	Stops after power is restored.	
	Hold	Continues (resumes) after power is restored.	
		Suspends (on hold) after power is restored.	
1 111		when Program control is selected in [OUT/OFF key function].	
\ <u>\</u> _\\ <u>\</u> _\\\\\\\\\\\\\\\\\\\\\\\\\\\\	_	art temperature	
		ep temperature when Program control starts.	
	_	ge: Scaling low limit value to Scaling high limit value (*1)	
1 1		when Program control is selected in [OUT/OFF key function].	
<u> </u>	_	ntrol start type	
PB		Program control start type.	
	Selection it		
	PB	PV start	
	PBr	PVR start	
	5 <u>8</u>	SV start	
Management provi	Available only when Program control is selected in [OUT/OFF key function].		
-EPT	Number of repetitions		
	Sets the number of repetitions for Program control.		
	Setting ran	ge: 0 to 10000 times	
7888 50 - 50	Available only v	when Program control is selected in [OUT/OFF key function].	
-855 -	SV Rise/Fal		
\ <u>\</u> \ <u>\</u> \\\\\\\\\\\\\\\\\\\\\\\\\\\\\\		rol output is turned from OFF to ON, or switched from Manual to	
	Automatic control, SV start or PV start can be selected for SV rise rate or SV fall		
	rate action.		
	When power	er is turned ON, PV start is adopted for SV Rise/Fall rate action,	
	regardless of the selected type.		
	Selection item:		
	585F	SV start	
	P855	PV start	
-85U	SV rise rate		
		e rate (rising value for 1 minute).	
		SV is adjusted, it approaches the new SV by the preset rate-of-change	
	(°C/min, °F/min).		
	When the power is turned on, the control starts from the PV, and approaches the		
	-	ate-of-change (°C/min, °F/min).	
	_	ge: 0 to 10000°C/min (°F/min)	
	·	ole, RTD inputs with a decimal point: 0.0 to 1000.0°C/min (°F/min)	
		, current inputs: 0 to 10000/min	
(*1) The placement of t		or 0.0 disables this function.	

 $^{(^{\}star}1)$ The placement of the decimal point follows the selection.

Characters,		Setting Item, Function, Setting Range	
Factory Default			
r8fd	SV fall rate		
	Sets SV fall rate (falling value for 1 minute).		
	When the SV is adjusted, it approaches the new SV by the preset rate-of-change		
	,	nin). When the power is turned on, the control starts from the PV and	
	' '	the SV by the rate-of-change (°C/min, °F/min).	
		ge: 0 to 10000°C/min (℉/min)	
		ble, RTD inputs with a decimal point: 0.0 to 1000.0℃/min (℉/min)	
	_	current inputs: 0 to 10000/min	
		or 0.0 disables this function.	
P58 		hen control output OFF	
off.		indication when control output is OFF.	
	Selection it		
	off.	OFF indication	
	Roff	No indication	
	PB	PV indication	
	PBAL	PV indication + Any Alarm active	
8F_6	AT bias		
	Sets bias value	alue for the AT.	
	AT point is	automatically determined by the deviation between PV and SV.	
		ction '8.5 Setting PID Constants (by performing AT)' (p.84).	
	• Setting range: 0 to 50℃ (0 to 100℉) or		
	0.0 to 50.0°C (0.0 to 100.0°F)		
	Available only for PID control.		
		r DC voltage, current inputs	
Ar_E	AT gain	rtional band ratio calculated by performing AT or 'AT on startup'.	
ΕΕΕΕ Ι.ΕΙ		ge: 0.1 to 10.0	
EaUF		us when input errors occur	
off	Selects the output status when input errors occur.		
	Selection item:		
	□ FF Output OFF		
	00	Output ON	
		ct current and voltage inputs, and direct current output type.	
ā8aU	OUT/OFF ke		
off.		T/OFF key function.	
	• Selection item:		
	off[]	Control output OFF function	
	585U	Auto/Manual control	
	ProD	Program control	
58ch	Auto/Manua	I control after power ON	
RUFa		ower to the controller is turned ON, selects whether the unit starts using	
	=	control or Manual control.	
	Selection it		
	RUF a	Automatic control	
	ลิสิกป	Manual control	
	Available only v	when Auto/Manual control is selected in [OUT/OFF key function].	
	aabio only v		

Characters, Factory Default	Setting Item, Function, Setting Range	
ri aE	Indication time	
0000	Sets time from no operation status until Displays are switched off.	
	Displays relight by pressing any key while in Display sleep mode.	
	When input error (Overscale, Underscale) or burnout has occurred, Displays are	
	lit, and error codes are displayed.	
	If errors are cancelled, Displays will be unlit after indication time has passed again.	
	• Setting range: 00:00 to 60:00 (Minutes:Seconds)	
	When set to 00:00, Displays remain ON.	
Phr I	OUT1 MV preset value	
	If 'Preset output 1 ON/OFF' or 'Preset output 2 ON/OFF' is selected in [Event]	
	input allocation], OUT1 MV can be set.	
	Preset output 1 ON/OFF:	
	If sensor is burnt out during Event Input ON, control is performed with the preset	
	MV.	
	Preset output 2 ON/OFF:	
	When Event input is ON, control is performed with the preset MV.	
	Setting range: OUT1 low limit to OUT1 high limit	
	For Direct current output type, and when OUT1 is in ON/OFF control: OUT1 low	
ļ	limit or OUT1 high limit	
	For Relay contact output or Non-contact voltage output type, and when OUT1 is in	
	ON/OFF control: 0.0% or 100.0%	
ļ	For BCS2, available only when Event input (EIW, EIT, EI options) is ordered.	
ļ	For BCR2/BCD2, available when Serial communication (C5W option) or Event input (EIW, EIT, EI options) is	
P572	ordered.	
	OUT2 MV preset value • If 'Preset output 1 ON/OFF' or 'Preset output 2 ON/OFF' is selected in [Event	
1	input allocation], OUT2 MV can be set.	
ļ	Preset output 1 ON/OFF:	
	If sensor is burnt out during Event Input ON, control is performed with the preset	
ļ	MV.	
ļ	Preset output 2 ON/OFF:	
	When Event input is ON, control is performed with the preset MV.	
	Setting range: OUT2 low limit to OUT2 high limit	
	For DA, EV2+DA options, and when OUT2 is in ON/OFF control: OUT2 low limit or	
	OUT2 high limit	
	For DR, DS, EV2+DR, EV2+DS options, and when OUT2 is in ON/OFF control:	
ļ	0.0% or 100.0%	
	Available for the following:	
	• For BCS2, Heating/Cooling control [DS, DA, EV2(*1), EV2+D□ options] or Event input (EIW, EIT, EI	
	options) is ordered.	
	 For BCR2/BCD2, Heating/Cooling control [DS, DA, EV2(*1), EV2+D□ options], Serial communication (C5W option) or Event input (EIW, EIT, EI options) is ordered. 	
FUnc	Controller/Converter function	
EnTr	Selects either controller or converter function.	
	Selection item:	
	בחוֹר Controller	
1		
	□ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □	

^(*1) When $\Box \mathcal{I} \mathcal{I} \mathcal{I}$ (Heating/Cooling control relay contact output) is selected in [Event output EV2 allocation].

Characters, Factory Default		Setting Item, Function, Setting Range	
Ed! F	Error indica	tion Enabled/Disabled	
חם	When input errors occur, the error code can be displayed (Enabled) or not		
	displayed (Disabled).		
	Selection item:		
	70	ng Disabled	
	BE h□	当日本 Enabled	

7.4 Engineering Mode 2

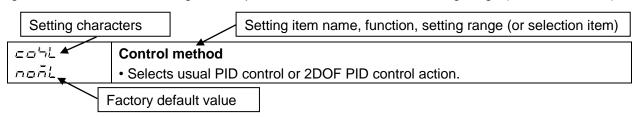
To enter Engineering mode 2, press and hold the \wedge , \vee and \otimes keys (in that order) together for approximately 5 seconds in RUN mode.

Use the \wedge or \vee key for settings (or selections).

To register the set data, use the Q key.

Explanation of setting items:

- Upper left: PV Display: Indicates setting characters.
- Lower left: SV Display: Indicates factory default value.
- Right side: Indicates the setting item, explanation of its function and setting range (or selection item).



Characters, Factory Default		Setting Item, Function, Setting Range
cohl	Control me	ethod
noñL	Selects us	sual PID control or 2DOF PID control action.
	DOF: Deg	ree(s) of freedom
	noñL	PID control
	25oF	2DOF PID control
Ł PRH	Proportion	al gain 2DOF coefficient (α)
	 Sets Prop 	ortional gain 2DOF coefficient.
	Increasing	Proportional gain 2DOF coefficient (α) results in a quick response,
	and decreasing it causes a slow response.	
	Setting range: 0.00 to 1.00	
	Available only	when 2DOF PID control is selected in [Control method].
ΓΙ <u></u>	Integral 2D	OF coefficient (β)
□ <i>t</i> 35	Sets Integral	ral 2DOF coefficient.
	By increas	ing Integral 2DOF coefficient (β), overshoot or undershoot can be
	controlled	more effectively.
	However, r	esponse will be slower than the usual PID control for suppressing the
	overshoot	or undershoot.
	 Setting ra 	nge: 0.00 to 10.00
	Available only	when 2DOF PID control is selected in [Control method].

2DOF PID Control

Two degree-of-freedom PID control has follow-up characteristics when SV is changed, and can suppress disturbance.

Two degree-of-freedom means that the above 2 characteristics can be adjusted independently. Follow-up characteristics when SV is changed, can be adjusted by setting the Proportional gain 2DOF coefficient (α).

To suppress disturbance, Integral 2DOF coefficient (β) is used for adjustment.

The factory default values have been set at the optimum coefficients (α, β) for standard control.

8. Operation and Settings of Standard Functions

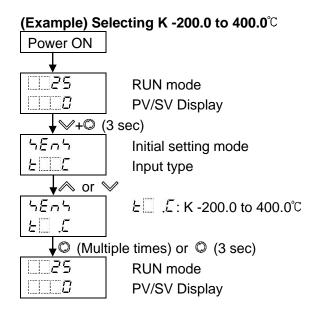
8.1 Selecting an input type

Select an input type in [Input type] in Initial setting mode.

Selection item:

EILE	K -200 to 1370°C	ELLF	K -328 to 2498°F
E□ .E	K -200.0 to 400.0°C	E□ F	K -328.0 to 752.0°F
JII	J -200 to 1000°C	JULF	J -328 to 1832°F
r I E	R 0 to 1760°C	rF	R 32 to 3200°F
4 E	S 0 to 1760°C	5□F	S 32 to 3200°F
ЫШЕ	B 0 to 1820°C	ЫШЕ	B 32 to 3308°F
ELLE	E -200 to 800°C	ELLF	E -328 to 1472°F
	T -200.0 to 400.0℃	Γ□ .F	T -328.0 to 752.0°F
πIII	N -200 to 1300°C	nIF	N -328 to 2372°F
PLZE	PL-Ⅱ 0 to 1390°C	PLZF	PL-II 32 to 2534°F
ΕΙΙΕ	C(W/Re5-26) 0 to 2315°C	c F	C(W/Re5-26) 32 to 4199°F
PF .E	Pt100 -200.0 to 850.0℃	PT F	Pt100 -328.0 to 1562.0°F
JPT.E	JPt100 -200.0 to 500.0℃	JPT.F	JPt100 -328.0 to 932.0°F
PFE	Pt100 -200 to 850°C	PFEF	Pt100 -328 to 1562°F
JPFE	JPt100 -200 to 500°C	JPFF	JPt100 -328 to 932°F
420R	4 to 20 mA DC -2000 to 10000		
020R	0 to 20 mA DC -2000 to 10000		
DO IR	0 to 1 V DC -2000 to 10000		
<u> </u>	0 to 5 V DC -2000 to 10000		
1 58	1 to 5 V DC -2000 to 10000		
0 108	0 to 10 V DC -2000 to 10000		

Factory default value is K -200 to 1370°C.



8.2 Selecting PID Control or ON/OFF Control

Selects PID control or ON/OFF control action.

Select PID control or ON/OFF control action in [OUT1 proportional band] in Sub setting mode. If 'OUT1 proportional band' is set to 0 (zero), the unit performs ON/OFF control action. Factory default value is PID control.

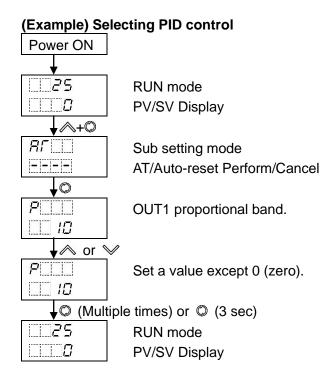
PID control

Proportional (P) action suppresses overshoot and hunting, Integral (I) action corrects offset, and Derivative (D) action adjusts for rapid temperature change due to disturbance in shorter time. Optimum values of P, I, D, ARW for PID control can be automatically set by performing AT.

ON/OFF control

When PV is lower than the SV, the control output is turned ON, and if PV exceeds the SV, the control output is turned OFF.

Overshoot, undershoot and hunting are generated in ON/OFF control action.



- P control action: When [Integral time] and [Derivative time] are set to 0 (zero).
- PD control action: When [Integral time] is set to 0 (zero).
- PI control action: When [Derivative time] is set to 0 (zero).
- Usual PID control or 2DOF PID control can be selected in [Control method] in Section '7.4 Engineering Mode 2' (p.78).

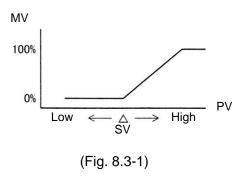
8.3 Selecting Direct/Reverse Action

Selects Direct or Reverse control action.

Select Direct or Reverse control action in [Direct/Reverse action] in Sub setting mode. Factory default value is Reverse action.

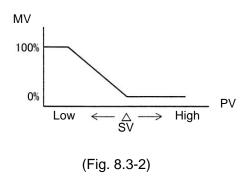
Direct action

In Direct action, MV is increased when PV is higher than SV (positive deviation). Refrigerators, etc. perform Direct action.

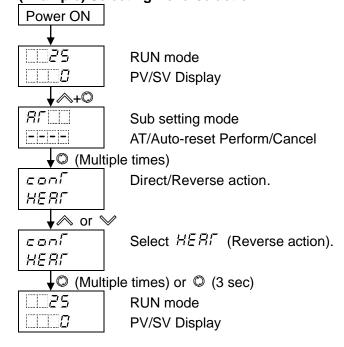


Reverse action

In Reverse action, MV is increased when SV is higher than PV (negative deviation). Electric furnaces, etc. perform Reverse action.



(Example) Selecting Reverse action



8.4 Performing Fixed Value Control

Fixed value control is a typical temperature control action, which reduces deviation from a single SV by comparing with PV.

To perform Fixed value control, set the SV.

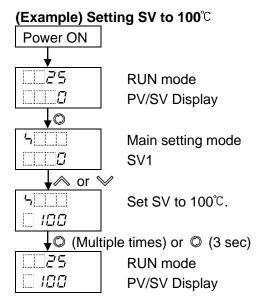
There are 2 ways to set the SV.

- Set the SV in [SV1] in Initial setting mode.
- Set the SV in [SV1] in Main setting mode.

Setting item [SV1] in Initial setting mode corresponds to [SV1] in Main setting mode.

Therefore, if one SV1 is changed, the other SV1 will also be changed.

Factory default value is 0 (zero).



Settings are complete.

/N N

'!∖ Notice

- Perform the AT during the trial run.
- During the AT, none of the setting items can be set.
- If power failure occurs during the AT, the AT stops.
- If AT is cancelled during the process, P, I, D and ARW values revert to the values before AT was performed.
- AT will be forced to stop if it has not been completed within 4 hours.
- Sometimes the AT process will not fluctuate if AT is performed at or near room temperature. Therefore, AT might not finish normally.

To set PID constants, perform AT.

There are 2 types of AT: Usual AT and 'AT on Startup'

8.5.1 Usual AT

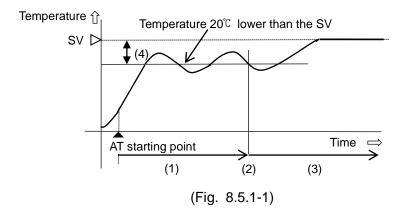
In order to set each value of P, I, D and ARW automatically, the AT process should be made to fluctuate to obtain an optimal value.

For DC voltage, current inputs, the AT process will fluctuate around the SV for conditions of [A], [B] and [C] below.

One of 3 types of fluctuation below is automatically selected depending on the deviation between SV and PV.

[A] If there is a large difference between the SV and PV as the temperature is rising

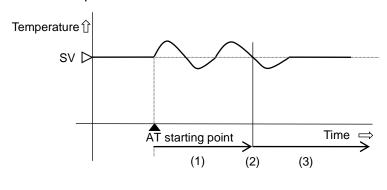
When AT bias is set to 20°C, the AT process will fluctuate at the temperature 20°C lower than the SV.



- (1) Calculates PID constants.
- (2) PID constants calculated
- (3) Controlled by the PID constants set by AT
- (4) AT bias value (Factory default: 20°C)

[B] When the control is stable

The AT process will fluctuate around the SV.

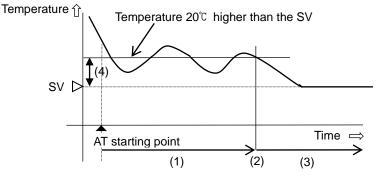


(Fig. 8.5.1-2)

- (1) Calculates PID constants.
- (2) PID constants calculated
- (3) Controlled by the PID constants set by AT

[C] If there is a large difference between the SV and PV as the temperature is falling

When AT bias is set to 20° C, the AT process will fluctuate at the temperature 20° C higher than the SV.



(Fig. 8.5.1-3)

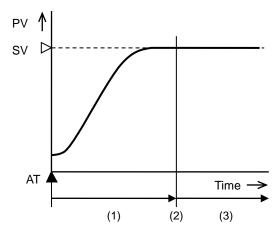
- (1) Calculates PID constants.
- (2) PID constants calculated
- (3) Controlled by the PID constants set by AT
- (4) AT bias value (Factory default: 20°C)

8.5.2 AT on Startup

When usual AT cannot be performed normally due to temperature interference, P, I, D and ARW values can be calculated only when temperature is rising.

As the selected [AT on startup Perform] is internally memorized, 'AT on startup' is performed whenever the power is turned ON.

To stop 'AT on startup', select 'AT/AT on startup/Auto-reset Cancel' in [AT/Auto-reset Perform/Cancel].



- (1) Calculates AT (from startup, until PV is stabilized at SV).
- (2) PID constants calculated
- (3) Controls with PID constants set by 'AT on startup'.

(Fig. 8.5.2-1)

[Conditions of Performing 'AT on startup']

• When starting 'AT on startup', if deviation between PV and SV exceeds the proportional band by 2 times or more, 'AT on startup' will perform.

When power is turned ON (*), or when the unit reverts to RUN mode after canceling control output OFF, 'AT on startup' performs.

Even after 'AT on startup' is successfully finished, 'AT on startup' has been still selected in [AT/Auto-reset Perform/Cancel].

When power is turned ON again, or when the unit reverts to RUN mode by cancelling Control output OFF, 'AT on startup' performs again under the above performance conditions.

To stop 'AT on startup', select 'AT/AT on startup/Auto-reset Cancel' in [AT/Auto-reset Perform/Cancel].

(*) For Fixed value control, 'AT on startup' can be performed when power is turned ON. It cannot be performed for Program control.

However, if PV slope and delay time cannot be measured normally for P, I, D calculation, the error code below will be indicated on the PV Display, and automatically 'AT on startup' will stop. If an error has occurred, P, I, D and ARW values revert to the previous value at which 'AT on startup' is performed.

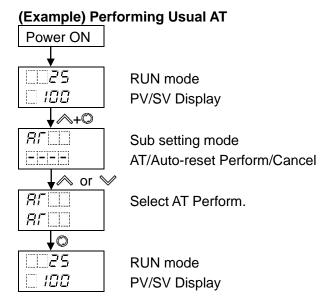
Error Code	Error Contents
E-20	Normally PV slope and delay time cannot be measured for P, I, D calculation.

To cancel the error code, press the \(\mathbb{O} \) key.

If 'AT on startup' is performed or stopped again, the error code will be cancelled.

[Conditions of Cancelling 'AT on startup']

- · When Control output OFF is enabled
- When input is burnt out
- When deviation between SV and PV is not within $2^{\circ}C$ or is not within 2% of proportional band (even though the set integral time has elapsed when the control is stable) in stable control status



Selection is complete.

The AT indicator flashes while AT is performing.

After AT is complete, the AT indicator turns off, and control is performed using PID constants calculated by the AT.

If AT does not finish after 4 hours, the error code below will be indicated on the PV Display, and AT will automatically stop.

Error Code	Error Contents
E-20	If AT or 'AT on startup' does not finish after 4 hours.

To cancel the error code, press the \bigcirc key.

The error code will be cancelled in the following cases.

- When Control output OFF function is enabled
- When Program control is stopped and the unit reverts to Standby (Program control waiting) mode.
- When 'Control output OFF function' or 'Auto/Manual control' is selected in [OUT/OFF key function].
- When 'AT/AT on startup/Auto-reset Cancel' is selected in [AT/Auto-reset Perform/Cancel].

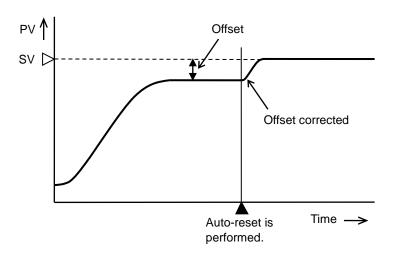


Notice

- Auto-reset finishes in approximately 4 minutes. It cannot be cancelled while performing this function.
- If input is burnt out, Auto-reset will be forced to stop.

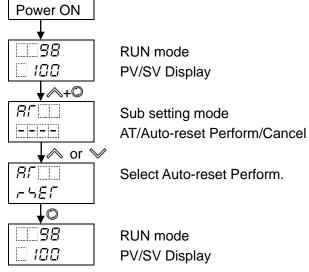
In PD control, Auto-reset is performed to correct the offset at the point at which PV indication is stabilized within the proportional band. Since the corrected value is internally memorized, it is not necessary to perform the Auto-reset again as long as the process is the same.

However, when OUT1 proportional band (P) is set to 0 or 0.0, the corrected value is cleared to 0 (zero).



(Fig. 8.6-1)





Selection is complete.

The AT indicator flashes while Auto-reset is performing.

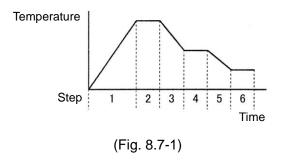
Auto-reset is completed in approximately 4 minutes.

After Auto-reset is complete, the AT indicator turns off, and control is performed using the offset corrected value.

8.7 Performing Program Control

In Program control, SV changes as time elapses, and PV is controlled in order to reach each SV. SV and time can be set for every step, and a maximum of 9 steps can be repeatedly controlled. SV can be set as (Fig. 8.7-1).

(e.g.) Program control of electric furnaces in ceramic manufacture, food machinery, etc.



Major functions of Program control are shown below.

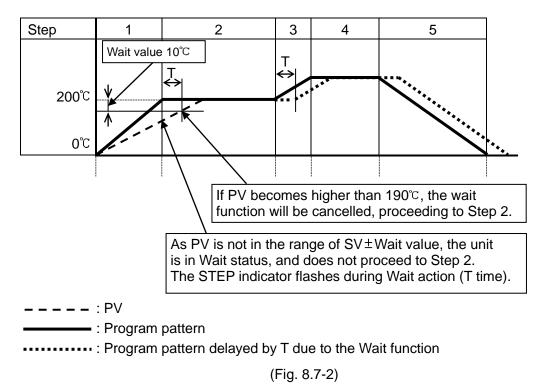
Number of patterns and steps: 1 pattern; 9 steps

Wait function

While Program control is running, the program does not proceed to the next step until the deviation between PV and SV enters SV±Wait value at the end of step. The PV Display flashes while the Wait function is working.

The Wait function is cancelled on the condition that:

- When program pattern is rising: PV is higher than SV- Wait value
- When program pattern is falling: PV is lower than SV+ Wait value



Program control Holding/Not holding

During Program control, progress of current step is suspended, and then

Fixed value control is performed using the SV from the point of suspension.

Program control Holding/Not holding can be selected in [Event input DI1/DI2 allocation].

Advance function

Interrupts current step while Program control is running, and proceeds to the beginning of the next step.

By pressing the \wedge key for approx. 1 second during Program control, Advance function initiates. Select this function in [Event input DI1/DI2 allocation].

Pattern end output

If Pattern end output is selected in [Event output EV1/EV2 allocation], pattern end output is turned ON after Program control is finished, and the SV Display flashes \$\mathcal{P}.\mathcal{E} \sigma \mathcal{D}\$.

By pressing the ® key for approx. 1 second, pattern end output is turned OFF, and the unit enters Standby mode.

Step time unit

Step time unit can be selected: Hours:Minutes, Minutes:Seconds

Factory default value is Hours:Minutes.

Power Restore Action (Program control after power is restored)

If power fails during Program control, selects a status after the power is restored.

Factory default value is 'Stops after power is restored'.

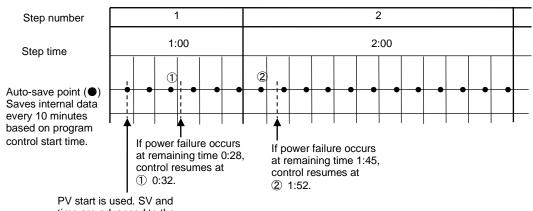
Power Restore Action	Description
Stops after power is	Stops Program control, and returns to Standby (Program control
restored.	waiting) mode.
Continues after power is	Continues (resumes) Program control.
restored. (*)	
Suspends after power is	Suspends (on hold) current program, and performs Fixed value
restored. (*)	control using the SV from the point of suspension.
	Pressing the ® key cancels suspension, and Program control
	resumes.

^(*) Progressing time error when power is restored: 10 minutes

This controller saves internal status every 10 minutes after Program control starts.

Internal status is also saved when step is changed.

When power is restored, the unit starts from the last auto-save point.



PV start is used. SV and time are advanced to the remaining time 0:52, and program control starts.

(Fig. 8.7-3)

Program start temperature

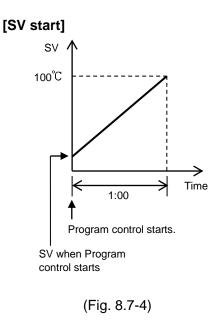
When Program control starts, it starts from the value set in [Program start temperature]. Factory default value is 0° C.

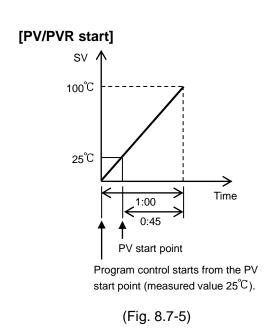
Program control start type

One type can be selected: PV start, PVR start, SV start.

Factory default value is PV start.

Program control start type	Description
PV start	When Program control starts, the SV and step time are advanced to the PV,
	then Program control starts.
	However, if [Program start temperature] at the time of Program control start is
	higher than the PV (when PV start is initiated), then Program control will start
	from the SV set in [Program start temperature].
PVR start	In pattern repeating, the SV and step time are advanced to the PV, then the
	Program control starts.
SV start	Program control starts from the SV which has been set in [Program start
	temperature].





Repeat function

When Program control is finished, control can be repeated from Step 1.

The user determines the number of repetitions.

Factory default value is 0 (zero).

Select 'Program control' in [OUT/OFF key function] in Engineering mode 1. Factory default value is Control output OFF function.

Set the following items in Engineering mode 1:

Step time unit, Power restore action, Program start temperature,

Program control start type, Number of repetitions

Program pattern can be set in Main setting mode.

Example of program pattern setting

Step	1	2	3	4	5
SV (°C)	200	200	300	300	0
Time	1:00	2:00	0:30	1:00	2:00
Wait value (°C)	10	0	10	0	0
300 ℃					
3000					
200℃					
0℃					
	< 1:00 >	← 2:00 >	0:30	< 1:00 >	← 2:00
1		n control starts			• •

(Fig. 8.7-6)

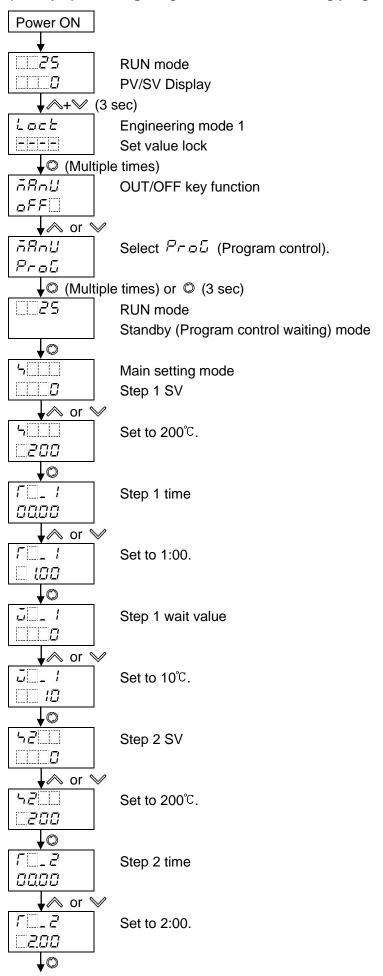
In the above program pattern, control is performed at each step as follows.

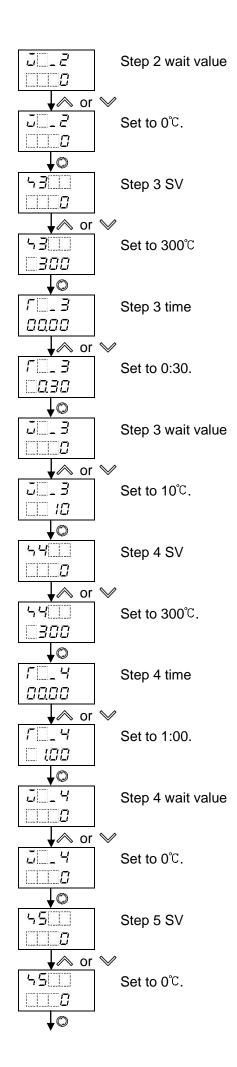
- Step 1: The SV gradually rises to 200°C for 1 hour.

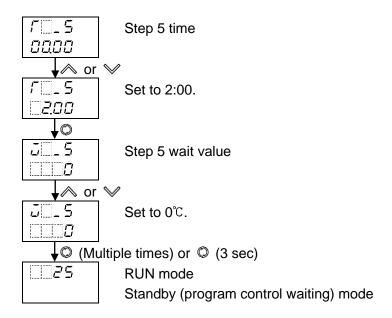
 When the step ends, Wait function works so that control cannot proceed to the next step until PV reaches 190°C when step ends.
- Step 2: Fixed value control is performed to keep SV at 200°C for 2 hours.
- Step 3: Control is performed so that the SV gradually rises to 300°C for 30 minutes.

 When the step is finished, Wait function works so that control cannot proceed to the next step until PV reaches 290°C.
- Step 4: Fixed value control is performed to keep SV at 300°C for 1 hour.
- Step 5: Control is performed so that the SV gradually falls to 0° C for 2 hours.

(Example) Selecting Program control and Setting program pattern of (Fig. 8.7-6)







Selection is complete.

Program control RUN

To perform Program control, press and hold the ® key for approx. 1 second in Standby (program control waiting) mode.

Program control starts using the start type selected in [Program control start type].

While Wait function is working, the PV Display flashes.

Program control STOP

To stop Program control, press and hold the key for approx. 1 second during Program control. Program control will stop, and the unit will revert to Standby (Program control waiting) mode.

Proceeding to the next step during Program control (Advance function)

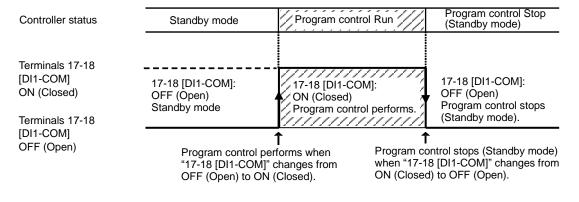
By pressing the \(\infty \) key for approx. 1 second during Program control, the performing step is interrupted, proceeding to the next step. (Advance function)

While Wait function is working, the Wait function is cancelled, and proceeds to the next step.

If \$\insigneq \mathbb{D} \mathbb{D} \mathbb{B}\$ (Program control RUN/STOP)' is selected in [Event input DI1 allocation], Program control RUN/STOP can be switched by terminals 17 and 18 [DI1-COM]:

Signal edge action from OFF to ON / ON to OFF is engaged.

However, for the action when power is turned ON, Level action [ON (Closed) or OFF (Open)] is engaged.



(Fig. 8.7-7)

8.8 Event Output EV1 Allocation

Selects Event output EV1 allocation.

There are 2 methods in selection of Event output EV1 allocation.

- Select in [Event output EV1 allocation] in Initial setting mode.
- Select in [Event output EV1 allocation] in Engineering mode 1.
 Setting item [Event output EV1 allocation] in Initial setting mode corresponds to [Event output EV1 allocation] in Engineering mode 1.

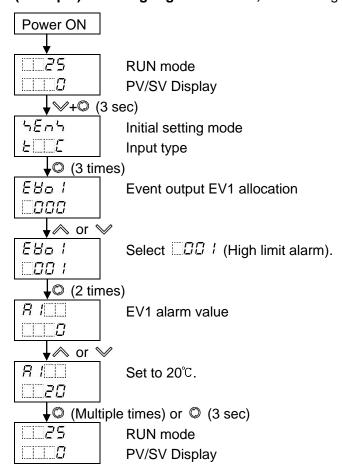
Therefore, if one [Event output EV1 allocation] is changed, the other [Event output EV1 allocation] will also be changed.

Factory default value is No event.

Selection item:

201000000000000000000000000000000000000		T
	No event	
_00 i	Alarm output, High limit alarm	
	Alarm output, Low limit alarm	
	Alarm output, High/Low limits alarm	
<u> </u>	Alarm output, High/Low limits independent alarm	
<u> </u>	Alarm output, High/Low limit range alarm	
005	Alarm output, High/Low limit range	
	independent alarm	
	Alarm output, Process high alarm	
	Alarm output, Process low alarm	
009	Alarm output, High limit with standby alarm	
0 10	Alarm output, Low limit with standby alarm	
	Alarm output, High/Low limits with standby alarm	
<u> </u>	Alarm output, High/Low limits with standby independent alarm	
I3	Heater burnout alarm output	
8 14	Loop break alarm output	
<u>□</u> 0 /5	Time signal output	Turns OFF or ON during Program control, by setting OFF time and ON time within
		the step set in [Step number].
<u> 0 15</u>	Output during AT	Turns ON during AT.
	Pattern end output	Turns ON when Program control ends, and
	·	remains ON until turned OFF by pressing
		the ® key.
_0 <i>18</i>	Output by communication command	Turns OFF or ON by communication
		command 00E4H during Serial
		communication.
		B0 EV1 output 0: OFF
		1: ON
		B1 EV2 output 0: OFF
		1: ON

(Example) Selecting High limit alarm, and setting EV1 alarm value to 20°C



Settings are complete.

8.9 Indicating MV, Remaining Time (Program Control)

In Fixed value control and Program control, MV and remaining time are indicated.

To indicate MV, press and hold the key for approx. 3 seconds on the PV/SV Display.

The unit enters Monitor mode, and indicates MV.

While MV is indicating, the decimal point flashes.

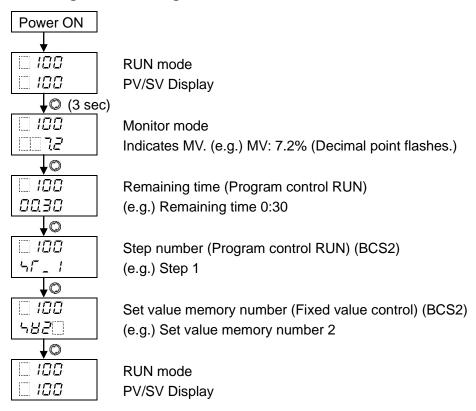
While in Standby (Program control waiting) mode of Program control, the unit cannot move to Monitor mode.

In Monitor mode, the following contents are switched every time the © key is pressed.

Model	Indicated Contents		
BCS2	Fixed value control	Indicates MV, Set value memory number (in that order).	
	Program control	Indicates MV, Remaining time, Step number (in that order).	
BCR2, BCD2	Fixed value control	Indicates only MV. (*)	
	Program control	Indicates MV, Remaining time (in that order). (*)	

^(*) For the BCR2, BCD2, Set value memory number (Fixed value control) and step number (Program control) are indicated on the MEMO/STEP Display.

Indicating MV, Remaining time



8.10 Items to be Initialized by Changing Settings

If settings are changed, the following items will be initialized.

•: Initialized

X: Not initialized

Setting item to be	Lancet Town	Event output	Event output	Transmission
Item changed to be initialized	Input Type	EV1 allocation	EV2 allocation	output
SV1 to SV9	•	Х	Х	X
Steps 1 to 9 wait value	•	Х	Х	Х
AT bias	•	Х	Х	Х
OUT1 proportional band	•	X	Х	X
Manual reset	•	X	Х	X
SV rise rate	•	Х	Х	Х
SV fall rate	•	Х	Х	Х
Scaling high limit	•	Х	Х	X
Scaling low limit	•	Х	Х	Х
Program start temperature	•	Х	Х	Х
EV1 alarm value	•	•	Х	Х
EV1 high limit alarm value	•	•	Х	Х
Loop break alarm time	•	X	Х	X
Loop break alarm band	•	Х	Х	X
SVTC bias	•	X	X	X
Remote bias	•	Х	Х	Х
EV2 alarm value	•	X	•	Х
EV2 high limit alarm value	•	Х	•	Х
Transmission output high limit	•	Х	Х	•
(Except MV transmission)				
Transmission output low limit	•	X	X	•
(Except MV transmission)				
OUT2 proportional band	•	X	X	X
EV1 alarm value 0 Enabled/Disabled	Х	•	X	X
EV1 alarm hysteresis	X	•	X	X
EV1 alarm delay time	X	•	X	X
EV1 alarm Energized/De-energized	X	•	X	X
EV2 alarm value 0 Enabled/Disabled	X	X	•	X
EV2 alarm hysteresis	X	X	•	X
EV2 alarm delay time	X	X	•	X
EV2 alarm Energized/De-energized	X	X	•	X
Sensor correction coefficient	•	X	X	X
Sensor correction	•	X	X	X
External setting input high limit	•	X	X	X
External setting input low limit	•	X	X	X

9. Attached Function

9.1 Input Value Correction

Input value can be corrected in [Sensor correction coefficient] and [Sensor correction] in Engineering mode 1.

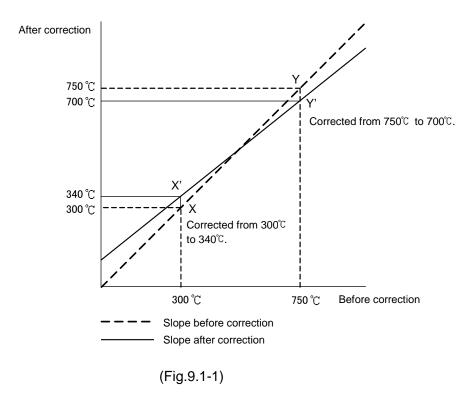
In [Sensor correction coefficient], set the slope of temperature change.

In [Sensor correction], set the difference between temperatures before correction and after correction.

PV after input correction is expressed by the following formula.

PV after input correction = Current PV x Sensor correction coefficient + (Sensor correction value)

The following shows an example of input value correction using 'Sensor correction coefficient' and 'Sensor correction value'.



(1) Select any 2 points of PV to be corrected, and determine the PV after correction.

PV before correction: 300° C \rightarrow PV after correction: 340° C

PV before correction: 750°C → PV after correction: 700°C

(2) Calculate Sensor correction coefficient from Step (1).

$$(Y'-X')/(Y-X) = (700-340)/(750-300) = 0.8$$

- (3) Enter a PV value of 300°C using an mV generator or dial resistor.
- (4) Set Step (2) value as a Sensor correction coefficient.
- (5) Read the PV.

240°C will be indicated.

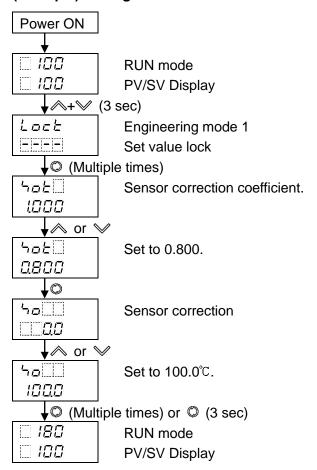
(6) Calculate the sensor correction value.

Calculate the difference between 'PV after correction' and Step (5) PV.

 $340^{\circ}\text{C} - 240^{\circ}\text{C} = 100^{\circ}\text{C}$

- (7) Set Step (6) value as a Sensor correction value.
- (8) Enter an electromotive force or resistance value equivalent to 750°C using an mV generator or dial resistor.
- (9) Read the PV, and confirm that 700°C is indicated.

(Example) Setting Sensor correction coefficient to 0.800, and Sensor correction to 100.0℃



Settings are complete.

9.2 Set Value Lock

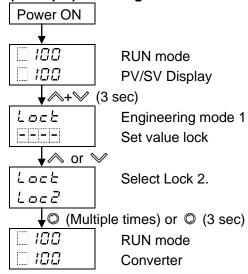
Locks the set values to prevent setting errors.

Make a selection in [Set value lock] in Engineering mode 1.

The setting item to be locked depends on the selection.

Selection Item	Change via Keypad	Change via Software Communication
Unlock	All set values can be changed.	All set values can be changed.
Lock 1	None of the set values can be changed.	
Lock 2	In Fixed value control, only SV and	
	Alarm value can be changed.	
	In Program control, Step SV, Step time	
	and Alarm value can be changed.	
Lock 3	All set values can be changed.	Setting items – except Input type,
Lock 4	None of the set values can be changed.	Controller/Converter – can be changed
Lock 5	In Fixed value control, only SV and	temporarily via software communication.
	Alarm value can be changed.	However, if power is turned ON again,
	In Program control, Step SV, Step time	the setting values revert to the values
	and Alarm value can be changed.	before Lock 3, 4 or 5 was selected.



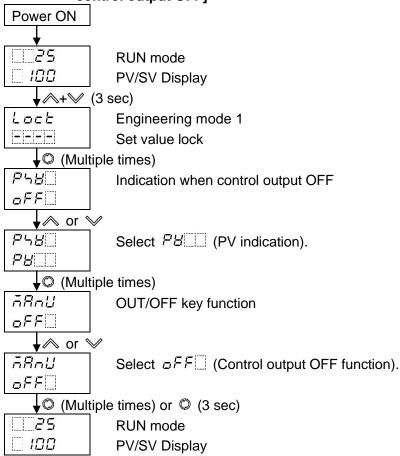


9.3 Control Output OFF Function

The control action and output of an instrument (or instruments) can be turned OFF without turning OFF their power supplies using this function.

Select 'Control output OFF function' in [OUT/OFF key function] in Engineering mode 1. Factory default value is Control output OFF function.

(Example) Selecting 'Control output OFF function', and 'PV indication' in [Indication when control output OFF]

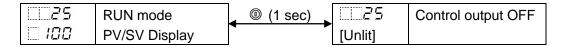


Selection is complete.

To turn the control output OFF, press the ® key for approximately 1 second on the PV/SV Display. PV is indicated on the PV Display. Indication differs depending on the selection in [Indication when control output OFF].

Once the control output OFF function is enabled, the function cannot be cancelled even if the power to the instrument is turned OFF and ON again.

To cancel the function, press the key again for approx. 1 second.



9.4 Switching Auto/Manual Control (Auto/Manual Control Function)

Control action can be switched from automatic to manual and vice versa.

When power to the controller is turned ON, Automatic or Manual control is selectable.

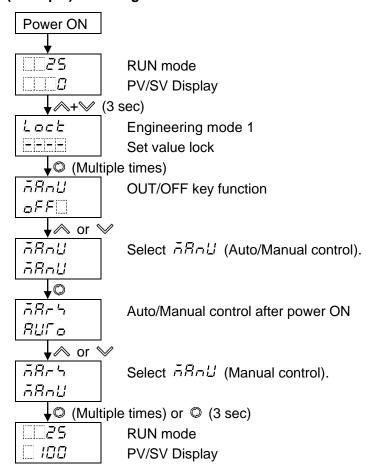
Select 'Auto/Manual control' in [OUT/OFF key function] in Engineering mode 1.

Factory default value is Control output OFF function.

Select 'Automatic control' or 'Manual control' in [Auto/Manual control after power ON] in Engineering mode 1.

Factory default value is Automatic control.

(Example) Selecting 'Auto/Manual control 'and 'Manual control' after power ON



Selection is complete.

By pressing the ® key in PV/SV Display for approx. 1 second, Auto/Manual control function can be switched.

If control action is switched from automatic to manual and vice versa, balanceless-bumpless function works to prevent a sudden change in the MV.

When automatic control is switched to manual control, MV flashes on the SV Display.

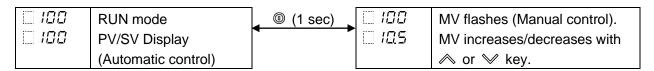
The MV on the SV Display can be increased or decreased by pressing the \infty or \infty key.

Data is saved 1 second after MV is changed, and manual control is performed.

If Manual control is selected in [Auto/Manual control after power ON: When power is turned ON, control resumes using the previously saved MV.

However, if $\Box\Box\Box\Box$ (Auto/Manual control) is selected in [Event input DI1/DI2 allocation], then Event input status has priority.

By pressing the @ key again for approx. 1 second, the unit reverts to automatic control.



⚠ Caution

Input/Output response time of this instrument is approx. 1 second.

When using as a converter, the converter input will be 1 sec slower due to the response time. (In such cases please use a converter with input time slower than the response time above.)

This instrument can be used as a simplified converter.

Converts each input value (thermocouple, RTD, DC voltage and current inputs) to '4 to 20 mA DC', and outputs it.

When OUT1 is direct current output type, the controller can be used as a converter.

Select 'Converter' in [Controller/Converter] in Engineering mode 1.

Factory default value is 'Controller'.

When this instrument is switched from controller to converter, values in the table below (Table 9.5-1) are automatically set. The SV Display turns blank.

When this instrument is switched from converter to controller, the PV Display indicates $\frac{l}{l} \pi l \frac{l}{l}$ for 1 second, and factory default values are set.

(Table 9.5-1)

Setting Item	Set Value (or Selection)
SV1 (*1)	Scaling low limit value
SV2 (*1)	Scaling low limit value
(BCS2: EIW, EIT, EI options,	
BCR2/BCD2: C5W, EIW, EIT, EI options)	
SV3 (*1)	Scaling low limit value
(BCS2: EIW, EI options,	
BCR2/BCD2: C5W, EIW, EIT, EI options)	
SV4 (*1)	Scaling low limit value
(BCS2: EIW, EI options,	
BCR2/BCD2: C5W, EIW, EIT, EI options)	
AT/Auto-reset Perform/Cancel (*2)	AT/AT on startup/Auto-reset Cancel
OUT1 proportional band (*1)	Scaling span
Integral time	0
Derivative time	0
Reset (*3)	0 (Initialized)
	(Reset value, calculated by Auto-reset function)
OUT1 high limit	100
OUT1 low limit	0
OUT1 rate-of-change	0
OUT2 proportional band (*1)	Scaling span
Direct/Reverse action	Direct action
EV1/EV2 alarm value 0 Enabled/Disabled	Disabled
EV1/EV2 alarm value	0 or Input range low limit value (Scaling low limit value)
EV1/EV2 high limit alarm value	0 or Input range low limit value (Scaling low limit value)
EV1/EV2 alarm hysteresis	1.0 (DC voltage, current input: The placement of
	the decimal point follows the selection.)
EV1/EV2 alarm delay time	0
EV1/EV2 alarm Energized/De-energized	Energized

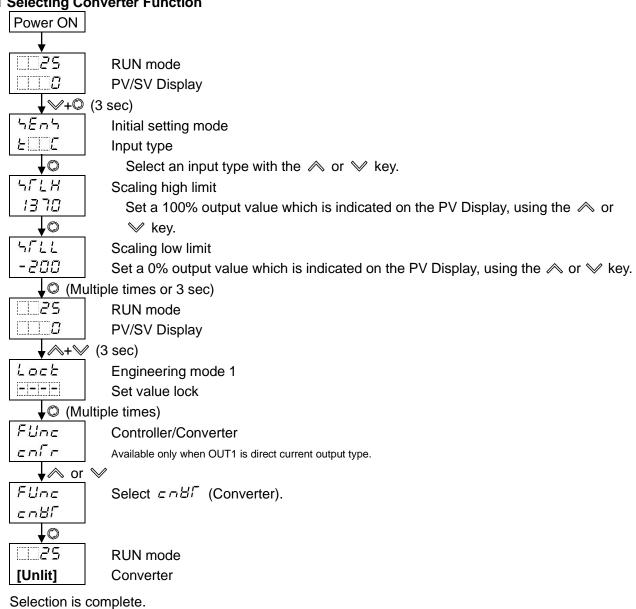
^(*1) When input range is changed while this instrument is used as a converter, SV1 to SV4, OUT1 and OUT2 proportional bands will be automatically set to values corresponding to the input range.

^(*2) If "AT on startup" is successfully completed and "AT on startup Perform" has been still selected, "AT on startup" will be stopped (AT/AT on startup/Auto-reset Cancel).

^(*3) The reset value calculated by Auto-reset function will be initialized.

Setting Item	Set Value (or Selection)
Loop break alarm time	0
Loop break alarm band	0
Event input DI1 allocation (BCS2: EIW, EIT, EI options, BCR2/BCD2: C5W, EIW, EIT, EI options)	No event
Event input DI2 allocation (BCS2: EIW, EI options, BCR2/BCD2: C5W, EIW, EIT, EI options)	No event
Event output EV1 allocation	No event
Event output EV2 allocation (EV2, EV2+D□ options)	No event
Remote/Local (EIT option)	Local
Transmission output type (EIT option)	PV transmission
Transmission output high limit (EIT option)	Input range high limit
Transmission output low limit (EIT option)	Input range low limit
SV rise rate	0
SV fall rate	0
OUT/OFF key function	Control output OFF function

9.5.1 Selecting Converter Function



9.5.2 Fine Adjustment of Converter Output (4 to 20 mA DC)

4 to 20 mA DC will be output corresponding to the input from Scaling low limit to Scaling high limit.

Fine adjustment range: 1/Scaling span

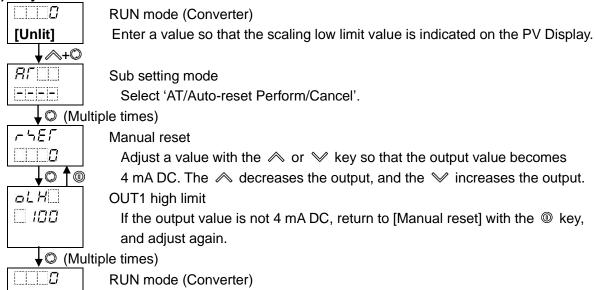
Fine Adjustment Method for Converter Output

Be sure to perform Zero side first in fine adjustment of converter output.

Perform Zero side adjustment in [Manual reset].

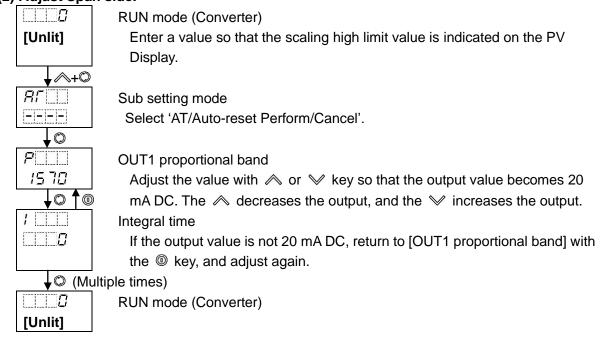
Perform Span side adjustment in [OUT1 proportional band].

(1) Adjust Zero side.



(2) Adjust Span side.

[Unlit]



(3) Repeat (1) and (2) until the correct value is output.

9.5.3 Converter Setting Example

When the input is any other value except 4 to 20 mA DC Input and output conditions:

Input: 6 to 14 mA DC (Indication: 30.0 to 130.0),

Output: 4 to 20 mA DC

Setting method

(1) Calculating Scaling high and low limit values of 4 to 20 mA DC

Indication value per mA DC: $(130.0 - 30.0) \div (14 - 6) = 100 \div 8 = 12.5$

Scaling high limit value: $130.0 + (20 - 14) \times 12.5 = 205.0$

Scaling low limit value $30.0 - (6 - 4) \times 12.5 = 5.0$

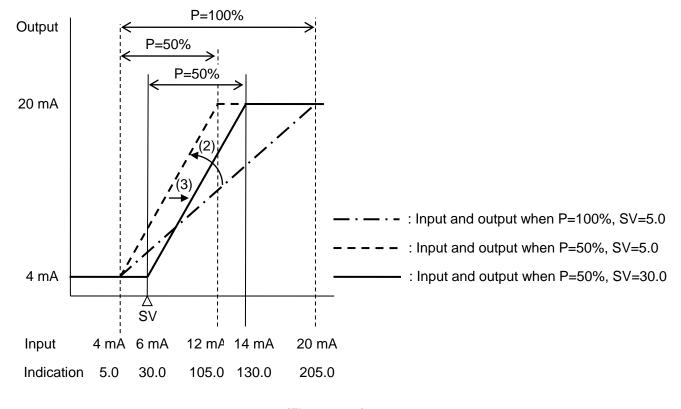
(2) Calculating OUT1 Proportional band of 6 to 14 mA DC (Slope setting)

OUT1 Proportional band (P) = $\{(14-6) \div (20-4)\}$ x 100 = 0.5 x 100 = 50 (%)

(3) Calculating SV (desired value) so that 4 mA DC output can be obtained from 6 mA DC input (Parallel shift setting)

 $SV = \{(6-4) \times 12.5\} + 5.0 \text{ (Scaling low limit)} = 30.0$

Input, Output and Indication



(Fig. 9.5.3-1)

9.6 Clearing Data

If data is cleared, data will revert to factory default values.

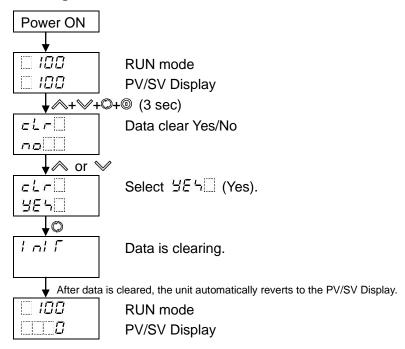
To clear data, press and hold \wedge , \vee , \mathbb{O} , \mathbb{O} (in that order) together for approx. 3 seconds on the PV/SV Display.

The unit enters [Data clear Yes/No] mode.

Select 'Yes', and press the O key. Data will be cleared.

While data is clearing, Int I is indicated on the PV Display.

Clearing Data



10. Action Explanation

10.1 OUT1 Action (BCS2)

Action	Reverse (Heatin	g) Action	Direct (Cooling)	Action
Control action	ON P-band OFF	∑ SV	P-band >	ON OFF
Relay contact output	© Cycle action is perfor according to deviati	Timed on.	© Cycle action is perfor according to deviati	7 3 8 med on.
Non-contact voltage output	+ ⑦¬¬ + ⑦¬¬ 12 V DC	+7¬ 0 V DC -8¬	+7 +7 0 V DC 0/12 V DC -8 Cycle action is perfaccording to devia	+7— 12 V DC -8— ormed tion.
Direct current output	+ ⑦	- 8	+7 +7 +7 4 mA DC 4 to 20 mA DC -8 Changes continuaccording to devia	_ 8 ously
Indicator (O1) Green	Lit	Unlit	Unlit	Lit

: Turns ON (lit) or OFF (unlit).

BCR2, BCD2: OUT1 terminal numbers: 15, 16

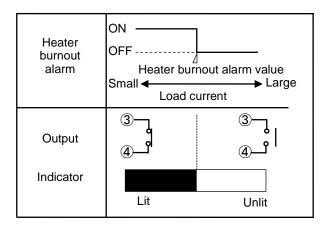
10.2 OUT1 ON/OFF Control Action (BCS2)

Action	Reverse (Heating	g) Action	Direc	ct (Cooling) A	ction
Control action	ON Hysteresis	Š SV		Hysteresis	ON OFF
Relay contact output	⑦	77	7 %		®
Non-contact voltage output	+⑦¬ 12 V DC -®¬	+7¬¬ 0 V DC -8¬¬	+7¬¬ 0 V DC -8)¬		+⑦¬ 12 V DC -®¬
Direct current output	+⑦¬¬ 20 mA DC -8¬¬	+⑦¬ 4 mA DC -®¬	+7¬¬ 4 mA DC -8>¬		+⑦¬¬ 20 mA DC -®¬¬
Indicator (O1) Green	Lit	Unlit	Unlit		Lit

: Turns ON (lit) or OFF (unlit).

BCR2, BCD2: OUT1 terminal numbers: 15, 16

10.3 Heater Burnout Alarm Action



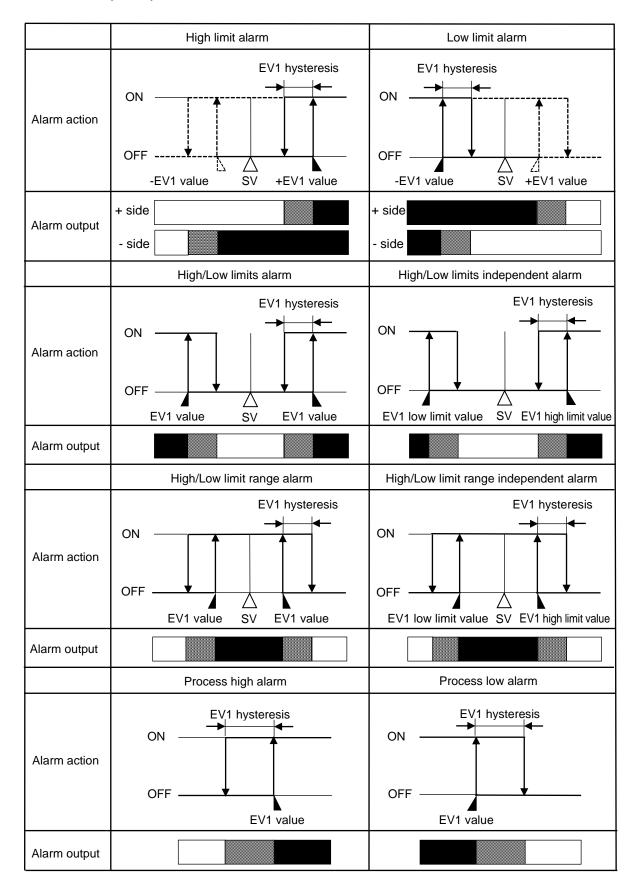
• BCS2: Event output 1 terminal numbers: 3, 4 Event output 2 terminal numbers: 5, 6

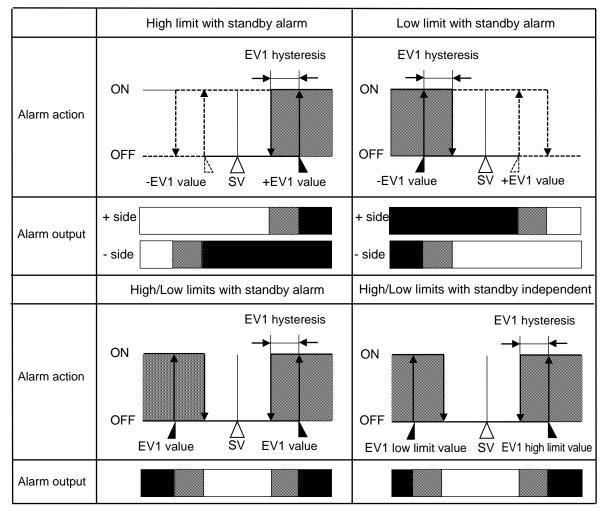
• BCR2, BCD2: Event output 1 terminal numbers: 17, 18

Event output 2 terminal numbers: 19, 20

If EV2+D□ option is ordered: Event output 2 terminal numbers: 6, 7

10.4 Alarm Action (BCS2)





: Event output EV1 terminals 3, 4: ON

: Event output EV1 terminals 3, 4: ON or OFF

: Event output EV1 terminals 3, 4: OFF

: Alarm output is in standby.

 EV1 value, EV1 high limit value, and EV1 hysteresis represent EV1 alarm value, EV1 high limit alarm value, and EV1 alarm hysteresis respectively.
 For EV2, read "EV2" for "EV1".

• EV1 indicator lights when Event output 1 terminals 3 and 4 are ON, and turns off when their output terminals 3 and 4 are OFF.

EV2 indicator lights when Event output 2 terminals 5 and 6 are ON, and turns off when their output terminals 5 and 6 are OFF.

BCR2, BCD2: Event output 1 terminal numbers: 17, 18
 Event output 2 terminal numbers: 19, 20

If EV2+D□ option is added: Event output 2 terminal numbers: 6, 7

10.5 OUT2 (Heating/Cooling Control) Action (BCS2)

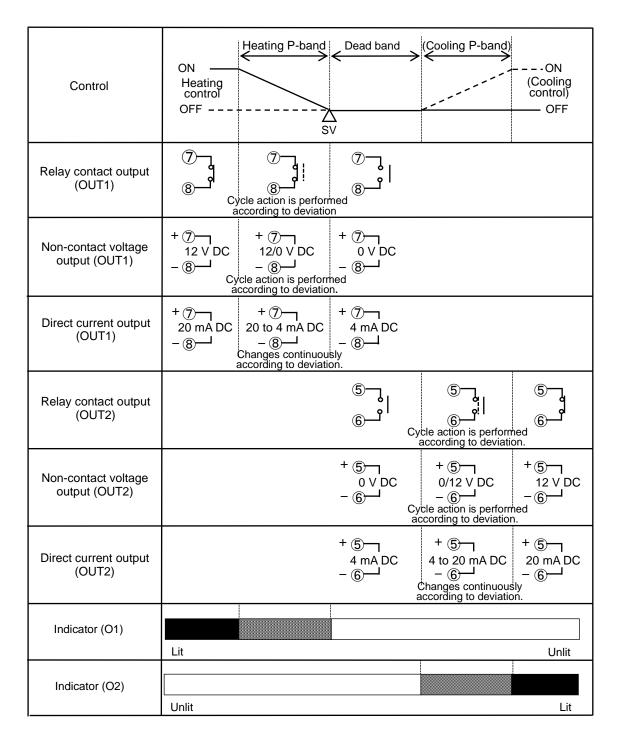
	ON —	Heating P-band	(Cooling P-band)	ON
Control action	Heating control			(Cooling control)
	OFF	z s	<u> </u>	—— OFF
Relay contact output (OUT1)	? 8	(7) (8) Cycle action is performaccording to deviate	(7) (8) (med ion.	
Non-contact voltage output (OUT1)	+⑦¬¬ 12 V DC -®¬	+ ⑦¬¬ 12/0 V DC - ⑧¬¬ ycle action is perfor according to deviati	+ ⑦¬¬ 0 V DC - ⑧¬¬ med on.	
Direct current output (OUT1)	+ ⑦— 20 mA DC - ⑧—	+ 7 — 20 to 4 mA DC — 8 — Changes continuous according to deviation	+ ⑦¬¬ 4 mA DC - ⑧¬¬ sly on.	
Non-contact voltage output (OUT2)		5 6	ycle action is perfor	5 6 med on.
Non-contact voltage output (OUT2)		+⑤¬ 0 V DC -⑥¬	+ ⑤ DC 0/12 V DC - ⑥ Vector of the control of the c	+5 — 12 V DC —6 — med on.
Direct current output (OUT2)		+ ⑤ — 4 mA DC — ⑥ — C a	+5— 4 to 20 mA DC -6— hanges continuous coording to deviation	+ ⑤— 20 mA DC – ⑥— 'y n.
Indicator (O1)	Lit			Unlit
Indicator (O2)	Unlit			Lit

: Turns ON (lit) or OFF (unlit).

: Represents Heating control action. : Represents Cooling control action.

• BCR2, BCD2: OUT1 terminal numbers: 15, 16 OUT2 terminal numbers: 19, 20

10.6 OUT2 (Heating/Cooling Control) Action (When Setting Dead Band) (BCS2)

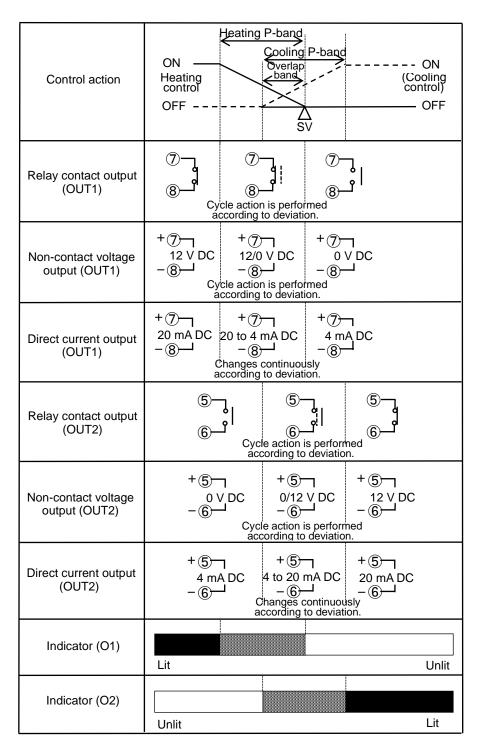


: Turns ON (lit) or OFF (unlit).

: Represents Heating control action.: Represents Cooling control action.

BCR2, BCD2: OUT1 terminal numbers: 15, 16
 OUT2 terminal numbers: 19, 20

10.7 OUT2 (Heating/Cooling Control) Action (When Setting Overlap Band) (BCS2)



: Turns ON (lit) or OFF (unlit).

: Represents Heating control action.: Represents Cooling control action.

• BCR2, BCD2: OUT1 terminal numbers: 15, 16
OUT2 terminal numbers: 19, 20

11. Specifications

11.1 Standard Specifications

Rating

Rated scale		Input	Input	Range	Resolution
		K	-200 to 1370°C	-328 to 2498°F	1℃ (℉)
		IX.	-200.0 to 400.0℃	-328.0 to 752.0°F	0.1℃ (℉)
		J	-200 to 1000°C	-328 to 1832°F	1℃ (℉)
		R	0 to 1760°C	32 to 3200°F	1℃ (℉)
			0 to 1760°ℂ	32 to 3200°F	1°C (°F)
		В	0 to 1820℃	32 to 3308°F	1℃ (℉)
		E	-200 to 800°C	-328 to 1472°F	1°C (°F)
		Т	-200.0 to 400.0℃	-328.0 to 752.0°F	0.1℃ (℉)
		N	-200 to 1300°C	-328 to 2372 F	1°C (°F)
		PL-Ⅱ	0 to 1390°C	32 to 2534°F	1°C (°F)
		C(W/Re5-26)	0 to 2315℃	32 to 4199°F	1°C (°F)
		D4400	-200.0 to 850.0℃	-328.0 to 1562.0°F	0.1℃ (°F)
		Pt100	-200 to 850°C	-328 to 1562°F	1°C (°F)
		ID4400	-200.0 to 500.0℃	-328.0 to 932.0 F	0.1℃ (℉)
		JPt100	-200 to 500°C	-328 to 932°F	1°C (°F)
		4 to 20 mA	-2000 to	10000 (*)	1
		0 to 20 mA	-2000 to	10000 (*)	1
		0 to 1 V	-2000 to 10000 (*)		1
		0 to 5 V	-2000 to 10000 (*)		1
		1 to 5 V	-2000 to 10000 (*)		1
		0 to 10 V	-2000 to 10000 (*)		1
		(*) Scaling and de	cimal point place selection	on are possible.	
Input	Thermocouple	K, J, R, S, B, E,	, T, N, PL-II , C(W/Re	5-26)	
		External resis	stance: 100 Ω max.		
		However, for	B input, External resi	stance: 40 Ω max.	
	RTD	Pt100, JPt100	7.		
		·		ce: 10 Ω max. per wire	1
	Direct current	0 to 20 mA DC,			
		Input impeda			
	DO Herri		ut current: 50 mA ma	X.	
	DC voltage	0 to 1 V DC			
			Input impedance: 1 M Ω min. Allowable input voltage: 5 V DC max.		
		•	•		
		Allowable signal source resistance: 2 kΩ max. 0 to 5 V DC, 1 to 5 V DC, 0 to 10 V DC			
		Input impedance: $100 \text{ k}\Omega$ min.			
		Allowable input voltage: 15 V DC max.			
		Allowable signal source resistance: 100 Ω max.			
Power	BC 2 00-	100 to 240 V A	C 50/60 Hz		
supply voltage	BC□2□10-□□	24 V AC/DC 50/60 Hz			
Allowable	BC 2 00-	85 to 264 V AC			
voltage fluctuation	BC□2□10-□□	20 to 28 V AC/[DC .		

General Structure

eneral Structi	ure			
External	BCS2	48 x 48 x 68 mm (W x H x D) (Depth of control panel interior: 60 mm)		
dimensions	BCR2	48 x 96 x 68 mm	(W x H x D) (Depth of control panel interior: 60 mm)	
	BCD2	96 x 96 x 68 mm	(W x H x D) (Depth of control panel interior: 60 mm)	
Mounting		Flush	, , , , , , , , , , , , , , , , , , , ,	
Case		Flame-resistant r	resin. Black	
Front panel		Membrane sheet		
Drip-proof/Du	et proof			
- · ·	EN	Front panel: IP66, Rear case: IP20, Terminal section: IP00		
Compliant standards		EN61010-1 (Pollution degree 2, Overvoltage category II)		
Standards	EC	EMI: EN61326	and of a Paral Paral and ENERGOA On a A	
	(EMC	Electric-field strength of radiated disturbance: EN55001 Group 1		
	directive)		Class A	
			oltage: EN55011 Group 1 Class A	
		EMS: EN61326		
Indication	PV Display	Indicates PV.	ED Pauls	
structure		7-segment Red L		
		BCS2	Character size: 12.4 x 5.8 mm (H x W)	
		BCR2	Character size: 14 x 5.8 mm (H x W)	
		BCD2	Character size: 24 x 11 mm (H x W)	
	SV Display	Indicates SV.		
		7-segment Green	1	
		BCS2	Character size: 8.8 x 3.9 mm (H x W)	
		BCR2	Character size: 14 x 5.8 mm (H x W)	
		BCD2 Character size: 14 x 7 mm (H x W)		
	MEMO/STEP	Indicates Set value memory number (Fixed value control) or Step		
	Display	number (Progran	•	
	(BCR2,	7-segment Green		
	BCD2)	BCR2	Character size: 14 x 5.8 mm (H x W)	
		BCD2	Character size: 14 x 7 mm (H x W)	
	Action	O1 (Green)	Lit when control output OUT1 is ON.	
	indicators		For direct current output type, flashes corresponding	
		O2 (Yellow)	to the MV in 125 ms cycles. Lit when control output OUT2 (EV2, DS, DA, EV2+D	
		OZ (TOHOW)	options) is ON.	
			For direct current output type (DA, EV2+DA options),	
			flashes corresponding to the MV in 125 ms cycles.	
		EV1 (Red)	Lit when Event output 1 is ON.	
		EV2 (Red)	Lit when Event output 2 (EV2, EV2+D□ options) is	
			ON.	
			Unlit if 19 (Heating/Cooling control relay contact	
		ΛΤ (\/alla)	output) is selected in [Event output EV2 allocation].	
		AT (Yellow)	Flashes while AT, 'AT on startup' or Auto-reset is performing.	
		R/L (Yellow)	Lit during Remote action from Remote/Local	
			switching (EIT option).	
		T/R (Yellow)	Lit during Serial communication (C5W, C5 options) TX	
		, ,	(transmitting) output.	
		MEMO (Yellow)	Lit when Set value memory number (Fixed value	
		,	control) is indicated.	
			(BCR2, BCD2)	
		STEP (Green)	Lit when a step number (Program control) is indicated.	
			(BCR2, BCD2)	

Terminal arrangement	Refer to 'Terminal arrangement'. (p.19)	
Console connector	By connecting to the tool cable (CMD-001, sold separately), the	
	following operations can be conducted from an external computer using	
	the Console software SWC-BCx01M.	
	Reading and setting of SV, PID and various set values	
	Reading of PV and action status	

Setting Structure

Function	UP key	Increases the numeric value.		
key		By pressing this key for 1 second during Program control, the performing		
		step is interrupted, proceeding to the beginning of the next step.		
		(Advance function)		
	DOWN key	Decreases the numeric value.		
	MODE key	Selects a setting mode, or regi	sters the set data.	
		By pressing this key for 3 seconds during RUN mode, the unit enters		
		Monitor mode.		
	OUT/OFF key	The following function can be selected in [OUT/OFF key function].		
		Selection Item	Action	
		Control output OFF function	Turns the control output ON or OFF.	
		Auto/Manual control	Switches the Auto/Manual control.	
		Program control	Starts/Stops the Program control.	

Indication Performance

Base accuracy		At ambient temperature 23°C (for a single unit mounting)	
	Thermocouple	Within ±0.2% of each input span±1 digit	
		However R, S inputs, 0 to 200°C (32 to 392°F): Within ± 6 °C (12°F)	
		B input, 0 to 300° (32 to 572°F): Accuracy is not guaranteed.	
		K, J, E, T, N inputs, Less than 0°C (32°F): Within ±0.4% of input	
		span±1 digit	
	RTD	Within ±0.1% of each input span±1 digit	
	Direct current,	Within ±0.2% of each input span±1 digit	
	DC voltage		
Effect of ambient temperature		Within 50 ppm/°C of each input span	
Input sampling period		125 ms	
Time accur	acy	Within ±1.0% of setting time	

Control Performance

Control action	PID control (with AT function)
	• PI control: When derivative time is set to 0
	PD control (with Auto-reset, Manual reset function):
	When integral time is set to 0
	P control (with Auto-reset, Manual reset function):
	When derivative time and integral time are set to 0.
	ON/OFF control: When proportional band is set to 0 (or 0.0)
OUT1	Thermocouple, RTD inputs without decimal point: 0 to input span
proportional	Thermocouple, RTD inputs with decimal point: 0.0 to input span
band	Direct current, voltage inputs: 0.0 to 1000.0%
Integral time	0 to 3600 sec
Derivative time	0 to 1800 sec
OUT1 propor-	0.5, or 1 to 120 sec
tional cycle	,-
ARW	0 to 100%

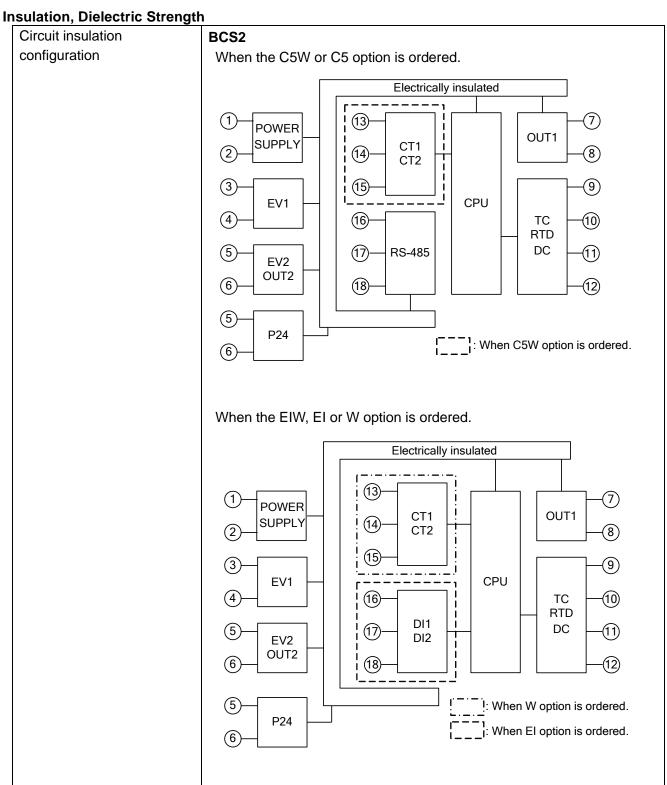
	Manual reset	±Proportional band value
	OUT1 ON/OFF	Thermocouple, RTD inputs: 0.1 to 1000.0℃ (℉)
	hysteresis	Direct current, voltage inputs: 1 to 10000 (The placement of the decimal
		point follows the selection.)
	OUT1 high limit, OUT1 low limit	0 to 100% (Direct current output type: -5 to 105%)
Control	Relay contact	Control capacity: 3 A 250 V AC (resistive load)
output	1a	1 A 250 V AC (inductive load cos <i>Ф</i> =0.4)
		Electrical life: 100,000 cycles
		Minimum applicable load: 10 mA 5 V DC
	Non-contact	12 V DC±15%
	voltage (For SSR drive)	Max 40 mA (short circuit protected)
	Direct current	4 to 20 mA DC
		Resolution: 12000
		Load resistance: Max. 550 Ω

Standard Function

<u>tandard Fu</u>				
EV1 outpu	t	The output is turned ON or OFF depending on the conditions selected in		
		[Event output EV1 allocation].		
		Relay contact 1a Control capacity: 3 A 250 V AC (resistive load)		
		1 A 250 V AC (inductive load cos <i>ϕ</i> =0.4)		
		Electrical life: 100,000 cycles		
		Minimum applicable load: 10 mA 5 V DC		
		When an alarm type and Energized action are selected in [Event output		
		EV1 allocation] or [Event output EV2 allocation]: The alarm action point		
		is set by ±deviation from the SV (excluding Process alarm) and if PV		
		goes outside the range, alarm output is turned ON or OFF (High/Low		
		limit range alarm).		
		When De-energized action is selected, alarm is activated conversely.		
	Туре	High limit alarm, Low limit alarm, High/Low limits alarm, High/Low limits		
		independent alarm, High/Low limit range alarm, High/Low limit range		
		independent alarm, Process high alarm, Process low alarm, High limit		
		with standby alarm, Low limit with standby alarm, High/Low limits with		
		standby alarm, High/Low limits with standby independent alarm		
		Energized/De-energized action are applied to the above alarms, totaling		
		24 alarm types. No alarm action can also be selected.		
	Action	ON/OFF action		
	Hysteresis	Thermocouple, RTD inputs: 0.1 to 1000.0℃ (℉)		
		Direct current, voltage inputs: 1 to 10000 (The placement of the decimal point follows the selection.)		
	Output	EV1 output or EV2 output for which Alarm output (001 to 012) is		
		selected in [Event output EV1/EV2 allocation].		
	Alarm value 0	If 'Enabled' is selected in [Alarm value 0 Enabled/Disabled], the		
	Enabled/	following alarm type activates even if alarm value is set to 0 (zero):		
	Disabled	High limit alarm, Low limit alarm, High/Low limits alarm, High/Low limits		
		independent alarm, High/Low limit range alarm, High/Low limit range		
		independent alarm, High limit with standby alarm, Low limit with standby		
		alarm, High/Low limits with standby alarm, High/Low limits with standby		
	independent alarm.			
Loop breal	k alarm	Detects heater burnout, sensor burnout and actuator trouble.		
		Event output EV1 or Event output EV2 for which Loop break alarm (014)		
		is selected in [Event output EV1/EV2 allocation].		

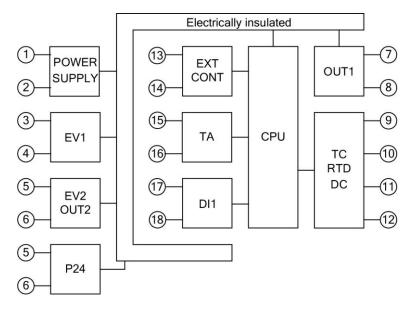
Simplified converter	If 'Converter' is selected in [Controller/Converter], this instrument can	
function	be used as a converter. The following items are automatically set.	
	Setting Item	Values or Selection
	SV1	Scaling low limit value
	SV2	Scaling low limit value
	(BCS2: EIW, EIT, EI options,	
	BCR2/BCD2: C5W, EIW, EIT, EI options)	
	SV3	Scaling low limit value
	(BCS2: EIW, EI options,	
	BCR2/BCD2: C5W, EIW, EIT, EI options)	
	SV4	Scaling low limit value
	(BCS2: EIW, EI options,	
	BCR2/BCD2: C5W, EIW, EIT, EI options)	
	AT/Auto-reset Perform/Cancel	AT/AT on startup/Auto-reset Cancel
	OUT1 proportional band	Scaling span
	Integral time	0
	Derivative time	0
	Reset	(Initialized) (Reset value calculated by Auto-reset function)
	OUT1 high limit	100
	OUT1 low limit	0
	OUT1 rate-of-change	0
	OUT2 proportional band	Scaling span
	Direct/Reverse action	Direct action
	EV1/EV2 alarm value 0	Disabled
	Enabled/Disabled	
	EV1/EV2 alarm value	0 or Input range low limit value (Scaling
		low limit value)
	EV1/EV2 high limit alarm value	0 or Input range low limit value (Scaling
		low limit value)
	EV1/EV2 alarm hysteresis	1.0 (DC voltage, current inputs: The
		placement of the decimal point follows
		the selection.)
	EV1/EV2 alarm delay time	0
	EV1/EV2 alarm Energized/	Energized
	De-energized	
	Loop break alarm time	0
	Loop break alarm band	0
	Event input DI1 allocation	No event
	(BCS2: EIW, EIT, EI options,	
	BCR2/BCD2: C5W, EIW, EIT, EI options)	
	Event input DI2 allocation	No event
	(BCS2: EIW, EI options,	
	BCR2/BCD2: C5W, EIW, EIT, EI options)	
	Event output EV1 allocation	No event
	Event output EV2 allocation	No event
	(EV2, EV2+D□ options)	
	Remote/Local (EIT option)	Local
	(LTT OPHOTI)	

Transmission output type (EIT option)	PV transmission
Transmission output high limit	Input range high limit
Transmission output low limit (EIT option)	Input range low limit
SV rise rate	0
SV fall rate	0
OUT/OFF key function	Control output OFF
4 to 20 mA DC	
Load resistance: Max 550 Ω	



Circuit insulation configuration

When the EIT option is ordered.

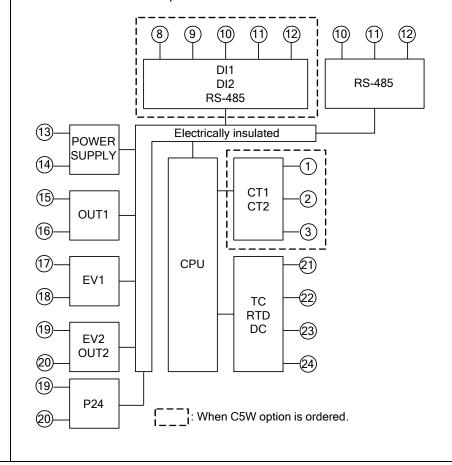


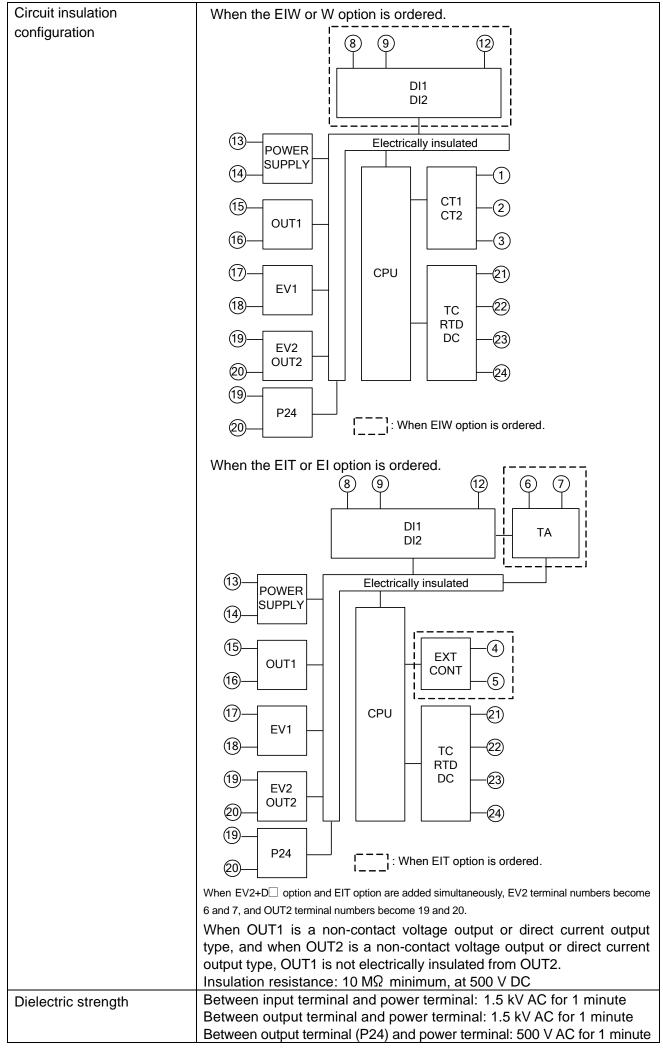
When OUT1 is a non-contact voltage output or direct current output type, and when OUT2 is a non-contact voltage output or direct current output type, OUT1 is not electrically insulated from OUT2.

Insulation resistance: 10 $M\Omega\,$ minimum, at 500 V DC

BCR2, BCD2

When the C5W or C5 option is ordered.





Power consumption		100 to 240 V AC	Approx. 8 VA max. (When the maximum number of	
			options are added: Approx. 11 VA max.)	
		24 V AC	Approx. 5 VA max. (When the maximum number of	
			options are added: Approx. 8 VA max.)	
		24 V DC	Approx. 5 W max. (When the maximum number of	
			options are added: Approx. 8 W max.)	
Rush current		100 to 240 V AC	Max. 14 to 34 A	
		24 V AC	Max. 34 A	
		24 V DC	Max. 34 A	
Ambient tempe	erature	-10 to 55°C (Non-c	condensing, No icing)	
Ambient humic	dity	35 to 85 %RH (No	n-condensing)	
Weight	BCS2	Approx. 110 g		
	BCR2	Approx. 160 g		
	BCD2	Approx. 220 g		
Accessories in	cluded	Mounting frame: 1	piece (BCS2)	
		Screw type mounting bracket: 1 set (BCR2, BCD2)		
		Instruction manua	I (excerpt): 1 copy	
Accessories so	old	Terminal cover		
separately		CT (Current transf	former):	
		CTL-6-S-H (For Heater burnout alarm 20 A)		
		CTL-12-S36-10L1U (For Heater burnout alarm 100 A)		
		Tool cable CMD-001		
Environmental	specification	RoHS directive compliant		
Altitude		2,000 m or less		

Attached Functions

Sensor cor	rection	Sets slope of input value from a sensor.	
coefficient			
Sensor cor	rection	Corrects the input value from a sensor.	
Set value lo	ock	Locks the set values to prevent setting errors.	
Auto/Manu	al control	Switches Auto/Manual control.	
switching		In Manual control, sets MV with the	
SV ramp fu	ınction	When the SV is adjusted, it approaches the new SV by the preset	
		However, the SV ramp function does not operate during remote operation.	
		rate-of-change. Set SV rise rate and SV fall rate respectively.	
SV Rise/Fa	all rate action	When control output is turned from OFF to ON, or switched from Manual	
		to Automatic control, SV start or PV start can be selected for SV rise rate	
		or SV fall rate action.	
Program co	ontrol	1 pattern; 9 steps	
Power failu	re	The setting data is backed up in the non-volatile IC memory.	
counterme	asure		
Self-diagnosis		The CPU is monitored by a watchdog timer, and if an abnormal status	
		occurs, the controller is switched to warm-up status, turning all outputs	
		OFF.	
Automatic	cold junction	This detects the temperature at the connecting terminal between the	
temperatur	e compensation	thermocouple and the instrument, and always maintains it at the same	
		status as if the reference junction location temperature was at 0°C (32°F).	
Indication	Thermocouple	[Input range low limit value – 50° (100°F)] to	
range,		[Input range high limit value + 50° (100°F)]	
Control	RTD	[Input range low limit value – (Input span x 1%)] to	
range		[Input range high limit value + 50°C (100°F)]	
	DC voltage,	[Scaling low limit value – (Scaling span x 1%)] to	
	Direct current	[Scaling high limit value + (Scaling span x 10%)]	

Input error (Overscale, Underscale) If input errors (overscale, underscale) occur, the following will be performed depending on the selection in [Error indication Enabled/Disabled]. If Disabled is selected in [Error indication Enabled/Disabled]: Overscale occurs if PV has exceeded Input range high limit

Overscale occurs if PV has exceeded Input range high limit value (Scaling high limit value for DC voltage, current inputs). The PV Display indicates PV.

Underscale occurs if PV has dropped below Input range low limit value (Scaling low limit value for DC voltage, current inputs). The PV Display indicates PV.

For manual control, the preset MV is output.

If Enabled is selected in [Error indication Enabled/Disabled]:

Overscale occurs if PV has exceeded Input range high limit value (Scaling high limit value for DC voltage, current inputs). The PV Display indicates the PV and error code $\mathcal{E}_{\mathcal{F}}\mathcal{D}\mathcal{G}$ alternately.

Underscale occurs if PV has dropped below Input range low limit value (Scaling low limit value for DC voltage, current inputs). The PV Display indicates the PV and error code $\mathcal{E} \vdash \mathcal{G}\mathcal{E}$ alternately.

For manual control, the preset MV is output.

Burnout

If burnout occurs, the following will be performed depending on the selection in [Error indication Enabled/Disabled].

If Disabled is selected in [Error indication Enabled/Disabled]:

If PV has exceeded Indication range and Control range, the PV Display flashes [_____].

If PV has dropped below Indication range and Control range, the PV Display flashes [____]. If thermocouple or RTD input is burnt out, or if DC voltage (0 to 1 V DC) input is disconnected, the PV Display flashes [____].

If DC voltage or current input is disconnected:

For 4 to 20 mA DC, 1 to 5 V DC inputs, the PV Display flashes [____].

For 0 to 20 mA DC, 0 to 5 V DC and 0 to 10 V DC inputs, the PV Display indicates the value corresponding with 0 mA DC or 0 V DC input.

OUT1 and OUT2 are turned OFF (OUT1 low limit value for direct current output, OUT2 low limit value for DA, EV2+DA). For manual control, the preset MV is output.

If Alarm, Heater burnout alarm or Loop break alarm is selected in [Event output EV1/EV2 allocation], Event output will be turned ON under the alarm active conditions.

Burnout is enabled even in standby (program control waiting) mode in Program control.

[Output status when input errors occur] can be used only for controllers using direct current and voltage inputs, and direct current output.

Output status differs depending on selection in [Output status when input errors occur].

Output status			Output	Status	
when input	Contents, O		JT1	OUT2	
errors occur	Indication	Direct (Cooling)	Reverse (Heating)	Direct (Cooling)	Reverse (Heating)
Circio occar		action	action	action	action
on	[]	ON (20mA) or OUT1 high limit value (*)	OFF (4mA) or	OFF or	ON or OUT2 high limit value (*)
oFF.	is flashing. OFF (4mA) or OUT1 low limit value	OUT1 low limit value	OUT2 low limit value	OFF or OUT2 low limit value	
on	[]	OFF (4mA) or OUT1 low limit	ON (20mA) or OUT1 high limit value (*)	ON or OUT2 high limit value (*)	OFF or OUT2 low limit
ρFF□	is flashing. Value	OFF (4mA) or OUT1 low limit value	OFF or OUT2 low limit value	value	

^(*) Outputs a value between OFF (4mA) and ON (20mA) or between OUT1 (or OUT2) low limit value and OUT1 (or OUT2) high limit value, depending on deviation.

If Enabled is selected in [Error indication Enabled/Disabled]:

If PV has exceeded Indication range, Control range, the PV Display indicates $[\ \ \]$ and $[\ \ \ \ \]$ alternately.

If PV has dropped below Indication range, Control range, the PV Display indicates [---] and $[E \cap G]$ alternately.

If thermocouple, RTD or DC voltage (0 to 1 V DC) input is burnt out or disconnected, the PV Display indicates $\begin{bmatrix} \overline{} & \overline{} \end{bmatrix}$ and $\begin{bmatrix} \overline{} & \overline{} & \overline{} \end{bmatrix}$ alternately.

If DC voltage or current input is disconnected:

For 4 to 20 mA DC, 1 to 5 V DC inputs, the PV Display indicates $[____]$ and $[\not \vdash r \ \vec{\Box} \ \vec{\ }]$ alternately. For 0 to 20 mA DC, 0 to 5 V DC and 0 to 10 V DC inputs, the PV Display indicates the value corresponding with 0 mA DC or 0 V DC input.

OUT1 and OUT2 are turned OFF (OUT1 low limit value for direct current output type, OUT2 low limit value for DA, EV2+DA).

For Manual control, the preset MV is output.

If Alarm, Heater burnout alarm or Loop break alarm is selected in [Event output EV1/EV2 allocation], Event output will be turned ON under the alarm active conditions.

In Program control, burnout is enabled even in standby (program control waiting) mode.

[Output status when input errors occur] can be used only for controllers using direct current and voltage inputs, and direct current output.

Output status differs depending on selection in [Output status when input errors occur].

Output status			Output	Status	
when input	Contents, OU		JT1	OUT2	
errors occur	Indication	Direct (Cooling)	Reverse (Heating)	Direct (Cooling)	Reverse (Heating)
Ciroio cocai		action	action	action	action
on III	Indicates [] and	ON (20mA) or OUT1 high limit value (*)	OFF (4mA) or OUT1 low limit	OFF or OUT2 low limit	ON or OUT2 high limit value (*)
oFF[]	[E - []] alternately.	OFF (4mA) or OUT1 low limit value	value	value	OFF or OUT2 low limit value
on	Indicates [] OFF (4mA) or and OUT1 low limit	ON (20mA) or OUT1 high limit value (*)	ON or OUT2 high limit value (*)	OFF or	
oFF[]	[E - [] 7] alternately.	OUT1 low limit value	OFF (4mA) or OUT1 low limit value	OFF or OUT2 low limit value	OUT2 low limit value

^(*) Outputs a value between OFF (4mA) and ON (20mA) or between OUT1 (or OUT2) low limit value and OUT1 (or OUT2) high limit value, depending on deviation.

Warm-up indication	After the power supply to the instrument is turned on, the PV Display indicates the input type, and SV Display indicates input range high limit value (for thermocouple, RTD inputs) or scaling high limit value (for direct current and voltage inputs) for approximately 3 seconds.
Console	By connecting to the tool cable (CMD-001, sold separately) to the console
communication	connector, the following operations can be conducted from an external computer, using the Console software SWC-BCx01M. Console communication and Serial communication (C5W option) cannot be used together. (1) Reading and setting of SV, PID and various set values (2) Reading of PV and action status
	(3) Function change Communication line: TTL level

11.2 Optional Specifications

1.2 Optional Specifications	
Event input	2 points of Event input (BCS2: 1 point for EIT option) can be applied.
BCS2: EIW, EIT, EI options	Any Event selected in [Event input DI1/DI2 allocation] will be performed
BCR2/BCD2: C5W, EIW,	depending on the DI1/DI2 input ON (Closed) or OFF (Open) status.
EIT, EI options	Circuit current when Closed: Approx. 16 mA
Event output	Output will be turned ON or OFF depending on the Event conditions
(EV2, EV2+D□ options)	selected in [Event output EV2 allocation].
(= : = , = : = : = : = : : : : : : : : :	Relay contact, 1a
	Control capacity: 3 A 250 V AC (resistive load)
	1 A 250 V AC (inductive load, $\cos\phi$ =0.4)
	Electrical life: 100,000 cycles
	Minimum applicable load: 10 mA 5 V DC
Heater burnout alarm	Monitors heater current with CT (current transformer), and detects burnout.
(C5W, EIW, W options)	EV1/EV2 output, for which Heater burnout alarm is selected in [Event output
(COVV, EIVV, VV Options)	EV1/EV2 allocation], will be turned ON or OFF.
	This alarm is also activated when the input is burnt out.
	Rated current: 20 A, 100 A (Must be specified when ordering.)
	Single-phase: Detects burnout with CT1 input.
	3-phase: Detects burnout with CT1 and CT2 inputs.
Lingting/Coolings control	Setting accuracy: Within ±5% of the rated value
Heating/Cooling control	Performs Heating/Cooling control.
(DS, DA, EV2, EV2+D	(Heating side specifications are the same as those of OUT1.)
options)	OUT2 proportional band:
	Thermocouple, RTD inputs without decimal point: 0 to Input span
	Thermocouple, RTD inputs with decimal point: 0.0 to Input span
	DC voltage, current inputs: 0.0 to 1000.0%
	OUT2 integral time: Same as OUT1 integral time
	OUT2 derivative time: Same as OUT1 derivative time
	OUT2 proportional cycle: 0.5, or 1 or 120 seconds
	Overlap/Dead band setting range:
	Thermocouple, RTD inputs: -200.0 to 200.0℃ (℉)
	DC voltage, current inputs: -2000 to 2000 (The placement of the decimal
	point follows the selection.)
	OUT2 ON/OFF hysteresis:
	Thermocouple, RTD inputs: 0.1 to 1000.0°C (°F)
	DC voltage, current inputs: 1 to 10000 (The placement of the decimal point
	follows the selection.)
	OUT2 high limit: 0 to 100% (Direct current output: -5 to 105%)
	OUT2 low limit: 0 to 100% (Direct current output: -5 to 105%)
	OUT2 cooling method:
	One cooling method can be selected from Air cooling (linear
	characteristics), Oil cooling (1.5th power of the linear characteristics)
	and Water cooling (2nd power of the linear characteristics) by keypad
	operation.
	Cooling output (OUT2):
	Relay contact 1a (EV2, EV2+DR)
	Control capacity: 3 A 250 V AC (resistive load)
	1 A 250 V AC (inductive load, $\cos\phi$ =0.4)
	Electrical life: 100,000 cycles
	Non-contact voltage (for SSR drive) (DS, EV2+DS): 12 V DC±15%,
	Max. 40 mA (short circuit protected)
	Direct current (DA, EV2+DA): 4 to 20 mA DC
	Resolution: 12000
	Load resistance: Max. 550 Ω

Serial communication			be carried out from an e	•
(C5W, C5 options)	Serial communication and Console communication cannot be used together.			
	(1) Reading and setting of the SV, PID values and various set values			
	(2) Reading of the PV and action status			
	. ,	(3) Function change Cable length: Max 1.2 km, Cable resistance: Within 50 Ω (Terminators are		
	_		but if used, use 120 Ω c	,
	side	-	but ii useu, use 120 ½ t	or more on bour
	Communication li	,	485	
			duplex communication	
			rt-stop synchronization	
	_		, 19200, 38400 bps (Sel	ectable by keypad)
	Data bit/Parity:		,, - (
	_	8 bits, (Sel	ectable by keypad)	
	Parity: Even/Od	dd/No parity	(Selectable by keypad)	
	Stop bit: 1 bit, 2 b	its (Selecta	ble by keypad)	
	Communication p	rotocol: Shi	nko protocol/MODBUS A	ASCII/MODBUS RTU
		(Se	electable by keypad)	
	Data format:			
	Communication	Shinko	MODBUS ASCII	MODBUS RTU
	protocol	protocol		
	Start bit	7	7 (0)	8
	Data bit	/	7 (8) Selectable	8
	Parity	Even	Even (No parity, Odd) Selectable	No parity (Even, Odd) Selectable
	Stop bit	1	1 (2) Selectable	1 (2) Selectable
	Number of conne	ctable units	: Maximum 31 units to 1	
	Communication e	rror detection	on: Parity, checksum (Sh	inko protocol),
	Digital automal co	-	ODBUS ASCII), CRC-16	6 (MODBUS RTU)
	Digital external se	•	inka nyawawamahla asat	rolloro DCA4 or DCD4
	<u>-</u>		inko programmable conti	
External setting input	,		sion' in [Communication	protocoij).
(EIT option)		0 0	al to remote bias value.	
(Lit option)	Not available for F	•		
	Setting signal: 4 to			
	Allowable input: 5			
	Input impedance:			
Transmission sutput	Input sampling pe			a) to analog signal
Transmission output (EIT option)	Converting the value (PV, SV, MV or DV transmission) to analog signal every 125 ms, outputs the value in current or voltage.			
(ETT Option)	<u> </u>	-	low limit value if Transn	
	·	-		mission output mgm
	limit and low limit value are the same. Resolution: 12000 Output: 4 to 20 mA DC (Load resistance: Maximum 550 Ω)			
				550 Ω)
	Output accuracy: Within ±0.3% of Transmission output span			<i>'</i>
Insulated power output				
(P24 option)		Output voltage: 24±3 V DC (when load current is 30 mA DC) Ripple voltage: Within 200 mV DC (when load current is 30 mA DC)		
, , ,	Max. load current:		0 (
	Mari Ioda Jarronti	20, (DO		

12. Troubleshooting

If any malfunctions occur, refer to the following items after checking that power is being supplied to the controller.

12.1 Indication

Problem	Possible Cause	Solution
The PV Display	Internal non-volatile IC	Cancel the error code by pressing the © key,
indicates [<i>E - □ l</i>].	memory is defective.	and perform data clearing. (p.108)
		If the problem is not still solved, contact our
The PV Display	Data writing (in non-volatile	agency or us. Cancel the error code by pressing the © key,
indicates $[E \cap GZ]$.	IC memory) error when	and perform data clearing. (p.108)
	power failure occurs.	
The PV Display	Overscale.	Check the input signal source.
indicates PV and	PV has exceeded Input range	
[<i>E-0</i> 5] (*)	high limit value (scaling high	
alternately.	limit value for DC voltage,	
The DV Display	current inputs).	Charletha investainmel accuracy and wining of invest
The PV Display indicates PV and	Underscale. PV has dropped below Input	Check the input signal source and wiring of input terminals.
[E-DE] (*)	range low limit value (scaling	terriniais.
alternately.	low limit value for DC voltage,	
,	current inputs).	
The PV Display	PV has exceeded the	Check the input signal source.
indicates [].	Indication range and Control	
	range.	
The PV Display	Burnout of thermocouple,	Replace each sensor. How to check whether the sensor is burnt out
indicates []	RTD or disconnection of DC voltage (0 to 1 V DC)	[Thermocouple]
and [<i>Ē ┌ 집 ヿ</i>] (*)	voltage (0 to 1 v DC)	If the input terminals of the instrument are
alternately.		shorted, and if a value around room temperature
		is indicated, the instrument is likely to be operating normally, however, the sensor may be
		burnt out.
		[RTD]
		If approx. 100 Ω of resistance is connected to
		the input terminals between A-B of the instrument and between B-B is shorted, and if a value
		around 0° (32°F) is indicated, the instrument is
		likely to be operating normally, however, the
		sensor may be burnt out.
		[DC voltage (0 to 1 V DC)]
		If the input terminals of the instrument are shorted, and if a scaling low limit value is
		indicated, the instrument is likely to be operating
		normally, however, the signal wire may be
		disconnected.
	Check whether the input	Connect the sensor terminals to the instrument
	terminals of thermocouple,	input terminals securely.
	RTD or DC voltage (0 to 1 V	
	DC) are securely mounted to	
	the instrument input terminals.	

^(*) Displayed when Enabled is selected in [Error indication Enabled/Disabled].

Problem	Possible Cause	Solution
The PV Display	PV has dropped below the	Check the input signal source and wiring of input
indicates [].	Indication range and Control	terminals.
	range.	
The PV Display	Check whether input signal	How to check whether the input signal wire is
indicates []	wire for DC voltage (1 to 5 V	disconnected
and $[E \cap G \cap T]$	DC) or direct current (4 to 20	[DC voltage (1 to 5 V DC)] If the input to the input terminals of the instrument
alternately.	mA DC) is disconnected.	is 1 V DC and if a scaling low limit value is
		indicated, the instrument is likely to be operating
		normally, however, the signal wire may be
		disconnected.
		[Direct current (4 to 20 mA DC)] If the input to the input terminals of the instrument
		is 4 mA DC and if a scaling low limit value is
		indicated, the instrument is likely to be operating
		normally, however, the signal wire may be
		disconnected.
	Check whether input signal	Connect the input signal wire to the terminals of
	wire for DC voltage (1 to 5 V	this instrument securely.
	DC) or current (4 to 20 mA	
	DC) is securely connected to	
	the instrument input terminals.	Wire there correctly
	Check if polarity of thermo- couple or compensating lead	Wire them correctly.
	wire is correct.	
	Check whether codes (A, B,	
	B) of RTD agree with the	
	instrument terminals.	
The PV Display	Hardware malfunction	Contact our agency or us.
indicates [E r III].		
The PV Display	Control output OFF function	Press the key for approx. 1 second to cancel
indicates [aFF],	is enabled.	the function.
nothing or PV.		
The indication of PV	Check whether sensor input	Select the sensor input and temperature unit (°C
Display is irregular	or temperature unit (°C or °F)	or °F) correctly.
or unstable.	is correct.	
	Sensor correction coefficient	Set them to suitable values.
	or Sensor correction value is	
	unsuitable.	Llac a cancer with an exercista an action a
	Check whether the sensor	Use a sensor with appropriate specifications.
	specification is correct. AC leaks into the sensor	Use an ungrounded type sensor.
	circuit.	See an angrounded type sensor.
	There may be equipment that	Keep the instrument clear of any potentially
	interferes with or makes noise	disruptive equipment.
	near the instrument.	
	is colocted in [Error indication Enabled/Dia	

 $^{(\}sp{*})$ Displayed when Enabled is selected in [Error indication Enabled/Disabled].

Problem	Possible Cause	Solution
The PV Display keeps indicating the value set in [Scaling low limit].	Check whether the input signal wire for DC voltage (0 to 5 V DC, 0 to 10 V DC) and direct current (0 to 20 mA DC) is disconnected.	Check the input signal wires of DC voltage (0 to 5 V DC, 0 to 10 V DC) and direct current (0 to 20 mA DC). How to check whether the input signal wire is disconnected [DC voltage (0 to 5 V DC, 0 to 10 V DC)] If the input to the input terminal of this controller is 1 V DC, and if a value (converted value from scaling high, low limit setting) corresponding to 1 V DC is indicated, the controller is likely to be operating normally, however, the input signal wire may be disconnected. [Direct current (0 to 20 mA DC)] If the input to the input terminal of this controller is 4 mA DC, and if a value (converted value from scaling high, low limit setting) corresponding to 4 mA DC is indicated, the controller is likely to be operating normally, however, the input signal wire may be disconnected.
	Check whether the input terminals for DC voltage (0 to 5 V DC, 0 to 10 V DC) or direct current (0 to 20 mA DC) are securely connected to the instrument input terminals.	Connect the input terminals of DC voltage and current to the input terminals of this instrument securely.

12.2 Key Operation

Problem	Possible Cause	Solution
None of the set	Set value lock (Lock 1 or	Release the lock in [Set value lock].
values can be set.	Lock 4) is selected.	
	AT, 'AT on startup' or	If AT or 'AT on startup' is performing, cancel AT or
	Auto-reset is performing.	'AT on startup'.
		Please wait until Auto-reset is finished.
		(It takes approximately 4 minutes until Auto-reset
		is finished.)
Only SV and Alarm	Set value lock (Lock 2 or	Release the lock in [Set value lock].
value can be set.	Lock 5) is selected.	
Other settings are		
impossible.		
The setting	Scaling high or low limit value	Set it to a suitable value.
indication does not	may be set at the point where	
change in the input	the value does not change.	
range, and new		
values are unable to		
be set.		

12.3 Control

Problem	Possible Cause	Solution
Temperature does	Sensor is out of order.	Replace the sensor.
not rise.	Check whether the sensor or	Ensure that the sensor or control output terminals
	control output terminals are	are mounted to the instrument input terminals
	securely mounted to the	securely.
	instrument input terminals.	
	Check whether the wiring of	Wire them correctly.
	sensor or control output	
	terminals is correct.	
The control output	OUT1 (or OUT2) low limit	Set it to a suitable value.
remains in an ON	value is set to 100% or higher.	
status.		
The control output	OUT1 (or OUT2) high limit	Set it to a suitable value.
remains in an OFF	value is set to 0% or less.	
status.		
The PV Display	AT or 'AT on startup' has not	Set P, I, D and ARW values manually
indicates [<i>Ē ┌ ፫'□</i>].	been completed even if	
	approx. 4 hours have elapsed	
	since AT or 'AT on startup'	
	started.	
	For 'AT on startup', PV slope	
	and delay time cannot be	
	measured normally for P, I, D	
	calculation.	

For all other malfunctions, please contact our main office or dealers.

13. Character Table

13.1 Error Code

Error codes are indicated on the PV Display.

Error Code	Error Contents	Occurrence
E-0 1	Internal non-volatile IC memory is defective.	When power
		is turned ON.
E-02	Data writing (in non-volatile IC memory) error when power	When power
	failure occurs.	is turned ON.
E-05 (*)	PV has exceeded Input range high limit value (Scaling high	When operating
L	limit value for DC voltage, current inputs).	
E-05 (*)	PV has dropped below Input range low limit value (Scaling low	When operating
LI LILI (*)	limit value for DC voltage, current inputs).	
E-07 (*)	Input burnout or disconnection.	When operating
	Input value is outside of the Indication range and control range.	
Er 10	Hardware malfunction	When operating
E-20	AT or 'AT on startup' has not been completed even if approx. 4	When AT or
	hours have elapsed since AT or 'AT on startup' started.	'AT on startup'
	For 'AT on startup', PV slope and delay time cannot be	starts
	measured normally for P, I, D calculation.	

^(*) Displayed when Enabled is selected in [Error indication Enabled/Disabled].

13.2 Run Mode

Character	Indicated Item Name
off.	Control output OFF
1125	Manual control
□ <i>I</i> Q5	(MV flashes.)

13.3 Monitor Mode

The PV Display indicates PV, and the SV Display indicates setting item value.

Character	Indicated Item Name	
<u> </u>	MV	
[MV]	(Decimal point flashes.)	
25	Remaining time (When Program control is performing)	
[Remaining time]		
11125	Current step number (When Program control is performing) (BCS2)	
[Step number]	ト 「 to ト 「 . 9	
25	SV number (BCS2)	
[Memory number]	〜8 /□ to 〜8 /□	

13.4 Initial Setting Mode

The PV Display (upper row) indicates setting characters, and the SV Display (lower row) indicates factory default value.

Characters,				
Factory Default	Setting Item, Setting Range			
5En5	Input type			
ELL	ELLE	K -200 to 1370°C	ELLF	K -328 to 2498°F
	<i>E</i> □. <i>E</i>	K -200.0 to 400.0℃	E□ F	K -328.0 to 752.0°F
	JIII	J -200 to 1000℃	JUF	J -328 to 1832°F
		R 0 to 1760℃	r	R 32 to 3200°F
	5 L	S 0 to 1760°C	4 <u> </u>	S 32 to 3200°F
	ЬШΕ	B 0 to 1820℃	ЫБ	B 32 to 3308°F
	ΕΙΙΙΣ	E -200 to 800°C	EIIF	E -328 to 1472°F
	7	T -200.0 to 400.0℃	Γ□ .F	T -328.0 to 752.0°F
	$\neg \square \bot$	N -200 to 1300°C	r F	N -328 to 2372°F
	PL 25	PL-Ⅱ 0 to 1390°C	PL 2F	PL-II 32 to 2534°F
	ΕΙΙΕ	C(W/Re5-26) 0 to 2315°C	c F	C(W/Re5-26) 32 to 4199°F
	PF .E	Pt100 -200.0 to 850.0℃	PT F	Pt100 -328.0 to 1562.0°F
	JPF.E	JPt100 -200.0 to 500.0℃	JPTF	JPt100 -328.0 to 932.0°F
	PFE	Pt100 -200 to 850°C	PILE	Pt100 -328 to 1562°F
	JPF E	JPt100 -200 to 500°C	JPFF	JPt100 -328 to 932°F
	4208	4 to 20 mA DC -2000 to 10000		
	0208	0 to 20 mA DC -2000 to 10000		
	O IR	0 to 1 V DC -2000 to 10000		
	0 58	0 to 5 V DC -2000 to 10000		
	/ <u>5</u>	1 to 5 V DC -2000 to 10000		
	0 108	0 to 10 V DC -2000 to 10000		
\5 <u>\</u> \5 <u>\</u> \LH	Scaling hig			
1370	Setting ra	ange: Scaling low limit value to in		•
. =		DC voltage, current inputs	: -2000 to	10000 (*1)
\\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\	Scaling low limit			
-200	Setting range: Input range low limit value to scaling high limit value			
, , , , , , , , , , , , , , , , , , ,	DC voltage, current inputs: -2000 to 10000 (*1)			
dP	Decimal point place			
		No decimal point		
		1 digit after decimal point		
	0000	2 digits after decimal point		
	0,000	3 digits after decimal point		

^(*1) The placement of the decimal point follows the selection.

Characters,	Setting Item, Setting Range				
Factory Default	Front sytuat FVA allocation				
	Event output EV1 allocation [Event Output Allocation Table]				
		<u>.</u> .			
	000		nh limit alarm		
	002	Alarm output, High limit alarm			
		Alarm output, Low limit alarm			
	007		Alarm output, High/Low limits alarm Alarm output, High/Low limits independent alarm		
	005		,		
	005		gh/Low limit range alarm		
	000		gh/Low limit range independent alarm		
	008	Alarm output, Pro			
	009	Alarm output, Pro			
	0 10		gh limit with standby alarm		
	011	•	w limit with standby alarm		
	0 12	·	gh/Low limits with standby alarm gh/Low limits with standby independent		
	LUIE	alarm	gn/Low limits with standby independent		
	0 i3	Heater burnout a	larm output		
	0 14	Loop break alarm	n output		
	_0 IS	Time signal outpo	ut		
	0 15	Output during AT			
		Pattern end output			
	_0 i8	Output by communication command			
RIER	EV1 alarm value 0 Enabled/Disabled				
00	no	Disabled			
	4E 4	Enabled			
R I	EV1 alarm value				
	High limit a	larm	-(Input span) to Input span °C (°F) (*1) (*2))	
	Low limit al	arm	-(Input span) to Input span °C (°F) (*1) (*2))	
	High/Low li	mits alarm	0 to Input span [℃] (˚F) (*1) (*2)		
	High/Low li	mits independent	0 to Input span ℃ (°F) (*1) (*2)		
	alarm				
	High/Low li	mit range alarm	0 to Input span ℃ (℉) (*1) (*2)		
	High/Low li	mit range	0 to Input span ℃ (℉) (*1) (*2)		
	independer	nt alarm			
	Process hig	gh alarm	Input range low limit to Input range high	limit (*1) (*3)	
	Process lov	v alarm	Input range low limit to Input range high	limit (*1) (*3)	
	High limit w	rith standby alarm	-(Input span) to Input span ${}^{\circ}\mathbb{C}$ (${}^{\circ}\mathbb{F}$) (*1) (*2)	
	Low limit with standby alarm-(Input span) to Input span $^{\circ}\mathbb{C}$ ($^{\circ}\mathbb{F}$) (*1) (*2)High/Low limits with standby alarm0 to Input span $^{\circ}\mathbb{C}$ ($^{\circ}\mathbb{F}$) (*1) (*2)High/Low limits with standby0 to Input span $^{\circ}\mathbb{C}$ ($^{\circ}\mathbb{F}$) (*1) (*2))	
			0 to Input span °C (°F) (*1) (*2)		
	independent alarm				
R IH	_	imit alarm value	o of EVA clares value		
		nge: Same as thos	e of EV1 alarm value		

 $^{(^{\}star}1)$ The placement of the decimal point follows the selection.

 $^{(\}ensuremath{^{*}}\xspace2)$ For DC voltage, current inputs, the input span is the same as the scaling span.

 $^{(^*3) \} For \ DC \ voltage, \ current \ inputs, \ input \ range \ low \ (or \ high) \ limit \ value \ is \ the \ same \ as \ scaling \ low \ (or \ high) \ limit \ value.$

Characters, Factory Default	Setting Item, Setting Range		
A IHA	EV1 alarm hysteresis		
LII to	Setting range: 0.1 to 1000.0℃(℉),		
(700)	DC voltage, current inputs: 1 to 10000 (*1)		
8 144	EV1 alarm		
		nge: 0 to 10000 seconds	
R ILā		nergized/De-energized	
noñL	noñL	Energized	
	rE85	De-energized	
['-	-	step number	
	•	nge: 1 to 9	
[TS1 OFF tir		
0000		nge: 00:00 to 99:59 (*4)	
[TS1 ON tim		
0000		nge: 00:00 to 99:59 (*4)	
E8o2 ::::::::::::::::::::::::::::::::::::	•	ut EV2 allocation	
		utput Allocation Table]	
	000	No event	
		Alarm output, High limit alarm	
	002	Alarm output, Low limit alarm	
	003	Alarm output, High/Low limits alarm	
	004	Alarm output, High/Low limits independent alarm	
	005	Alarm output, High/Low limit range alarm	
	005	Alarm output, High/Low limit range independent alarm	
		Alarm output, Process high alarm	
	009	Alarm output, Process low alarm	
		Alarm output, High limit with standby alarm	
		Alarm output, Low limit with standby alarm	
		Alarm output, High/Low limits with standby alarm Alarm output, High/Low limits with standby independent	
		alarm	
	I3	Heater burnout alarm output	
	0 14	Loop break alarm output	
	D 15	Time signal output	
	0 15	Output during AT	
	רו ם	Pattern end output	
	0 18	G 18 Output by communication command	
	0 19	Heating/Cooling control relay contact output	
8258	EV2 alarm	value 0 Enabled/Disabled	
no	חם	Disabled	
	9E5	Enabled	

^(*1) The placement of the decimal point follows the selection.

^(*4) Time unit follows the selection in [Step time unit].

Characters,				
Factory Default	Setting Item, Setting Range			
R2	EV2 alarm value			
	High limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)		
	Low limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)		
	High/Low limits alarm	0 to Input span °C (°F) (*1) (*2)		
	High/Low limits independent	0 to Input span °C (°F) (*1) (*2)		
	alarm			
	High/Low limit range alarm	0 to Input span °C (°F) (*1) (*2)		
	High/Low limit range	0 to Input span °C (°F) (*1) (*2)		
	independent alarm			
	Process high alarm	Input range low limit to Input range high limit (*1) (*3)		
	Process low alarm	Input range low limit to Input range high limit (*1) (*3)		
	High limit with standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)		
	Low limit with standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)		
	High/Low limits with standby	0 to Input span °C (°F) (*1) (*2)		
	alarm			
	High/Low limits with standby	0 to Input span °C (°F) (*1) (*2)		
	independent alarm			
R2H_	EV2 high limit alarm value			
	Setting range: Same as those of EV2 alarm value			
R2HY	EV2 alarm hysteresis			
□□□ tΒ	Setting range: 0.1 to 1000.0℃ (℉),			
	DC voltage, current inputs: 1 to 10000 (*1)			
8244	EV2 alarm delay time			
	Setting range: 0 to 10000 s			
82L A	EV2 alarm Energized/De-ene	rgized		
noñL	nank Energized			
- · · - ·	ー E 出っ De-energized			
[525]	TS2 output step number			
	Setting range: 1 to 9			
F 5 2 F	TS2 OFF time	20		
0000	Setting range: 00:00 to 99:5	99 (*4)		
5 5 2 6 00,00		TS2 ON time		
HI	Setting range: 00:00 to 99:59 (*4)			
	Heater burnout alarm 1 value			
20	Setting range:			
H and CT1 current value are alternately	20 A: 0.0 to 20.0 A 100 A: 0.0 to 100.0 A			
indicated on the PV Display.	10071. 0.0 to 100.071			
HZ[[]]	Heater burnout alarm 2 valu	e		
	Setting range:			
H₽ and CT2 current	20 A: 0.0 to 20.0 A			
value are alternately indicated on the PV	100 A: 0.0 to 100.0 A			
Display.				

^(*1) The placement of the decimal point follows the selection.

^(*2) For DC voltage, current inputs, the input span is the same as the scaling span.

^(*3) For DC voltage, current inputs, input range low (or high) limit value is the same as scaling low (or high) limit value.

^(*4) Time unit follows the selection in [Step time unit].

Factory Default	Setting Item, Setting Range			
LP_F	Loop break alarm time			
	Setting range: 0 to 200 minutes			
LP_H	Loop break alarm band			
		ange: 0 to 150℃ (℉), or	0.0 to 150.0℃(℉	')
		DC voltage, currer	•	•
EBI I	Event inpu	it DI1 allocation		
□000	[Event Ir	put Allocation Table]		
		Event input	Input ON	Input OFF
		function	(Closed)	(Open)
		No event		
		Set value memory		
		Control ON/OFF	Control OFF	Control ON
		Direct/Reverse action	Direct action	Reverse action
		Preset output 1 ON/OFF	Preset output	Usual control
	005	Preset output 2	Preset output	Usual control
		ON/OFF	l root output	Coddi comion
	008	Auto/Manual control	Manual	Automatic
			control	control
	007	Remote/Local	Remote	Local
	008	Program control	RUN	STOP
		RUN/STOP		
	008	Program control	Holding	Not holding
	0 10	Holding/Not holding	A dy compan	Lloud control
		Program control Advance function	Advance function	Usual control
		Integral action	Integral action	Usual
		Holding	Holding	integral action
EBI 2	Event innu	it DI2 allocation	1 loluling	intogral action
	-	item: Same as those of	Event input DI1 :	allocation
-FLH		etting input high limit		and dation
מרצו		ange: External setting in	out low limit to Inp	out range high limit (*1)
- TLL		External setting input low limit		
-200		ange: Input range low lim	nit to External set	ting input high limit (*1)
Froh	Transmiss	ion output type		
PB	PB	PV transmission		
	5 <u>8</u>	SV transmission		
	⊼8∐	MV transmission		
	68 III	DV transmission		
(*1) The placement of the	ne decimal point	follows the selection.		

Characters,

Characters, Factory Default		Setting Item, Setting Range	
Γ - L H	Transmission output high limit		
1370	PV, SV transmission	Transmission output low limit to Input range high limit	
		DC voltage, currents: -2000 to 10000	
	MV transmission	Transmission output low limit to 105.0%	
	DV transmission	Transmission output low limit to Scaling span (*1)	
Γ – L L	Transmission output low limit		
-200	PV, SV transmission	Input range low limit to Transmission output high limit	
		DC voltage, currents: -2000 to 10000	
	MV transmission	-5.0% to Transmission output high limit value	
	DV transmission	-Scaling span to Transmission output high limit value (*1)	
5	SV1		
	Setting range: Scaling low limit to Scaling high limit (*1)		
5 <u>2</u>	SV2		
	Setting range: Scaling low limit to Scaling high limit (*1)		
43	SV3		
	Setting range: Scaling low limit to Scaling high limit (*1)		
54	SV4		
	Setting range: Scaling low limit to Scaling high limit (*1)		

^(*1) The placement of the decimal point follows the selection.

13.5 Main Setting Mode

The PV Display (upper row) indicates setting characters, and the SV Display (lower row) indicates factory default value.

Characters,			
Factory Default	Setting Item, Setting Range		
4	SV1		
	Setting range: Scaling low limit to Scaling high limit (*1)		
<i>F</i> 1	Step 1 time		
00.00	Setting range:, or 00:00 to 99:59		
ŭL. I	Step 1 wait value		
	Setting range: 0 to 20% of input span		
	DC voltage, current inputs: 0 to 20% of scaling span (*1)		
42 III	SV2		
	Setting range: Scaling low limit to Scaling high limit (*1)		
r2	Step 2 time		
00.00	Setting range: [-]-[-], or 00:00 to 99:59		
J Z	Step 2 wait value		
	Setting range: 0 to 20% of input span		
	DC voltage, current inputs: 0 to 20% of scaling span (*1)		
5 3 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	SV3		
	Setting range: Scaling low limit to Scaling high limit (*1)		
Γ3	Step 3 time		
00,00	Setting range:, or 00:00 to 99:59		
J□_ 3	Step 3 wait value		
	Setting range: 0 to 20% of input span		
	DC voltage, current inputs: 0 to 20% of scaling span (*1)		
44	SV4		
	Setting range: Scaling low limit to Scaling high limit (*1)		
<u> </u>	Step 4 time		
0000	Setting range:		
<u> </u>	Step 4 wait value		
	Setting range: 0 to 20% of input span		
* ************************************	DC voltage, current inputs: 0 to 20% of scaling span (*1)		
\ <u> \ \ 5 </u>	Step 5 SV		
	Setting range: Scaling low limit to Scaling high limit (*1)		
	Step 5 time		
0000	Setting range: [:::::::::::::::::::::::::::::::::::		
5_5	Step 5 wait value		
	Setting range: 0 to 20% of input span		
, ,-,-,-,-	DC voltage, current inputs: 0 to 20% of scaling span (*1)		
\ \5 <u>\</u>	Step 6 SV		
	Setting range: Scaling low limit to Scaling high limit (*1)		
	Step 6 time		
0000	Setting range: = = = = , or 00:00 to 99:59		
5 5	Step 6 wait value		
	Setting range: 0 to 20% of input span		
	DC voltage, current inputs: 0 to 20% of scaling span (*1)		

 $^{(^{\}star}1)$ The placement of the decimal point follows the selection.

Characters, Factory Default	Setting Item, Setting Range		
47	Step 7 SV		
	Setting range: Scaling low limit to Scaling high limit (*1)		
Γ <u></u> _7	Step 7 time		
00.00	Setting range:, or 00:00 to 99:59		
<u> </u>	Step 7 wait value		
	Setting range: 0 to 20% of input span		
	DC voltage, current inputs: 0 to 20% of scaling span (*1)		
<i>48</i>	Step 8 SV		
	Setting range: Scaling low limit to Scaling high limit (*1)		
Γ <u></u> 8	Step 8 time		
00,00	Setting range:, or 00:00 to 99:59		
J8	Step 8 wait value		
	Setting range: 0 to 20% of input span		
	DC voltage, current inputs: 0 to 20% of scaling span (*1)		
\ <u> 58 </u>	Step 9 SV		
	Setting range: Scaling low limit to Scaling high limit (*1)		
Γ <u></u> 9	Step 9 time		
00,00	Setting range:, or 00:00 to 99:59		
J9	Step 9 wait value		
	Setting range: 0 to 20% of input span		
	DC voltage, current inputs: 0 to 20% of scaling span (*1)		

^(*1) The placement of the decimal point follows the selection.

13.6 Sub Setting Mode

The PV Display (upper row) indicates setting characters, and the SV Display (lower row) indicates factory default value.

factory default value	e. 				
Characters, Factory Default	Setting Item, Setting Range				
Rr	AT/Auto-reset Perform/Cancel				
	AT/AT on startup/Auto-reset Cancel				
	AT Perform				
	用によっ AT on startup Perform				
	r 与E「 Auto-reset Perform				
P	OUT1 proportional band				
III ID	Thermocouple, RTD input without decimal point: 0 to Input span °C(°F)				
	Thermocouple, RTD input with decimal point: 0.0 to Input span °ℂ(℉) DC voltage, current inputs: 0.0 to 1000.0%				
1	Integral time				
200	Setting range: 0 to 3600 seconds				
d	Derivative time				
50	Setting range: 0 to 1800 seconds				
R-J	ARW				
50	Setting range: 0 to 100%				
	Manual reset				
	Setting range: ±Proportional band value				
	OUT1 proportional cycle				
30	Setting range: 0.5, or 1 to 120 seconds				
	Factory default value:				
	Relay contact output: 30 sec Non-contact voltage output: 3 sec				
<i>H</i> <u> </u>	OUT1 ON/OFF hysteresis				
	Setting range: 0.1 to 1000.0℃ (℉)				
	DC voltage, current inputs: 1 to 10000 (*1)				
ol H	OUT1 high limit				
□ <i>100</i>	Setting range: OUT1 low limit value to 100%				
	(Direct current output type: OUT1 low limit value to 105%)				
oll [OUT1 low limit				
	Setting range: 0% to OUT1 high limit value				
	(Direct current output type: -5% to OUT1 high limit value)				
or Af	OUT1 rate-of-change				
	Setting range: 0 to 100 %/second				
cac .	OUT2 cooling method				
Ai -	Air cooling (linear characteristics)				
	Oil cooling (1.5th power of the linear characteristics)				
(Fig. 1)	ŭ≅େ Water cooling (2nd power of the linear characteristics)				
<u>P_</u> b	OUT2 proportional band				
	Thermocouple, RTD input without decimal point: 0 to Input span°C (°F) Thermocouple, RTD input with decimal point: 0.0 to Input span°C (°F)				
	DC voltage, current inputs: 0.0 to 1000.0%				
c_b[]	OUT2 proportional cycle				
30	Setting range: 0.5, or 1 to 120 seconds				
	Factory default value:				
	• EV2(*2), EV2+DR: 30 sec • DS, EV2+DS: 3 sec				
<i>H</i> 575	OUT2 ON/OFF hysteresis				
	Setting range: 0.1 to 1000.0℃ (℉),				
	DC voltage, current inputs: 1 to 10000 (*1)				

^(*1) The placement of the decimal point follows the selection.
(*2) When EV2 is selected { ((Heating/Cooling control relay contact output) is selected in [Event output EV2 allocation]}.

Characters, Factory Default	Setting Item, Setting Range			
aL Hb	OUT2 high limit			
□ <i>100</i>	Setting range: OUT2 low limit value to 100%			
8 8 8	(Direct current output type: OUT2 low limit value to 105%)			
0116	OUT2 low limit			
	Setting range: 0% to OUT2	<u> </u>		
db		-5% to OUT2 high limit value)		
	Overlap/Dead band	O°C (°E)		
	Setting range: -200.0 to 200. DC voltage, current inputs:	· /·		
conf	Direct/Reverse action	2000 to 2000 (1)		
HERF	HERI Reverse (Heatin	g) action		
	□□□L Direct (Cooling)	·		
R I	EV1 alarm value			
	High limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)		
	Low limit alarm	-(Input span) to Input span °C (°F) (*1) (*2)		
	High/Low limits alarm	0 to Input span °C (°F) (*1) (*2)		
	High/Low limits independent	0 to Input span °C (°F) (*1) (*2)		
	High/Low limit range alarm	0 to Input span °C (°F) (*1) (*2)		
	High/Low limit range	0 to Input span °C (°F) (*1) (*2)		
	independent alarm			
	Process high alarm	Input range low limit to Input range high limit (*1) (*3)		
	Process low alarm	Input range low limit to Input range high limit (*1) (*3)		
	High limit with standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)		
	Low limit with standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)		
	High/Low limits with standby	0 to Input span °C (°F) (*1) (*2)		
	High/Low limits with standby independent alarm	0 to Input span °C (°F) (*1) (*2)		
A IH	EV1 high limit alarm value			
	Setting range: Same as those of EV1 alarm value			
82	EV2 alarm value			
	Setting range: Same as those of EV1 alarm value			
82H	EV2 high limit alarm value			
	Setting range: Same as tho	se of EV1 alarm value		
HI	Heater burnout alarm 1 valu	e		
	Setting range:			
H I and CT1 current	20 A: 0.0 to 20.0 A			
value are alternately indicated on the PV	100 A: 0.0 to 100.0 A			
Display.				
H2	Heater burnout alarm 2 value			
	Setting range:			
ドラ and CT2 current value are alternately	20 A: 0.0 to 20.0 A 100 A: 0.0 to 100.0 A			
indicated on the PV	100 A. 0.0 to 100.0 A			
Display.	Loop break alarm time			
	Setting range: 0 to 200 minu	utes		
LP_H	Loop break alarm band			
	Thermocouple, RTD input without decimal point: 0 to 150°C (°F)			
	Thermocouple, RTD input wi	th decimal point: 0.0 to 150.0°C (°F)		
	DC voltage, current inputs:	0 to 1500 (*1)		

^(*1) The placement of the decimal point follows the selection.
(*2) For DC voltage, current inputs, the input span is the same as the scaling span.
(*3) For DC voltage, current inputs, input range low (or high) limit value is the same as scaling low (or high) limit value.

13.7 Engineering Mode 1

The PV Display (upper row) indicates setting characters, and the SV Display (lower row) indicates

factory default value.

factory default value	₹. 						
Characters, Factory Default	Setting Item, Setting Range						
Lock	Set value lock						
	Oct Value	IOOK	Change via Keypad		Change via Software Communication		
	[-[-]-	Unlock	All set values	can be changed		All set values can be	
	Loci	Lock 1		set values can be		changed.	
			changed.				
	Loc2	Lock 2	In Fixed value	e control, only SV	/		
			and Alarm va	llue can be chang	ged.		
			In Program c	ontrol, Step SV,			
			Step time and	d Alarm value car	1		
	_		be changed.				
		Lock 3		can be changed		•	ns – except Input
	Locy	Lock 4		set values can be			oller/Converter –
	=		changed.				nged temporarily
	Locs	Lock 5		e control, only S\			communication.
				llue can be chang	ged.		power is turned he set values
				ontrol, Step SV,		_	e values before
			·	d Alarm value car	1		5 was selected.
EBI I	Event inn	ut DI1 s	be changed.				
	Event input DI1 allocation [Event Input Allocation Table]						
	LEVOIR				nput OFF		
			function	(Closed)		(Open)	
	000	No ev	/ent			· · · /	
		Set v	alue memory				
	002	Conti	ol ON/OFF	Control OFF	Со	ntrol ON	
	□003	Direc	t/Reverse	Direct	Re	verse	
		action	า	action	act	tion	
	<u> </u>	Prese	et output 1	Preset output	Us	ual control	
		ON/C)FF				
	005		et output 2	Preset output	Us	ual control	
	; ; ; ; ; ; ; ; ; ; ; ; ; ; ; ; ; ; ;	ON/C					
	005		Manual	Manual		tomatic	
		contr		control		ntrol	
	007		ote/Local	Remote		cal	
	<u> </u>		ram control STOP	RUN	SI	OP	
	009		am control	Holding	No	t holding	
			ng/Not				
	(, , , , , , ,	holdii					
	□ <i>0 10</i>		am control	Advance	Us	ual control	
		_	nce function	function			
		"	ral action	Integral action		ual	
		holdii	ng	holding	Inte	egral action	

Characters, Factory Default		Set	ting Item, Setting Range		
EBI 2	Event inpu	t DI2 allocation			
000	Selection item: Same as Event input DI1 allocation				
E80 I		out EV1 allocation	•		
	-	output Allocation •			
	000	No event			
		Alarm output, Hig	nh limit alarm		
	002	Alarm output, Lov			
	003	•	h/Low limits alarm		
	004		gh/Low limits independent alarm		
	005	Alarm output, Hig	gh/Low limit range alarm		
	008	-	gh/Low limit range independent alarm		
	007	Alarm output, Pro	ocess high alarm		
	008	Alarm output, Pro	ocess low alarm		
	009	Alarm output, Hig	gh limit with standby alarm		
		Alarm output, Lov	w limit with standby alarm		
		Alarm output, Hig	h/Low limits with standby alarm		
	I2	Alarm output, Hig alarm	h/Low limits with standby independent		
	_0 i3	Heater burnout a	larm outout		
	0 14	Loop break alarm			
	0 /5	Time signal outpu	•		
	0 15	Output during AT			
	017	Pattern end output			
	_C 18	Output by communication command			
RIER	EV1 alarm value 0 Enabled/Disabled				
70	no				
	4E 5	Enabled			
R (EV1 alarm	value			
	High limit a	larm	-(Input span) to Input span °C (°F) (*1) (*	(2)	
	Low limit al	arm	-(Input span) to Input span °C (°F) (*1) (*	2)	
	High/Low li	mits alarm	0 to Input span °C (°F) (*1) (*2)		
	High/Low li alarm	mits independent	0 to Input span °C (°F) (*1) (*2)		
	High/Low li	mit range alarm	0 to Input span [°] C ([°] F) (*1) (*2)		
	High/Low li	mit range	0 to Input span °C (°F) (*1) (*2)		
	independer	nt alarm			
	Process high alarm		Input range low limit to Input range hig	h limit (*1) (*3)	
	Process low alarm		Input range low limit to Input range high limit (*1) (*3		
	High limit with standby alarm		-(Input span) to Input span [°] C (°F) (*1) (*	2)	
	Low limit w	ith standby alarm	-(Input span) to Input span $^{\circ}\mathbb{C}$ ($^{\circ}\mathbb{F}$) (*1) (*	2)	
	High/Low limits with standby 0 to Input span [°] C ([°] F) (*1) (*2)				
	alarm				
		mits with standby	0 to Input span [°] C (°F) (*1) (*2)		
<i>[</i>] [[]	independer				
R IH[]	_	imit alarm value	as of EVA alasma all		
	Setting ra	ange: Same as tho	se of EV1 alarm value		

 $^{(^{\}star}1)$ The placement of the decimal point follows the selection.

^(*2) For DC voltage, current inputs, the input span is the same as the scaling span.
(*3) For DC voltage, current inputs, input range low (or high) limit value is the same as scaling low (or high) limit value.

Characters, Factory Default		Setting Item, Setting Range			
R IHY	EV1 alarm hysteresis				
	Setting range: 0.1 to 1000.0℃ (℉),				
(CE) 0 000 0	DC voltage, current inputs: 1 to 10000 (*1)				
B 197	EV1 alarm				
	Setting ra	ange: 0 to 10000 seconds			
A IL		Energized/De-energized			
noñL	noñL	Energized			
	-E85	De-energized			
[t step number ange: 1 to 9			
rs if					
,	TS1 OFF ti	me ange: 00:00 to 99:59 (*2)			
[5]	TS1 ON tin	<u> </u>			
,		ne ange: 00:00 to 99:59 (*2)			
E805		out EV2 allocation			
	· -	utput Allocation Table]			
	_ooo	No event			
		Alarm output, High limit alarm			
	002	Alarm output, Low limit alarm			
		Alarm output, High/Low limits alarm			
	004	Alarm output, High/Low limits independent alarm			
	005	Alarm output, High/Low limit range alarm			
	005	Alarm output, High/Low limit range independent alarm			
	007	Alarm output, Process high alarm			
	008	Alarm output, Process low alarm			
	009	Alarm output, High limit with standby alarm			
	_0 i0	Alarm output, Low limit with standby alarm			
		Alarm output, High/Low limits with standby alarm			
	□0 IZ	Alarm output, High/Low limits with standby independent alarm			
	0 /3	Heater burnout alarm output			
	0 14	Loop break alarm output			
	0 15	Time signal output			
	DD 15	Output during AT			
	0 17	Pattern end output			
	_0 i8	Output by communication command			
	0 19	Heating/Cooling control relay contact output			
RZER	EV2 alarm	value 0 Enabled/Disabled			
00	no	Disabled			
	4E5	Enabled			
		<u> </u>			

^(*1) The placement of the decimal point follows the selection. (*2) Time unit follows the selection in [Step time unit].

Characters, Factory Default	Setting Item, Setting Range				
R2[[]	EV2 alarm value				
	High limit a	larm	-(Input span) to Input span °C (°F) (*1) (*2)		
	Low limit al	arm	-(Input span) to Input span °C (°F) (*1) (*2)		
	High/Low li	mits alarm	0 to Input span °C (°F) (*1) (*2)		
	High/Low limits independent alarm		0 to Input span °C (°F) (*1) (*2)		
		mit range alarm	0 to Input span ℃ (˚F) (*1) (*2)		
	High/Low lindepender		0 to Input span °C (°F) (*1) (*2)		
	Process hig	gh alarm	Input range low limit to Input range high limit (*1) (*3)		
	Process lov	v alarm	Input range low limit to Input range high limit (*1) (*3)		
	High limit w	rith standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)		
		th standby alarm	-(Input span) to Input span °C (°F) (*1) (*2)		
	High/Low ling alarm	mits with standby	0 to Input span °C (°F) (*1) (*2)		
	High/Low lindepender	mits with standby nt alarm	0 to Input span °C (°F) (*1) (*2)		
R2H	EV2 high li	mit alarm value			
	•		se of EV2 alarm value		
82HY		hysteresis	0.5		
LIII la	Setting range: 0.1 to 1000.0°C (°F), DC voltage, current inputs: 1 to 10000 (*1)				
8597	EV2 alarm	delay time			
	Setting range: 0 to 10000 seconds				
RZLĀ	EV2 alarm	Energized/De-ener	gized		
noñL	nañL Energized				
	rE85	De-energized			
[TS2 output step number				
	Setting range: 1 to 9				
r 52F 0000	TS2 OFF time				
0400 1520	TS2 ON tin	Setting range: 00:00 to 99:59 (*4)			
0000		ange: 00:00 to 99:5	9 (*4)		
505		rection coefficier			
1000		ange: -10.000 to 10			
50 <u> </u>	Sensor cor				
		ange: -1000.0 to 10	` ,		
· · · · ·	DC voltage, current inputs: -10000 to 10000 (*1)				
F1 L	PV filter time constant Setting range: 0.0 to 10.0 seconds				
	Communication protocol				
nañL	noñL	Shinko protocol			
	ňod8	MODBUS ASCII			
	nadr	MODBUS RTU			
	JoōL		JC command allocated)		
	JAdA		(JC command allocated)		
	Jādr		IC command allocated)		
	1	\-	,		

 $^{(\}ensuremath{^{\star}}\xspace1)$ The placement of the decimal point follows the selection.

^(*2) For DC voltage, current inputs, the input span is the same as the scaling span.

(*3) For DC voltage, current inputs, input range low (or high) limit value is the same as scaling low (or high) limit value.

(*4) Time unit follows the selection in [Step time unit].

Characters, Factory Default		Setting Item, Setting Range		
cñna	Instrument number			
	0 to 95			
cāhP	Communic	ation speed		
35	98	9600 bps		
	<u> </u>	19200 bps		
	384	38400 bps		
cāFF	Data bit/Pa	rity		
7885	8non	8 bits/No parity		
	Joon	7 bits/No parity		
	8E8n	8 bits/Even		
	7885	7 bits/Even		
	Bodd	8 bits/Odd		
	Todd	7 bits/Odd		
cñh「	Stop bit			
		1 bit		
		2 bits		
cādy	Response	delay time		
	Setting ra	ange: 0 to 1000 ms		
58_b	SVTC bias			
		ange: ±20% of the input span		
	DC voltage, current inputs: ±20% of scaling span (*1)			
reār	Remote/Local			
Lock	Lock rEnt	Local		
FFLH		Remote		
1370	Setting range: External setting input low limit to Input range high limit			
	Setting range: External setting input low limit to Input range high limit External setting input low limit			
-200		ange: Input range low limit to External setting input high limit		
-F_b	Remote bia			
		ange: ±20% of input span		
	_	ge, current inputs: ±20% of scaling span (*1)		
Frah		ion output type		
PU	PB	PV transmission		
	58	SV transmission		
	ā8	MV transmission		
	48	DV transmission		
T-LH		ion output high limit		
1370	PV, SV tran	· , ·		
	MV transmi			
	DV transmi	'		
r-LL		ion output low limit		
-200	PV, SV tran			
	MV transmi			
	DV transmi	1 0		

^(*1) The placement of the decimal point follows the selection.

Characters, Factory Default	Setting Item, Setting Range				
ñ_50	Step time unit				
ñi n□	กับกา				
	っとこ Minutes:Seconds				
PrES	Power restore action				
450P	¬「□F' Stops after power is restored				
	<i>⊆ □□i</i> Continues (resumes) after power is restored.				
	Halad Suspends (on hold) after power is restored.				
5_58	Program start temperature				
	Setting range: Scaling low limit value to Scaling high limit value (*1)				
5_5!	Program control start type				
PH	PB PV start				
	<i>PB</i> ┌□ PVR start				
	∽ <i>B</i> SV start				
-885	Number of repetitions				
	Setting range: 0 to 10000 times				
-855	SV Rise/Fall rate action				
585 [ちどうに SV start				
	PB与に PV start				
-AFU	SV rise rate				
	Setting range: 0 to10000 °C/min (°F/min)				
	Thermocouple, RTD inputs with a decimal point: 0.0 to 1000.0 °C/min (˚F/min)				
7 <u></u> 0	DC voltage, current inputs: 0 to 10000/min				
-AFd	SV fall rate				
	Setting range: 0 to10000 °C/min (°F/min)				
	Thermocouple, RTD inputs with a decimal point: 0.0 to 1000.0 °C/min (°F/min)				
P58	DC voltage, current inputs: 0 to 10000/min				
	Indication when control output OFF □FF□ OFF indication				
	PBI PV indication PBRL PV indication + Any Alarm active				
8F_b	AT bias				
	Setting range: 0 to 50°C (0 to 100°F), or 0.0 to 50.0°C (0.0 to 100.0°F)				
Ar_E	AT gain				
	Setting range: 0.1 to 10.0 times				
EaUF	Output status when input errors occur				
off	□FF□ Output OFF				
	Output ON				
ABAU	OUT/OFF key function				
off	©FF Control output OFF function				
	で見れば Auto/Manual control				
	Program control				
ñ8ch	Auto/Manual control after power ON				
RUFa	RUI D Automatic control				
	うろうり Manual control				

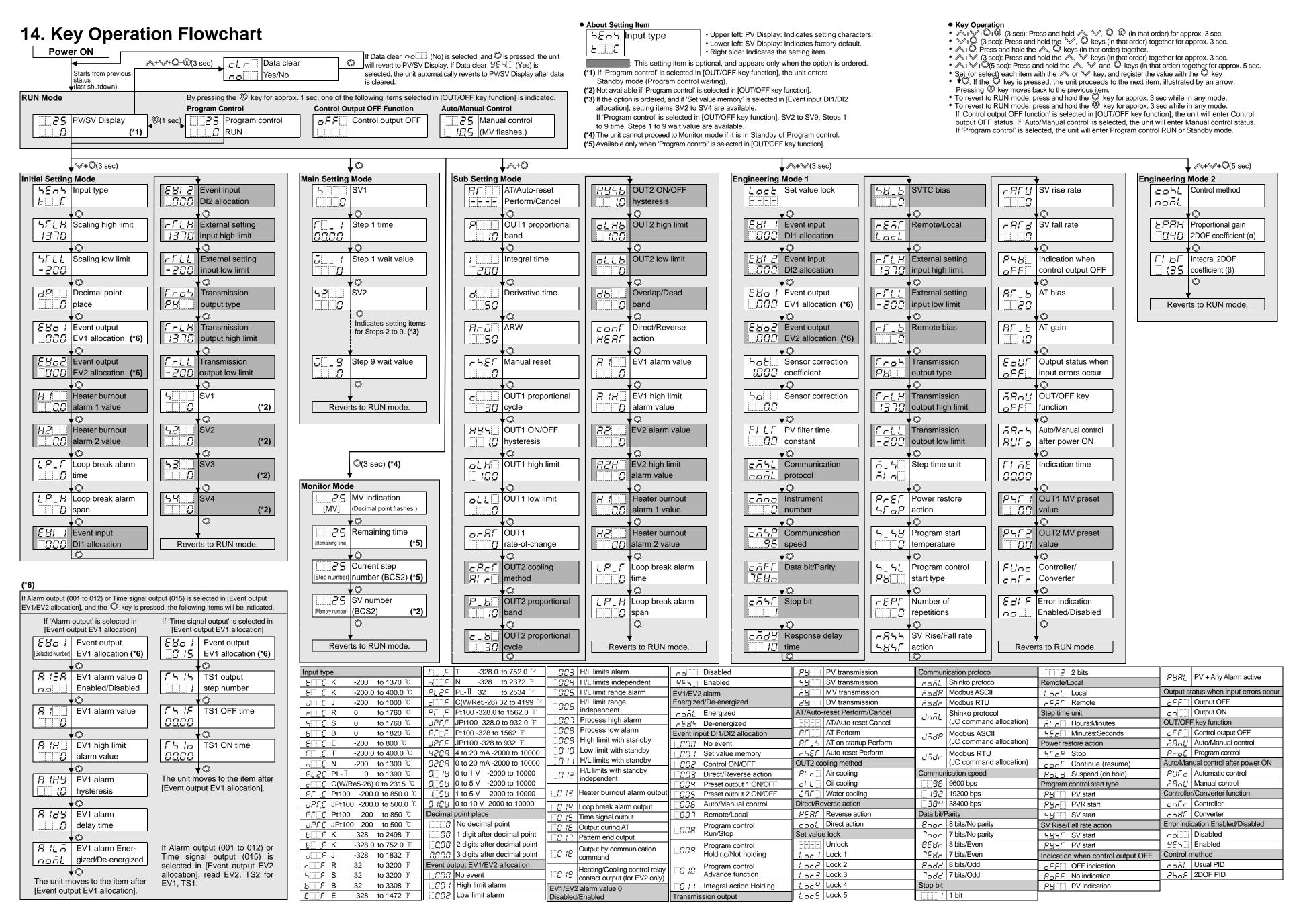
^(*1) The placement of the decimal point follows the selection.

Characters, Factory Default	Setting Item, Setting Range				
ri ae	Indication time				
0000	Setting ra	ange: 00:00 to 60:00 (Minutes:Seconds)			
	When se	t to 00:00, Displays remain ON.			
P55 !	OUT1 MV	preset value			
	Setting rai	nge: OUT1 low limit to OUT1 high limit			
	For Direct	ct current output type, and when OUT1 is in ON/OFF control: OUT1 low			
	limit or O	UT1 high limit			
	For Rela	y contact output or Non-contact voltage output type, and when OUT1 is			
	in ON/OFF control: 0.0% or 100.0%				
P552	OUT2 MV preset value				
		Setting range: OUT2 low limit to OUT2 high limit			
	For DA, EV2+DA options, and when OUT2 is in ON/OFF control: OUT2 low limit or OUT2 high limit				
	For DR, DS, EV2+DR, EV2+DS options, and when OUT2 is in ON/OFF control:				
	0.0% or 100.0%				
FUnc	Controller/Converter function				
cnfr	בחור	Controller			
	chal	Converter			
Edl F	Error indication Enabled/Disabled				
no	חם	Disabled			
	4E 4	Enabled			

13.8 Engineering Mode 2

The PV Display (upper row) indicates setting characters, and the SV Display (lower row) indicates factory default value.

Characters,				
Factory Default	Setting Item, Setting Range			
cohL	Control method			
noñL	noñL	PID control		
	25oF	2DOF PID control		
ŁPRH	Proportion	nal gain 2DOF coefficient (α)		
	0.00 to 1	.00		
<i>□ □ □ □</i>	Integral 2DOF coefficient (β)			
□ <i>t</i> 35	0.00 to 1	0.00		



***** Inquiries *****

For any inquiries about this unit, please contact our agency or the vendor where you purchased the unit after checking the following.

	[Example]
• Model	BCS2R00-12
• Option	EV2, C5W (100A)
Serial number	No. 145F05000

In addition to the above, please let us know the details of the malfunction, or discrepancy, and the operating conditions.

SHINKO TECHNOS CO., LTD. OVERSEAS DIVISION

Head Office: 2-5-1, Senbahigashi, Minoo, Osaka, 562-0035, Japan

[URL] https://shinko-technos.co.jp/e/ Tel: +81-72-727-6100 [E-mail] overseas@shinko-technos.co.jp Fax: +81-72-727-7006